

$\hat{n} \rightarrow$  vector normal to the surface

$P \rightarrow$  Polarisation

Volume bound charge density

$$\rho_b = -\nabla \cdot \vec{P}$$

Net Electric field, inside the dielectric then electric field is  $E_0 - E_0/\epsilon_r$  less than  $E_0$  by the amount  $E_0/\epsilon_r$ .  $\left\{ \epsilon_r = \frac{E_0}{E} \right.$

$$E_{\text{Net}} = \frac{E_0}{\epsilon_r}$$

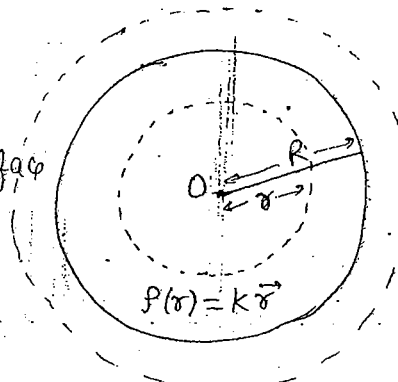
$\epsilon_r \rightarrow$  dielectric constant

Q. 11- A sphere of radius  $R$  carries a polarisation  $\vec{P}$ .  
 $P(r) = k \cdot \vec{r}$  where  $k$  is a constant &  $\vec{r}$  is the vector from the centre.

- (a) Calculate the bound charges  $\sigma_b$  &  $\rho_b$   
(b) Calculate the electric field inside & outside the sphere

$$\begin{aligned} \sigma_b &= \vec{P} \cdot \hat{n} \\ &= k \vec{r} \cdot \hat{n} = k r \hat{r} \cdot \hat{r} \\ &= k r = \underline{kR} \quad [\text{at surface } r=R] \end{aligned}$$

$$\begin{aligned} \rho_b &= -\nabla \cdot \vec{P} \\ &= -\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 k \cdot \vec{r}) \\ &= -\frac{k}{r^2} \cdot 3r^2 = \underline{\underline{-3k}} \end{aligned}$$



(b) Inside

$$q_{\text{enc}} = \int \rho_b d\tau = -3k \cdot \frac{4\pi r^3}{3}$$

$q_{\text{enc}} = -4\pi k r^3$

( $q_{\text{enc}}$  due to volume only)  
{ bcoz inside sphere is not enclosing its surface }

By Gauss law,  $\oint \vec{E} \cdot d\vec{s} = \frac{q_{\text{enc}}}{\epsilon_0}$

$$E \cdot 4\pi r^2 = \frac{-4\pi k r^3}{\epsilon_0}$$

$$E_{\text{in}} = \underline{\underline{-\frac{k r}{\epsilon_0} \hat{r}}}$$

If polarisation  $\vec{P}$  is radially outward then elec. field will be opposite to it (i.e. towards inside  $(-\hat{r})$ )

Outside the sphere :-  $q_{enc}$  will be due to surface & volume both.

$$q_b(\sigma_b) = KR \cdot 4\pi R^2$$

$$q_b(\sigma_b) = 4\pi KR^3$$

$$\& q(P_b) = -4\pi KR^3$$

$$\text{Total } q = 4\pi KR^3 - 4\pi KR^3$$

$$q = 0$$

$$\text{So } E_{out} = 0$$

- Gauss Law in Dielectrics :- We have 2 type of bound charge density  $\sigma_b$  &  $P_b$ . Gauss law deals with  $P_b$ . There are 2 types of  $P_b$ ,  $P_b$  &  $P_F$  are bound volume charge density & free volume charge density respectively

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\text{Here } \rho = \rho_b + \rho_F$$

$$\Rightarrow \epsilon_0 (\nabla \cdot \vec{E}) = \rho_b + \rho_F$$

$$\epsilon_0 (\nabla \cdot \vec{E}) = \rho_F - \nabla \cdot \vec{P}$$

$$\nabla \cdot (\epsilon_0 \vec{E} + \vec{P}) = \rho_F$$

$$\nabla \cdot \vec{D} = \rho_F$$

$\vec{D} \rightarrow$  displacement vector

$\vec{D}$ , includes  $\vec{E}$  &  $\vec{P}$  both.

This is the differential form of Gauss law of Dielectrics

Integral form :-  $\oint \vec{E} \cdot d\vec{s} = \frac{q_{enc}}{\epsilon_0}$

$$\oint \vec{D} \cdot d\vec{s} = q_{enc}$$

$\vec{D}$  is totally determined by the free charges,

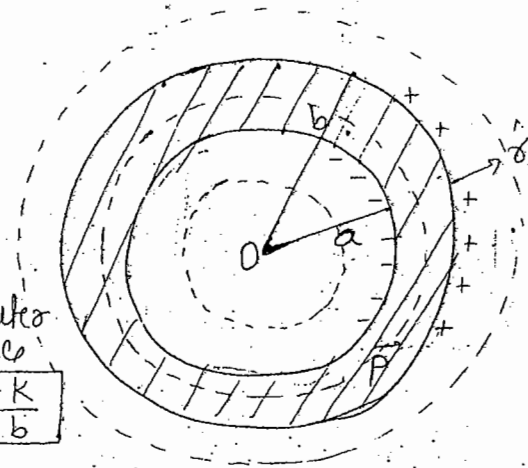
$\vec{E}$  " " " " " free & bound

bcz  $\vec{D}$  &  $\vec{E}$  in  $\vec{D}$ , bound charge is included in it. both

charge on the surface of metal or conductor  $\rightarrow$  free charge

Ques:- A thick spherical shell inner radius  $a$  & outer radius  $b$  is made of dielectric material with polarization  $\vec{P}(\vec{r}) = \epsilon_0 \frac{k}{r} \hat{r}$  where  $k$  is constant &  $r$  is the distance from the centre. There is no free charge in the region. Find the electric field in all the 3 regions:-

- (i)  $r < a$
- (ii)  $a < r < b$
- (iii)  $r > b$



$$\sigma_b = \vec{P} \cdot \hat{n} = \frac{k}{r} \hat{r} \cdot \hat{r} = \frac{k}{r}$$

inner surface:  $\sigma_b = -\frac{k}{a}$  & on outer surface:  $\sigma_b = +\frac{k}{b}$

$$\rho_b = -\nabla \cdot \vec{P}$$

$$= -\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{k}{r}) = -\frac{1}{r^2} \frac{\partial}{\partial r} (kr)$$

$$\rho_b = -\frac{k}{r^2}$$

for  $r < a$ ,  $q_{enc} = 0$   
 $E = 0$

$a < r < b$   
 due to volume  $q_{enc} = \int_a^r \rho_b d\tau = \int_a^r \frac{-k}{r^2} r^2 \sin\theta d\theta d\phi dr$   
 $= \int_a^r \frac{-k}{r^2} 4\pi r^2 dr = -4\pi k [r]_a^r = -4\pi k (r - a)$

due to inner surface  $q_{enc} = \int -\frac{k}{a} \cdot 4\pi r^2 dr = -\frac{k}{a} 4\pi [a^2]$   
 $= -4\pi k a$

$$q = -4\pi k r + 4\pi k a - 4\pi k a$$

$$q_{enc} = -4\pi k r$$

$$E \cdot 4\pi r^2 = \frac{-4\pi k r}{\epsilon_0} \Rightarrow E = -\frac{k}{\epsilon_0 r} \hat{r}$$

$r > b$   
 $q_{enc} = -4\pi k b + 4\pi k b = 0$   
 $E = 0$

II Method 1- (i)  $r < a$

$$\oint \mathbf{D} \cdot d\mathbf{s} = q_{enc}$$

$$q_{enc} = 0 \quad \text{So} \quad \boxed{\mathbf{D} = 0} \Rightarrow \epsilon_0 \mathbf{E} + \mathbf{P} = 0 \Rightarrow \boxed{\mathbf{E} = 0}$$

(ii)  $a < r < b$

$\mathbf{D} = 0$  (No free charge in this region)

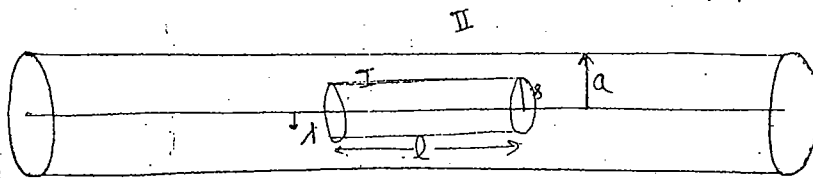
$$\epsilon_0 \mathbf{E} + \mathbf{P} = 0 \Rightarrow \epsilon_0 \mathbf{E} + \frac{K}{r} \hat{\mathbf{s}} = 0$$

$$\boxed{\mathbf{E} = -\frac{K}{\epsilon_0 r} \hat{\mathbf{s}}}$$

(iii)  $r > b$

$$\mathbf{D} = 0 \Rightarrow \epsilon_0 \mathbf{E} + \mathbf{P} = 0 \Rightarrow \boxed{\mathbf{E} = 0}$$

Q.21- A long straight wire carrying a line charge  $\lambda$  is surrounded by rubber insulation upto radius  $a$ . Find electric displacement  $\mathbf{D}$  & Electric field inside & outside the rubber insulation.



Here  $q_{enc}$  is not given & don't know about bound charge  
 $q_{enc} = q_f + q_b$

Use Gauss law in Dielectrics.

Inside:  $\oint \mathbf{D} \cdot d\mathbf{s} = q_{enc}$

$$q_{enc} = \lambda l$$

$$\therefore \mathbf{D} \cdot 2\pi r l = \lambda l$$

$$\boxed{\mathbf{D} = \frac{\lambda}{2\pi r} \hat{\mathbf{s}}}$$

$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P}$ . Also  $\vec{\mathbf{D}} = \epsilon \vec{\mathbf{E}}$ . This  $\epsilon$  includes  $\mathbf{P}$ .

$$\epsilon \mathbf{E} = \frac{\lambda}{2\pi r} \hat{\mathbf{s}}$$

$$\mathbf{E} = \frac{\mathbf{D}}{\epsilon}$$

$$\boxed{\mathbf{E}_{in} = \frac{\mathbf{D}}{\epsilon_0 \epsilon_r} = \frac{\lambda}{2\pi \epsilon_0 \epsilon_r r} \hat{\mathbf{s}}}$$

$$= \frac{\mathbf{D}}{\epsilon_0 \epsilon_r}$$

Outside:  $q$  free enclosed  $q_{enc} = \lambda l$

$$\mathbf{D} \cdot 2\pi r l = \lambda l \Rightarrow$$

$$\boxed{\mathbf{D} = \frac{\lambda}{2\pi r} \hat{\mathbf{s}}}$$

In free space  $\epsilon_r = 1$

$$\text{So } \boxed{E_{\text{out}} = \frac{\lambda}{2\pi\epsilon_0 r} \hat{s}}$$

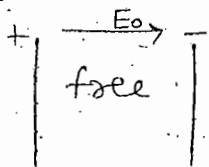
Linear Dielectrics - are those dielectrics<sup>in</sup> which polarisation is proportional to the electric field.

$$\vec{P} \propto \vec{E}$$

$$\Rightarrow \boxed{\vec{P} = \epsilon_0 \chi_e \vec{E}_{\text{Macro}}}$$

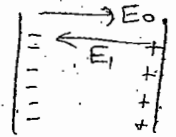
$\epsilon_0 \rightarrow$  permittivity  
 $\chi_e \rightarrow$  Electric susceptibility  
 $E \rightarrow$  Macroscopic elec. field

$$\{ \vec{P} = \alpha \vec{E}_{\text{local}} \}$$



When applied elec. field is  $E_0$ . This is local elec. field & if we filled dielectric b/w these plates. These are many atoms in dielectric.

Then a inside elec. field  $E_1$  which is in opposite dir<sup>n</sup> to  $E_0$ . Then total elec. field =  $E_0 + E_1$  (vector)



This elec. field is Macroscopic. =  $E_0 - E_1$  (magnitudes)

In Maxwell Eq<sup>n</sup>, the Macroscopic E-field on a individual atom is different from average field on plates called Local E.F.

We have  $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$  Also  $D = \epsilon E$

$$\text{So } \epsilon \vec{E} = \epsilon_0 \vec{E} + \epsilon_0 \chi_e \vec{E}$$

$$\epsilon = \epsilon_0 (1 + \chi_e)$$

$$\boxed{\epsilon_r = 1 + \chi_e}$$

If we apply external E.F. on a material then How much it oppose that E.F. will be susceptibility.

Ques - A metallic sphere of radius 'a' carries a charge  $Q$ . It is surrounded by a linear dielectric of permittivity  $\epsilon$  upto radius  $b$ . find

- (i) Polarisation
- (ii) bound charge densities
- (iii) Displacement vector
- (iv) Electric field

- (v) Pot<sup>n</sup> at the centre of the sphere  
 (vi) Energy of this configuration.

$$P = \epsilon_0 \chi_e E$$

$$r < a, q_{enc} = Q \Rightarrow \boxed{D = 0}$$

$$a < r < b, \oint D \cdot ds = q_{enc}$$

$$D \cdot 4\pi r^2 = Q$$

$$\boxed{\vec{D} = \frac{Q}{4\pi r^2} \hat{r}}$$

$$b < r, \boxed{\vec{D} = \frac{Q}{4\pi r^2} \hat{r}}$$

Now electric field,  $\vec{D} = \epsilon \vec{E}$

$$r < a, D = 0 \Rightarrow \boxed{E = 0}$$

$$a < r < b, \boxed{E = \frac{Q}{4\pi \epsilon r^2} \hat{r}}$$

$$r > b, \boxed{E = \frac{Q}{4\pi \epsilon_0 r^2} \hat{r}}$$

outside the sphere  
 permittivity is  $\epsilon_0$ .

Polarisation,  $\vec{P} = \epsilon_0 \chi_e \vec{E}$

$$r < a, \boxed{P = 0}$$

$$a < r < b, \vec{P} = \epsilon_0 (\epsilon_r - 1) \vec{E}$$

$$\boxed{\vec{P} = \frac{(\epsilon - \epsilon_0) Q}{4\pi \epsilon r^2} \hat{r}}$$

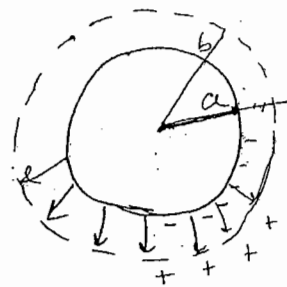
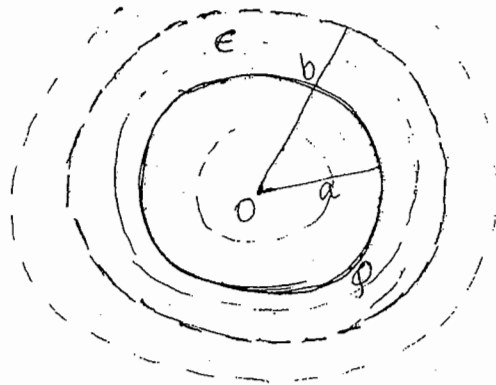
$$r > b, \boxed{\vec{P} = 0}$$

$$\left\{ \begin{array}{l} \vec{P} = \epsilon_0 (\epsilon_r - 1) \vec{E} \\ = 0 \quad [\epsilon_r = 1] \end{array} \right.$$

Bound charge density

$$\sigma_b = \vec{P} \cdot \hat{n} \Rightarrow \sigma_b |_{r=a} = - \frac{(\epsilon - \epsilon_0) Q}{4\pi \epsilon a^2}$$

$$\sigma_b |_{r=b} = + \frac{(\epsilon - \epsilon_0) Q}{4\pi \epsilon b^2}$$



$$P_b = -\vec{\nabla} \cdot \vec{P} \Rightarrow P_b = -\frac{(\epsilon - \epsilon_0)Q}{4\pi\epsilon r^2} \cdot 4\pi r^3$$

$$P_b = -\frac{(\epsilon - \epsilon_0)Q}{\epsilon} r^3$$

$$P_b = 0 \quad a < r < b, \text{ Not enclosing the origin.}$$

Pot<sup>n</sup> at the centre

$$Q_a = Q + \sigma_b|_{r=a} \times 4\pi a^2$$

$$= Q - \frac{(\epsilon - \epsilon_0)Q}{4\pi\epsilon a^2} \cdot 4\pi a^2$$

$$= Q - \frac{(\epsilon - \epsilon_0)Q}{\epsilon} = Q - Q + \frac{\epsilon_0 Q}{\epsilon}$$

$$Q_a = \frac{Q}{\epsilon_r}$$

That's why elec. field inside the dielectric becomes  $\frac{1}{\epsilon_r}$  of its value bcoz charge inside is  $Q/\epsilon_r$ .

$$Q_b = Q + \sigma_b|_{r=b} \times 4\pi b^2$$

$$= Q + \frac{(\epsilon - \epsilon_0)Q}{\epsilon} = Q + Q - \frac{\epsilon_0 Q}{\epsilon}$$

$$Q_b = 2Q - \frac{Q}{\epsilon_r}$$

Pot<sup>n</sup> at centre  $V = \frac{1}{4\pi\epsilon_0} \frac{Q_a}{a} + \frac{1}{4\pi\epsilon_0} \frac{Q_b}{b}$

$$= \frac{1}{4\pi\epsilon_0} \left[ \frac{Q}{\epsilon a} + \left( \frac{\epsilon - \epsilon_0}{\epsilon} \right) \frac{Q}{b} \right]$$

$$V_{\text{centre}} = \frac{Q}{4\pi} \left[ \frac{1}{\epsilon a} + \frac{1}{\epsilon_0 b} - \frac{1}{\epsilon b} \right]$$

By Another Method,

$$V_{\text{centre}} = - \int_{\infty}^0 \vec{E} \cdot d\vec{r}$$

$$= - \int_{\infty}^b \vec{E} \cdot d\vec{r} - \int_b^a \vec{E} \cdot d\vec{r} - \int_a^0 \vec{E} \cdot d\vec{r}$$

$$V = -\frac{Q}{4\pi\epsilon_0} \left[ \frac{-1}{r} \right]_{\infty}^b - \frac{Q}{4\pi\epsilon} \left[ \frac{-1}{r} \right]_b^a - 0 = \frac{Q}{4\pi\epsilon_0} \frac{1}{b} + \frac{Q}{4\pi\epsilon} \frac{1}{a} - \frac{Q}{4\pi\epsilon} \frac{1}{b}$$

Energy  $U = \frac{\epsilon_0}{2} \int_{\text{all space}} E^2 d\tau$

$$U = \frac{\epsilon_0}{2} \left[ \int_0^a E^2 \cdot 4\pi r^2 dr + \int_a^b E^2 \cdot 4\pi r^2 dr + \int_b^\infty E^2 \cdot 4\pi r^2 dr \right]$$

$$U = 0 + \frac{\epsilon_0}{2} \int_a^b \frac{Q^2}{(4\pi\epsilon^2 r^4)} \cdot 4\pi r^2 dr + \frac{\epsilon_0}{2} \int_b^\infty \frac{Q^2}{(4\pi\epsilon_0)^2 r^4} \cdot 4\pi r^2 dr$$

$$= \frac{\epsilon_0}{2} \frac{Q^2}{4\pi\epsilon^2} \left[ -\frac{1}{r} \right]_a^b + \frac{\epsilon_0}{2} \frac{Q^2}{4\pi\epsilon_0^2} \left[ -\frac{1}{r} \right]_b^\infty$$

$$= \frac{\epsilon_0}{2} \frac{Q^2}{4\pi} \left[ -\frac{1}{\epsilon^2} \left( \frac{1}{b} - \frac{1}{a} \right) + \frac{1}{\epsilon_0^2} \left[ -\frac{1}{b} \right] \right]$$

$$= \frac{\epsilon_0}{2} \frac{Q^2}{4\pi} \left[ -\frac{1}{\epsilon^2} \left( \frac{1}{b} - \frac{1}{a} \right) + \frac{1}{\epsilon_0^2} \cdot b \right]$$

$$U = \frac{\epsilon_0 Q^2}{8\pi} \left[ \frac{1}{\epsilon^2 a} - \frac{1}{\epsilon^2 b} + \frac{1}{\epsilon_0^2 b} \right]$$

\* Energy inside the Dielectric is

$$U = \frac{1}{2} \int_{\text{all space}} \vec{D} \cdot \vec{E} d\tau$$

### Boundary Conditions at dielectric interface

Boundary comes when medium changes.

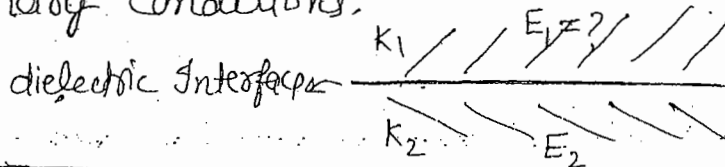
If we have 2 dielectrics having dielectric constants  $k_1$  &  $k_2$ , then if electric field is given in one region suppose  $E_2$  & we have to find out E-field in another region  $E_1$ .

This can be done by Boundary Conditions.

Gauss law in free space

$$\oint \vec{E} \cdot d\vec{s} = \frac{q_{enc}}{\epsilon_0}$$

$$\textcircled{1} E_{\text{above}}^+ - E_{\text{below}}^- = \frac{\sigma}{\epsilon_0}$$



Gauss law in Dielectric

$$\oint \vec{D} \cdot d\vec{s} = q_{enc}$$

$$\textcircled{1} D_{\text{above}}^+ - D_{\text{below}}^+ = \sigma_f \rightarrow \text{free charge density}$$

D is discontinuous by the amount

$$\sigma_f, D^+ \rightarrow \text{Normal Comp.}$$



$$(2) \oint \vec{E} \cdot d\vec{l} = 0$$

$$E_{\text{above}}^{\parallel} = E_{\text{below}}^{\parallel}$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

$$\vec{E} = \frac{1}{\epsilon_0} [\vec{D} - \vec{P}]$$

$$\text{So } \oint \vec{E} \cdot d\vec{l} = \frac{1}{\epsilon_0} \oint [\vec{D} - \vec{P}] \cdot d\vec{l} = 0$$

$$\oint \vec{D} \cdot d\vec{l} = \oint \vec{P} \cdot d\vec{l}$$

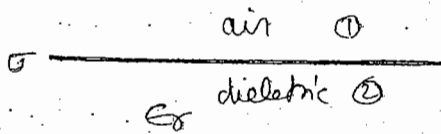
$$D_{\text{above}}^{\parallel} - D_{\text{below}}^{\parallel} = P_{\text{above}}^{\parallel} - P_{\text{below}}^{\parallel}$$

The tangential comp. of  $\vec{D}$  is discontinuous by the difference b/w Polarisation.

Case

1. Air dielectric interface - for air dielectric interface

$$\sigma_f = 0$$



$$D_{\text{above}}^{\perp} = D_{\text{below}}^{\perp}$$

$$D_{1n} = D_{2n}$$

$D_n \rightarrow$  normal comp. of  $\vec{D}$

Normal comp. of displacement vector  $\vec{D}$  is continuous but normal comp. of  $\vec{E}$  is discontinuous bcoz it contains tangential comp. of  $\vec{D}$ .

both charge density (free & bound)  $\sigma_b$  &  $\sigma_f$

$$E_{1n} - E_{2n} = \frac{\sigma}{\epsilon}$$

$$\sigma = \sigma_b + \sigma_f$$

Tangential Component -

$$E_{\text{above}}^{\parallel} = E_{\text{below}}^{\parallel}$$

$$E_{1t} = E_{2t}$$

$$\& D_{\text{above}}^{\parallel} = D_{\text{below}}^{\parallel}$$

$$D_{1t} = D_{2t}$$

still  $\sigma_f = 0$

2. Dielectric - Dielectric interface -  $\sigma_f = 0$

$$E_{1t} = E_{2t}$$

$$D_{1n} = D_{2n} \quad (\sigma_f \text{ should be zero})$$

$\epsilon_{01}$  ① dielectric

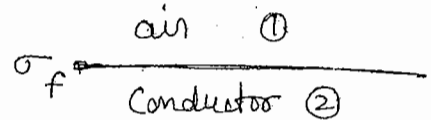
$\epsilon_{02}$  ② dielectric

### 3. Air + Conductor Interface :-

This boundary contain free charge then

$$\sigma_b \neq 0$$

$$D_{above}^{\perp} - D_{below}^{\perp} = \sigma_f$$



$$D_{1n} - D_{2n} = \sigma_f$$

$$\& E_{1n} - E_{2n} = \frac{\sigma_f}{\epsilon_0}$$

In region ② the normal & tangential comp. of electric field is zero.

$$E_{1t} = E_{2t} \quad \{E_{2t} = 0\}$$

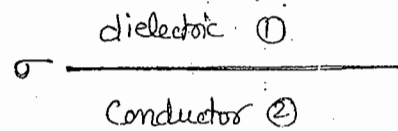
$$E_{1t} = 0$$

$$E_{1n} = \frac{\sigma_f}{\epsilon_0} \quad \& \quad D_{1t} - D_{2t} = P_{1t} - P_{2t}$$

### 4. Dielectric - Conductor Interface :-

Here charge density is  $\sigma$ .

$\sigma_f$  bcoz of conductor &  
 $\sigma_b$  " " dielectric



$$\sigma = \sigma_b + \sigma_f$$

$$E_{1n} - E_{2n} = \frac{\sigma}{\epsilon_0}$$

$$E_{2n} = 0$$

$$D_{1n} - D_{2n} = \sigma_f$$

$$E_{1n} = \frac{\sigma}{\epsilon_0}$$

$$D_{1t} - D_{2t} = P_{1t} - P_{2t}$$

$$E_{1t} = 0$$

Ques :- At the interface b/w 2 linear dielectrics & electric field lines bend as shown in the figure. Show that  $\frac{\tan \theta_2}{\tan \theta_1} = \frac{\epsilon_2}{\epsilon_1}$ . Assuming no free charge at the boundary.

for linear dielectrics

$$\vec{D} = \epsilon \vec{E}$$

This rel<sup>n</sup> is possible only for linear dielectrics.

In boundary b/w dielectric & dielectric, there is No free charge.

$$D_{1n} = D_{2n} \quad \text{--- (i)}$$

$$E_{1t} = E_{2t} \quad \text{--- (ii)}$$

elec. field in region ① is  $\vec{E}_1$  &

② is  $\vec{E}_2$  and permittivity in ① & ② are  $\epsilon_1$  &  $\epsilon_2$  then

$$(i) \rightarrow \epsilon_1 E_{1n} = \epsilon_2 E_{2n} \quad \text{--- (1)}$$

$$(ii) \Rightarrow \epsilon_1 E_1 \cos \theta_1 = \epsilon_2 E_2 \cos \theta_2 \quad \text{--- (1)}$$

$$(ii) \rightarrow E_1 \sin \theta_1 = E_2 \sin \theta_2 \quad \text{--- (2)}$$

Divide (2) / (1)  $\Rightarrow \frac{\tan \theta_1}{\epsilon_1} = \frac{\tan \theta_2}{\epsilon_2}$

$$\Rightarrow \frac{\tan \theta_2}{\tan \theta_1} = \frac{\epsilon_2}{\epsilon_1}$$

Here permittivity was given but if dielectric constant  $\epsilon_{r1}$  &  $\epsilon_{r2}$  are given then

$$\frac{\tan \theta_2}{\tan \theta_1} = \frac{\epsilon_2}{\epsilon_1} = \frac{\epsilon_0 \epsilon_{r2}}{\epsilon_0 \epsilon_{r1}}$$

$$\Rightarrow \frac{\tan \theta_2}{\tan \theta_1} = \frac{\epsilon_{r2}}{\epsilon_{r1}}$$

OR

$$\frac{\cot \theta_2}{\cot \theta_1} = \frac{\epsilon_{r1}}{\epsilon_{r2}} = \frac{\epsilon_1}{\epsilon_2}$$

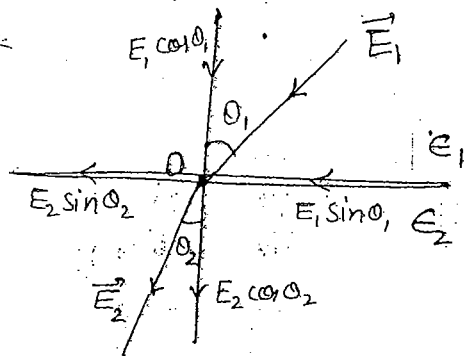
If an electric field comes from lower to higher dielectric region then it will bend away from the normal.

$$\text{If } \epsilon_{r1} = 2 \Rightarrow \frac{\epsilon_{r2}}{\epsilon_{r1}} > 1$$

$$\epsilon_{r2} = 3$$

$$\left\{ \begin{array}{l} \frac{\epsilon_{r2}}{\epsilon_{r1}} = \frac{3}{2} \\ = 1.5 > 1 \end{array} \right\} \text{ so } \tan \theta_2 > \tan \theta_1$$

$$\theta_2 > \theta_1$$



Ques :- Two extensive homogenous isotropic dielectric meet on  $z=0$  plane. for  $z>0$ ,  $\epsilon_{r1} = 4$  & for  $z<0$ ,  $\epsilon_{r2} = 3$ . A uniform electric field  $\vec{E}$

$$\vec{E}_1 = 5\hat{x} - 2\hat{y} + 3\hat{z} \text{ KV/m}$$

exist for  $z>0$ . Find

(a)  $E_2$  for  $z<0$  (b)  $D_1$ ,  $z>0$  &  $D_2$ ,  $z<0$

(c) The Angles,  $E_1$  &  $E_2$  making with the normal.

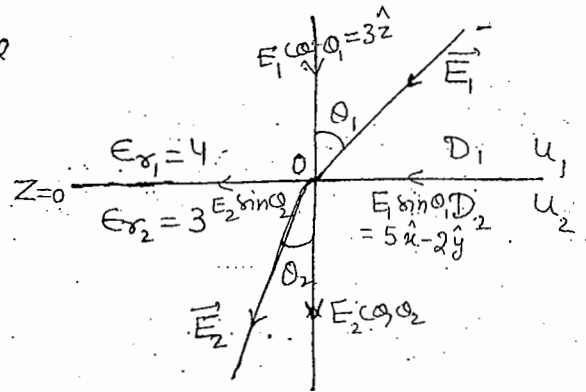
(d) Energy densities Joule/m<sup>3</sup> in both dielectrics.

Both are dielectrics - so there is no free charge.  $\therefore \sigma_f = 0$

$$D_{1n} = D_{2n} \text{ --- (1)}$$

$$E_{1t} = E_{2t} \text{ --- (2)}$$

$$\Rightarrow \epsilon_1 E_{1n} = \epsilon_2 E_{2n} \text{ --- (3)}$$



vector normal to the surface is  $z$ .

then  $E_{1t} = 5\hat{x} - 2\hat{y}$ ,  $E_{1n} = 3\hat{z}$

(a) from (2)  $\Rightarrow E_{1t} = E_{2t} \Rightarrow \boxed{E_{2t} = 5\hat{x} - 2\hat{y}}$

(3)  $\Rightarrow \epsilon_0 \epsilon_{r1} E_{1n} = \epsilon_0 \epsilon_{r2} E_{2n}$

$$E_{2n} = \frac{\epsilon_{r1}}{\epsilon_{r2}} E_{1n} = \frac{4}{3} \times 3\hat{z}$$

$$E_{2n} = 4\hat{z}$$

So  $E_2 = E_{1n} + E_{2n}$

$$\boxed{E_2 = 5\hat{x} - 2\hat{y} + 4\hat{z}} \text{ A}$$

(b)  $\vec{D} = \epsilon \vec{E}$

$$\vec{D}_1 = \epsilon_{r1} \epsilon_0 \vec{E}_1$$

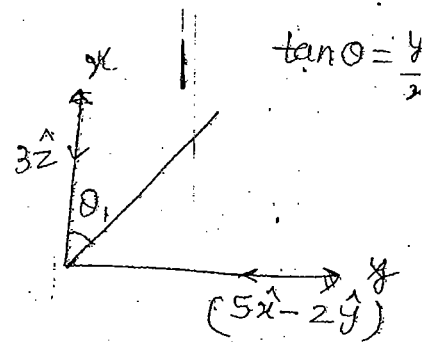
$$\boxed{\vec{D}_1 = 4 \epsilon_0 \vec{E}_1}$$

&  $\boxed{\vec{D}_2 = 3 \epsilon_0 \vec{E}_2}$  A

$$(c) \quad \frac{\tan \theta_2}{\tan \theta_1} = \frac{\epsilon_{r2}}{\epsilon_{r1}} = \frac{3}{4}$$

$$\tan \theta_1 = \frac{|5\hat{x} - 2\hat{y}|}{|3\hat{z}|} = \frac{\sqrt{29}}{\sqrt{9}}$$

$$\boxed{\tan \theta_1 = \frac{\sqrt{29}}{3}}$$



$$\text{So } \tan \theta_2 = \tan \theta_1 \times \frac{3}{4} = \frac{\sqrt{29}}{3} \times \frac{3}{4}$$

$$\boxed{\tan \theta_2 = \frac{\sqrt{29}}{4}}$$

$$(d) \quad U = \frac{\epsilon_0}{2} \int_{\text{all space}} E^2 d\tau$$

$\left. \begin{array}{l} \text{Energy density} = \\ \text{Energy per unit volume} \end{array} \right\} u = \frac{U}{V}$

$$u_1 = \frac{\epsilon_0}{2} E_1^2$$

$$u_2 = \frac{\epsilon_0}{2} E_2^2$$

$$\Rightarrow u_1 = \frac{\epsilon_0}{2} [\sqrt{25+4+9}]^2 = \frac{\epsilon_0}{2} (38) = 19 \epsilon_0$$

$$\boxed{u_1 = 19 \epsilon_0}$$

$$\Rightarrow u_2 = \frac{\epsilon_0}{2} [\sqrt{25+4+16}]^2 = \frac{\epsilon_0}{2} (90)$$

$$\boxed{u_2 = 45 \epsilon_0}$$

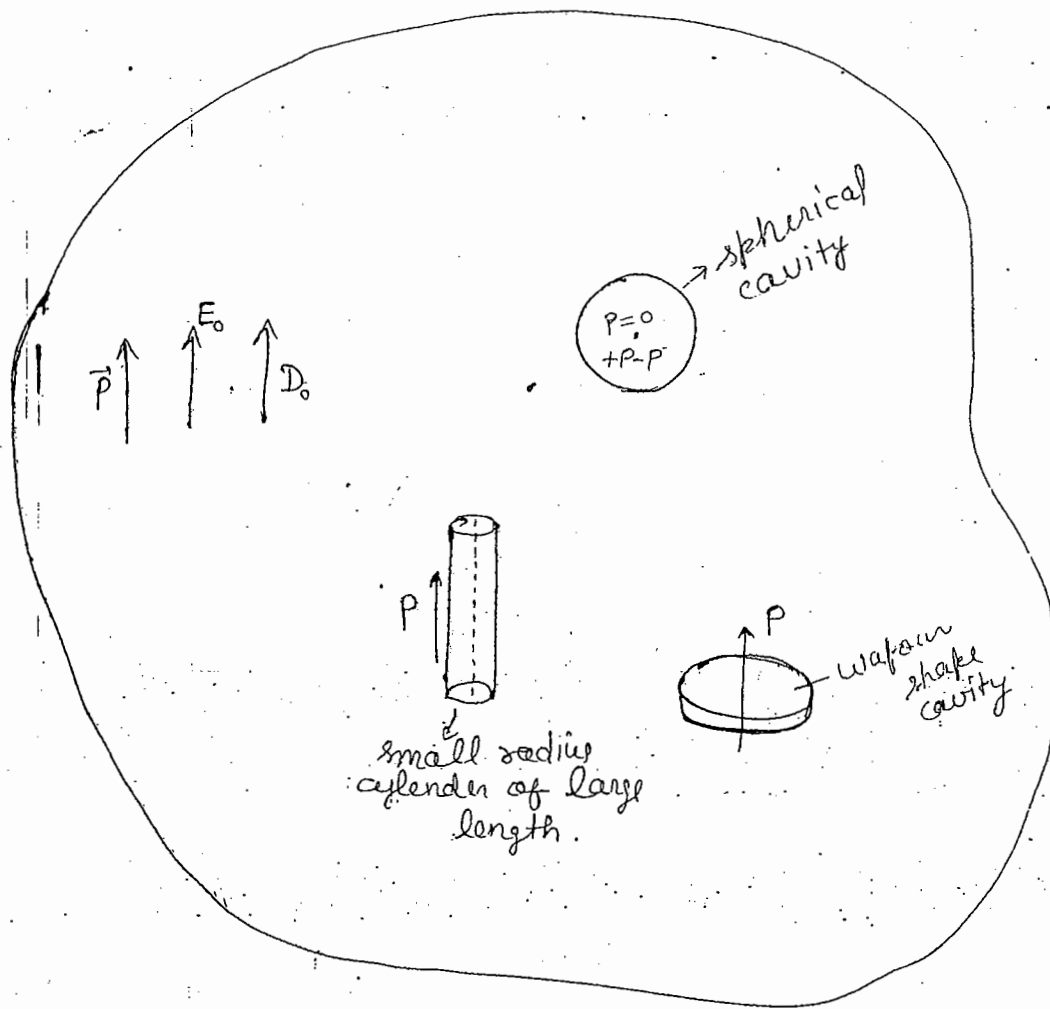
$$\left. \begin{array}{l} E = KV \\ E = 10^3 V \end{array} \right\}$$

$$\Rightarrow \boxed{u_1 = 19 \epsilon_0 \times 10^6 \text{ J/m}^3 \quad \& \quad u_2 = 45 \epsilon_0 \times 10^6 \text{ J/m}^3}$$

Que:- Suppose the field inside a large piece of dielectric is  $E_0$  such that electric displacement is  $D_0$  s.t.

$$\vec{D}_0 = \epsilon_0 \vec{E} + \vec{P}$$

- Now a spherical cavity is hollowed out of the material. Find electric field & displacement vector inside the cavity.
- To the same for a long riddle shape cavity running parallel to  $\vec{P}$ .
- To the same for a thin wavy shaped cavity  $\perp$  to  $\vec{P}$ .



Electric field in spherical cavity is more as compare to  
 Ele. field in dielectric. As we know that elec-field in  
 free space is greater than ele. field in dielectric.  
inside the spherical cavity

$$\vec{D}_0 = \epsilon_0 \vec{E} + \vec{P}$$

Polarisation,  $P = 0$   
 $+P - P = 0$

bcz of  $+P$  the elec. field will be  $E_0$   
 & " "  $-P$  " " " "  $-\frac{\vec{P}}{3\epsilon_0}$

$$\vec{E} = -\frac{\vec{P}}{3\epsilon_0}$$

So total Elec. field in spherical cavity is

$$= \vec{E}_0 + \frac{\vec{P}}{3\epsilon_0}$$

have  
 We if a uniformly polarised sphere,  $E_0$  is external  
 applied Ele. field then due to external field, internal ele.  
 field will be produced  $P/3\epsilon_0$ .

$$\text{Total} = E_0 - \frac{P}{3\epsilon_0} < E_0$$



$$\vec{D}_0 = \epsilon_0 \vec{E}_0 + \vec{P} \Rightarrow (\epsilon_0 E_0 = D_0 - P)$$

$$\vec{D} = \epsilon_0 \vec{E} \quad (\text{Put } \vec{E}')$$

$$\vec{D} = \epsilon_0 \vec{E}' + \frac{\vec{P}}{3}$$

$$\vec{D} = D_0 - \vec{P} + \frac{\vec{P}}{3} \Rightarrow \boxed{\vec{D}' = \vec{D}_0 - \frac{2\vec{P}}{3}}$$

Niddle shape cavity,

When external elec. field  $E_0$  is applied then it will produce polarisation  $\vec{P}$  inside it then total elec. field

$$\boxed{\vec{E}' = \vec{E}_0 - \frac{\vec{P}}{\epsilon_0} (1 - \cos \alpha)}$$

for Niddle shape cavity

$$\boxed{\theta = 0^\circ}$$

$$\text{So } \vec{E} = \vec{E}_0 - \frac{\vec{P}}{\epsilon_0} (1 - 1) \neq$$

$$\Rightarrow \boxed{\vec{E}' = \vec{E}_0}$$

$$\begin{aligned} \vec{D} &= \epsilon_0 \vec{E}' \\ &= \epsilon_0 \vec{E}_0 - P + P \end{aligned}$$

$$\boxed{\vec{D} = \vec{D}_0 - \vec{P}}$$

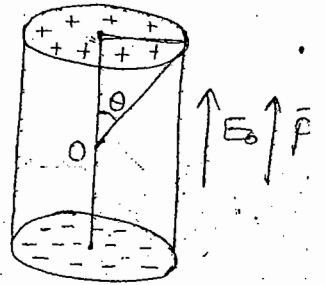
Wafer shape  $\boxed{\theta = \pi/2}$

$$\vec{E} = \vec{E}_0 + \frac{\vec{P}}{\epsilon_0}$$

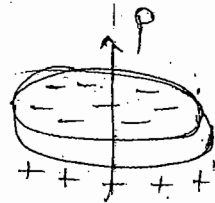
$$\left. \begin{array}{l} P=0 \Rightarrow +P - P = 0 \\ \quad \downarrow \quad \downarrow \\ \quad E_0 \quad -\frac{P}{\epsilon_0} \end{array} \right\} \text{by superposition} \\ \text{Principal}$$

$$\begin{aligned} \vec{D} &= \epsilon_0 \vec{E}' \\ &= \epsilon_0 \vec{E}_0 + P \end{aligned}$$

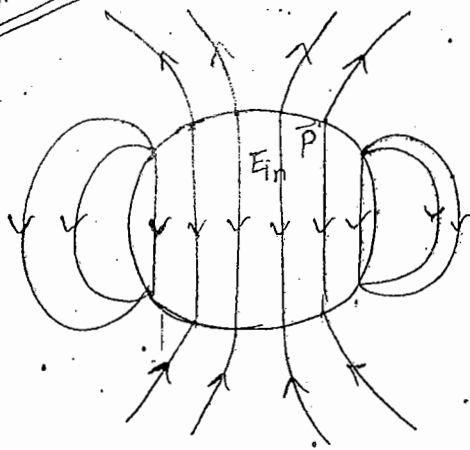
$$\boxed{\vec{D}' = \vec{D}_0}$$



elec. field inside the dielectric is less than  $E_0$

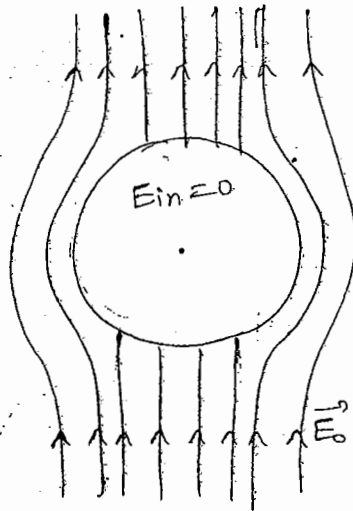


Problem :-



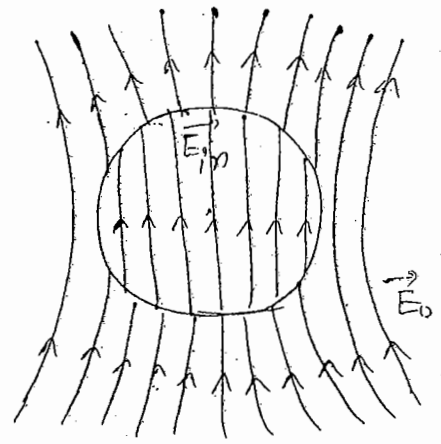
(i)  $\vec{P}$  uniformly polarised sphere

$$\vec{E}_{in} = -\frac{\vec{P}}{3\epsilon_0}$$



(ii) Conducting sphere in uniform elec. field

$$E_{in} = 0$$



(iii) sphere filled with homogeneous linear dielectric

$$\vec{E}_{in} = \frac{3}{\epsilon_r + 2} \vec{E}_0$$

Ques :- The space b/w plates of parallel plate capacitor is filled with two slabs of linear dielectric material. Each slab has thickness  $a$ . Slab 1 has dielectric const. of 2. Slab 2 has a dielectric const. of 1.5. Free charge density on the top plate is  $+\sigma$  & the bottom plate is  $-\sigma$ . Find

(a)  $\vec{D}$  in each slab

(b)  $\vec{E}$  in each slab

(c)  $\vec{P}$  in each slab

(d)  $V$  b/w the plates

(e) location & amount of bound charges

$+\sigma$  &  $-\sigma$  are free charge density bcoz plates of parallel plate capacitor is made up of metal. & on metal surface free charges are found & bound charge density is zero.



$$\textcircled{1}, \oint \vec{D} \cdot d\vec{S} = q_{\text{enc}}$$

$$D \cdot A = \sigma A$$

$$\boxed{D_1 = \sigma}$$

Amount of bound charges in slab (1) & (2) are different coz dielectric constant is different.

But amount of free charges is same & D is determined by free charges. so

$$\boxed{D_1 = D_2 = \sigma}$$

Electric field - It is determined by both bound & free charges.

$$\vec{D} = \epsilon_0 \epsilon_r \vec{E}$$

$$\boxed{\vec{E}_1 = \frac{\sigma}{2\epsilon_0} (-\hat{z})}$$

$$\boxed{\vec{E}_2 = \frac{2\sigma}{3\epsilon_0} (-\hat{z})}$$

Polarisation  $\vec{P} = \epsilon_0 \chi_e \vec{E}$

$$\vec{P} = \epsilon_0 (\epsilon_r - 1) \vec{E}$$

$$\boxed{\vec{P}_1 = \frac{\sigma}{2} (-\hat{z})}$$

$$\boxed{\vec{P}_2 = \frac{\sigma}{3} (-\hat{z})}$$

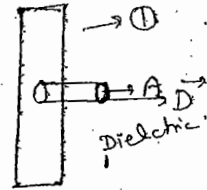
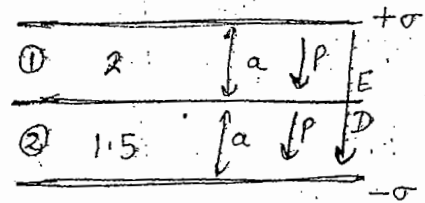
Pot<sup>n</sup> diff  $\vec{P}_1$  &  $\vec{P}_2$  adjust so that  $D_1$  &  $D_2$  same.

$$V = V_1 + V_2$$

$$V = \frac{\sigma a}{2\epsilon_0} + \frac{2\sigma a}{3\epsilon_0}$$

$$= \frac{\sigma a}{\epsilon_0} \left[ \frac{1}{2} + \frac{2}{3} \right]$$

$$\boxed{V = \frac{7\sigma a}{6\epsilon_0}}$$



flux will pass throo only by the cross-section which is in dielectric.

$D_1$  &  $D_2$  are same but  $E_1$  &  $E_2$  and  $P_1$  &  $P_2$  are different. so  $E_1$  &  $P_1$  and  $E_2$

(e) There are 4 surfaces, :- Upper & lower surfaces of dielectric (1) & (2).

Upper surface of Upper dielectric  $\sigma_b = -\vec{P}_1 \cdot \hat{n} = -\frac{\sigma}{2}$

lower " " " "  $\sigma_b = +\frac{\sigma}{2}$

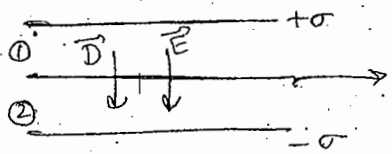
Upper surface of lower dielectric  $\sigma_b = -\frac{\sigma}{3}$

lower " " " "  $\sigma_b = +\frac{\sigma}{3}$

In dielectric (1),  $P_{b1} = 0$  { bcoz P is uniform }

" (2),  $P_{b2} = 0$  { " " " " }

\*



At this interface :-

(a) both E & D are continuous

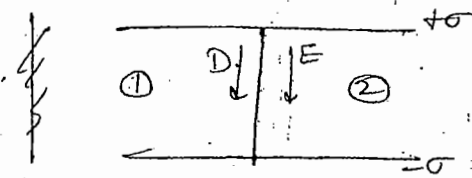
(b) " " " " dis " "

(c) E is continuous, D is discontinuous

✓ (d) E is discontinuous, D is continuous

Dir<sup>n</sup> of  $\vec{D}$  &  $\vec{E}$  → Normal to the surface. Normal comp. of D is continuous  
In Dielectric → free charges are zero.

\*



Dir<sup>n</sup> of  $\vec{D}$  &  $\vec{E}$  → tangential to the surface then

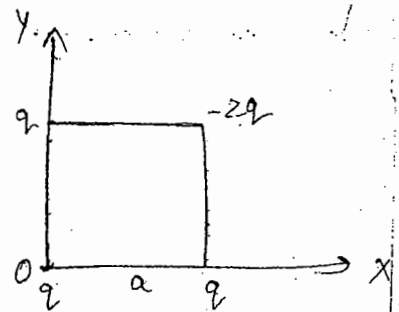
✓ (c) → correct.

tangential comp. of E is continuous.

(34) Taking 0 → origin

$$\vec{p} = 0 + qa\hat{x} + qa\hat{y} + (-2q)(a)\hat{x} + (-2q)(a)\hat{y}$$

$$= -qa\hat{i} - qa\hat{j}$$



## Assignment (Level-I)

①. (d) ✓

Q4 :- How many equilibrium points are there?

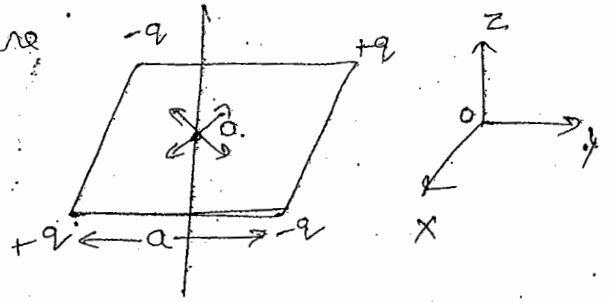
(a) 0

(b) 1

(c) 5

✓ (d) ∞

There are ∞ points at which E field is zero. If there are all +q charges on corner then there will be only 1 point at which E = 0. i.e. Equilibrium

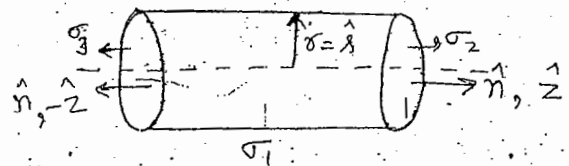


⑤.  $\vec{P} = P_0 \hat{r}$

$\sigma_b = \vec{P} \cdot \hat{n}$

$\sigma_1 = P_0 R$

$\sigma_2 = \sigma_3 = 0 \quad (\hat{r} \cdot \hat{z} = 0)$



⑪  $\vec{P} = K r^2 \hat{r}$

$P_b = -\vec{\nabla} \cdot \vec{P} = -\frac{1}{r^2} \frac{d}{dr} (r^2 \cdot K r^2)$

$P_b = -4K r$

⑫

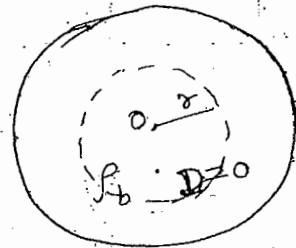
$q_b = \int P_b d\tau$

$= -4K \int_0^d r 4\pi r^2 dr$

$= -4K [\frac{r^4}{4}]_0^d \pi = -4K \pi d^3$

$\oint E \cdot ds = \frac{+q}{\epsilon_0} \Rightarrow E \cdot 4\pi d^2 = \frac{-4K \pi d^3}{\epsilon_0}$

$\vec{E} = -\frac{K d^2}{\epsilon_0} \hat{r}$



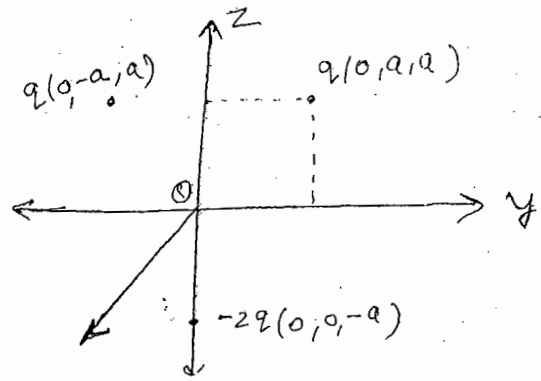
OR Another method :-  $D = 0$  (there is No free charges so  $D = 0$ )

$D = \epsilon_0 E + P \Rightarrow 0 = \epsilon_0 E + P$

$\Rightarrow E = -\frac{P}{\epsilon_0}$

$\vec{E} = -\frac{K d^2}{\epsilon_0} \hat{r}$

16) Monopole Mom = 0  
 so dipole mom. is independent  
 on choice of origin.  
 Take O as origin



Dipole Mom  $\rightarrow$

$$p = q a \hat{y} + q a \hat{z} + q(a) \hat{y} + q a \hat{z} + (-2q)(-a) \hat{z}$$

$$p = 4qa \hat{z}$$

17) (22)  $\phi = \phi_0 (x^2 + y^2 + z^2)$

$$\nabla^2 \phi = \rho / \epsilon_0 \Rightarrow \rho = -\epsilon_0 (\nabla^2 \phi) = -\epsilon_0 (2+2+2) = -6\epsilon_0 \phi_0$$

41)  $E = 0, r < a$

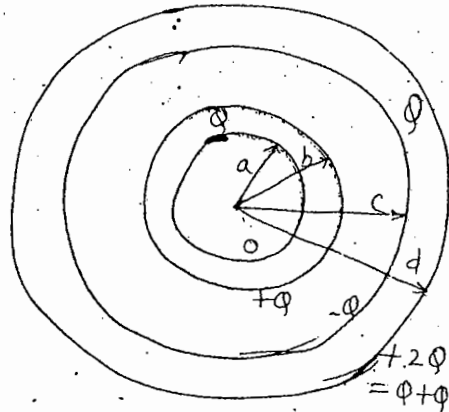
$E = 0, a < r < b$

(because no charge can exist in conducting sphere)

$E = \frac{\phi}{4\pi\epsilon_0 r^2}, b < r < c$

$E = 0, b < r < c$

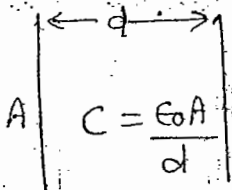
$E = \frac{2\phi}{4\pi\epsilon_0 r^2}, r > d$



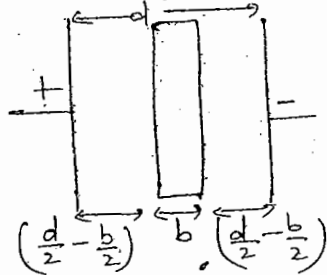
42) charge density of outer surface of inner shell = charge density of outer surface of outer shell

$$\frac{\phi}{4\pi b^2} = \frac{2\phi}{4\pi d^2} \Rightarrow d = \sqrt{2} b$$

50)



Now if we put a metal of thickness 'b'



$\rightarrow$  This is a series combination, because in parallel combination all the capacitors are at same potential.

$$C_1 = \frac{\epsilon_0 A}{(\frac{d}{2} - \frac{b}{2})} = \frac{2\epsilon_0 A}{(d-b)} \quad \& \quad C_2 = \frac{2\epsilon_0 A}{(d-b)}$$


for series combination,  
resultant capacitance  $\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2}$

$$\Rightarrow \frac{1}{C} = \frac{d-b}{2\epsilon_0 A} + \frac{d-b}{2\epsilon_0 A}$$

$$\frac{1}{C} = \frac{d-b}{\epsilon_0 A} \Rightarrow \boxed{C = \frac{\epsilon_0 A}{d-b}}$$

As compare to previous case, this ~~is~~ value of  $C$  is decrease by a finite value.

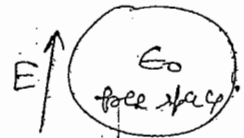
If full capacitor is filled with metal then  $C \rightarrow \infty$ .

87)  $\vec{E}_{in} = \frac{3}{\epsilon_0 + 2} \vec{E}_0$  (free space  $\rightarrow \epsilon_0$ , inside field  $\rightarrow ?$ , permittivity  $\epsilon$ ) 

$$= \left( \frac{3\epsilon_0}{\epsilon + 2\epsilon_0} \right) \vec{E}_0$$

In outer our prob. external elec. field  $\vec{E}$  inside & permittivity is  $\epsilon_0$ . Replace  $\epsilon_0$  by  $\epsilon$ .

$$E_{in} = \left( \frac{3\epsilon}{\epsilon_0 + 2\epsilon} \right) E$$



90) Energy  $W = \frac{1}{2} CV^2$

This much work done req. to store the charge.

for spherical capacitor  $C = 4\pi\epsilon_0 r$

$$W = \frac{1}{2} 4\pi\epsilon_0 r V^2 \quad (r=2)$$

$$= \frac{1}{2} \times \frac{1}{9 \times 10^9} \times (3000)^2 = \frac{1}{2} \times \frac{1}{9 \times 10^9} \times 9 \times 10^6$$

$$= 10^{-3} \text{ J}$$

92)  $\vec{E} = P \left[ xy \hat{i} + \left( \frac{1}{2}x^2 + y^2 \right) \hat{j} \right]$

$$V = - \int_{(0,0)}^{(1,2)} \vec{E} \cdot d\vec{l}$$

$$(d\vec{l} = dx \hat{x} + dy \hat{y})$$

$$= -P \int [xy dx + \left( \frac{1}{2}x^2 + y^2 \right) dy]$$

Let  $y = 2x \Rightarrow dy = 2 dx$

$$V = -P \int_0^1 [2x^2 + \left( \frac{1}{2}x^2 + 4x^2 \right) 2] dx = -11P \int_0^1 x^2 dx$$

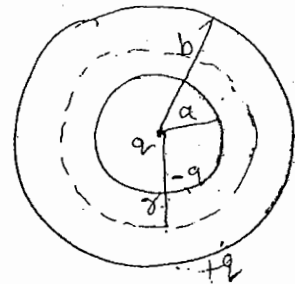
$$V = -11P \left( \frac{x^3}{3} \right)_0^1 = -\frac{11P}{3} \quad \left\{ \begin{array}{l} \text{sign means pot}^n \text{ is lower} \\ \text{at final position} \end{array} \right.$$

(93) Monopole = 0  
 Dipole mom =  $Q(-b)\hat{x} + Q(b)\hat{x} + (-Q)(-a)\hat{y} + (-Q)(a)\hat{y}$   
 $= 0$   
 So  $\phi$ . Mom.  $\rightarrow$  dominates.

(96)  $a < r < b$

$$V = \frac{q}{4\pi\epsilon_0 r} - \frac{q}{4\pi\epsilon_0 r} + \frac{q}{4\pi\epsilon_0 b}$$

$$V = \frac{q}{4\pi\epsilon_0 b}$$



(107)  $\vec{E} = \vec{E}_1 + \vec{E}_2$

$$u_1 = \frac{\epsilon_0}{2} E_1^2 \quad \& \quad u_2 = \frac{\epsilon_0}{2} E_2^2$$

$$u = \frac{\epsilon_0}{2} E^2 = \frac{\epsilon_0}{2} E_1^2 + \frac{\epsilon_0}{2} E_2^2 + \epsilon_0 E_1 E_2$$

$$= \frac{\epsilon_0}{2} (E_1 + E_2)^2 \Rightarrow u_1 + u_2 + \text{extra}$$

i.e. Energy does not follow superposition.

### Assignment - level - II

(7)  $\vec{P} = (5z^2 + 7)\hat{k}$

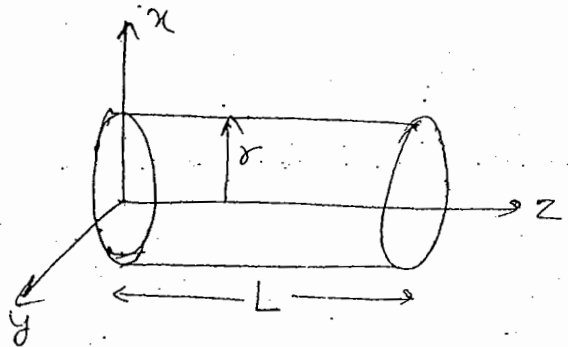
$$\rho_b = -\nabla \cdot \vec{P} = -10z$$

$$q_b = \int \rho_b d\tau$$

$$= - \int_0^L \int_0^{\delta} \int_0^{2\pi} 10z \delta^2 d\phi ds dz$$

$$= -10 \frac{L^2}{2} \cdot \frac{\delta^2}{2} \cdot 2\pi$$

$$q_b = -5\pi\delta^2 L^2 \quad (d) \checkmark$$



(22)  $+\frac{\partial V_{out}}{\partial \delta} = \Delta V_{out} = -\frac{\sigma}{\epsilon_0}$

$$V_{out} = \tau E_0 \left(1 - \frac{R^3}{\delta^3}\right) \delta \text{ case}$$

$$\sigma = \epsilon_0 \frac{\partial V}{\partial \delta} = +\epsilon_0 E_0 (-3)$$

33) Capacitance per unit length

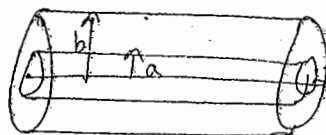
$$\frac{C}{l} = \frac{2\pi\epsilon_0}{\ln(b/a)}$$

\* dielectric is filled then  $\epsilon_0 \rightarrow \epsilon$

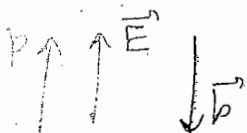
$$\frac{C}{l} = \frac{2\pi\epsilon_0\epsilon_r}{\ln(b/a)}$$

$$\frac{C}{l} = \frac{4\pi\epsilon_0}{2\ln(b/a)} = \frac{3.5}{9 \times 10^9 \times 2 \times \ln 2}$$

F/10<sup>-3</sup> Km



75)



$$\begin{aligned} W = \Delta U &= U_f - U_i \\ &= pE + pE \\ &= 2pE \end{aligned}$$

$$U = \vec{p} \cdot \vec{E}$$

$$U_f = -pE \cos 180^\circ$$

$$U_i = -pE \cos 0^\circ$$

92)

$$\rho(r) = \frac{A}{r} e^{-kr}$$

$$\nabla^2 V = -\rho/\epsilon_0$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial V}{\partial r} \right) = -\frac{1}{\epsilon_0} \frac{A}{r} e^{-kr}$$

$$\frac{\partial}{\partial r} \left( r^2 \frac{\partial V}{\partial r} \right) = -\frac{A}{\epsilon_0} r e^{-kr}$$

$$r^2 \frac{\partial V}{\partial r} = -\frac{A}{\epsilon_0} \left[ -\frac{r}{k} e^{-kr} + \frac{1}{k^2} e^{-kr} \right]$$

$$\begin{aligned} \frac{\partial V}{\partial r} &= -\frac{A}{\epsilon_0} \left[ -\frac{1}{kr} e^{-kr} - \frac{1}{k^2 r^2} e^{-kr} \right] \\ &= \frac{A}{\epsilon_0} \left[ \frac{1}{kr} e^{-kr} + \frac{1}{k^2 r^2} e^{-kr} \right] \end{aligned}$$

$$V = \frac{A}{\epsilon_0 k} \left[ \int \frac{1}{r} e^{-kr} dr + \int \frac{1}{k r^2} e^{-kr} dr \right]$$

$$V = \frac{A}{\epsilon_0 k} \left[ -\frac{1}{kr} e^{-kr} - \int \frac{1}{k r^2} e^{-kr} dr + \int \frac{1}{k r^2} e^{-kr} dr \right]$$

$$\boxed{V = -\frac{A}{\epsilon_0 k^2} \frac{1}{r} e^{-kr}} \quad (b) \checkmark$$

102)

$$\vec{E} = \alpha(1 - e^{-\gamma R}) \frac{\hat{r}}{r^2}$$

$$\rho = \nabla \cdot \vec{E}$$

$$\rho =$$

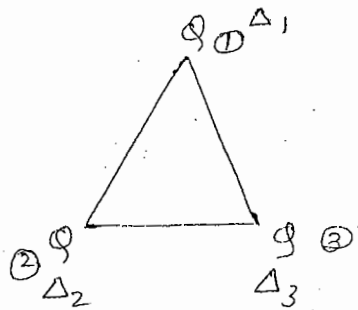
107

$$\Delta_1 = 0$$

$$\Delta_2 = \frac{Q^2}{4\pi\epsilon_0 a^2}$$

$$\Delta_3 = \frac{2Q^2}{4\pi\epsilon_0 a^2} = \frac{Q^2}{4\pi\epsilon_0 a^2} + \frac{Q^2}{4\pi\epsilon_0 a^2}$$

$$\Delta_1 : \Delta_2 : \Delta_3 = 0 : 1 : 2$$



109

$$\vec{D} = (2y^2 + z)\hat{i} + 4xy\hat{j} + x\hat{k}$$

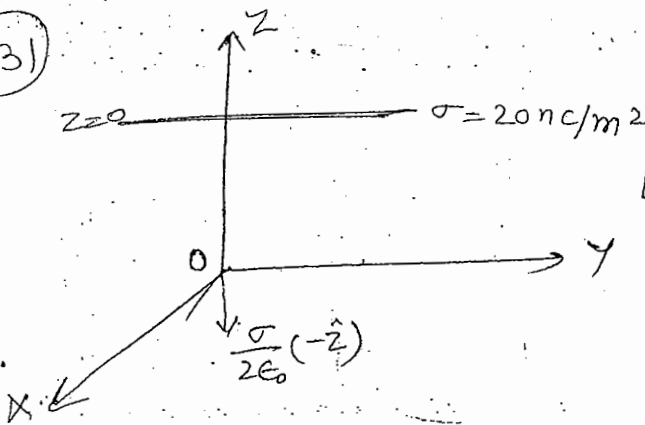
$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\vec{\nabla} \cdot \vec{D} = 4x \Rightarrow \rho_f = 4x$$

$$q_f = \int \rho_f d\tau = \int_0^1 \int_0^1 \int_0^1 4x dx dy dz$$

$$= 1 \times 1 \times 4 \left( \frac{x^2}{2} \right) \Big|_0^1 = 2 \text{ C}$$

131



$$\sigma = 20 \text{ nC/m}^2 = 20 \times 10^{-9} \text{ C/m}^2$$

$$E = \frac{\sigma}{2\epsilon_0} = \frac{2\pi\sigma}{4\pi\epsilon_0} = \frac{2\pi \times 20 \times 10^{-9}}{4 \times 10^9} = -360\pi \hat{z} \text{ V/m}$$

145

$$\frac{\epsilon_1}{\epsilon_0} = 2, \quad \frac{\epsilon_2}{\epsilon_0} = 5$$

$$E_1 = 2\hat{i} - 3\hat{j} + 5\hat{k}$$

$$D_1 = \epsilon_1 E_1$$

$$= 2\epsilon_0 (2\hat{i} - 3\hat{j} + 5\hat{k}) = \epsilon_0 (4\hat{i} - 6\hat{j} + 10\hat{k})$$

$$D_{1n} = D_{2n}$$

$$D_{2n} = 10\epsilon_0 \hat{z}$$

$$E_{1t} = E_{2t}$$

$$E_{2t} = 2\hat{x} - 3\hat{y}$$

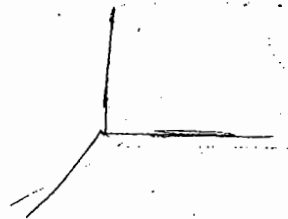
$$D_{2t} = \epsilon_2 E_{2t}$$

$$= \epsilon_0 (2\hat{x} - 3\hat{y}) 5$$

$$D_2 = D_{2t} + D_{2n}$$

$$D_2 = \epsilon_0 (10\hat{i} - 15\hat{j} + 10\hat{k})$$

$$\epsilon_0 (10\hat{i} - 15\hat{j} + 10\hat{k})$$





(146)

$$a = 0.5 \times 10^{-10} \text{ m}, \quad E = 30 \times 10^5 \text{ V/m}$$

$$E = \frac{1}{4\pi\epsilon_0} \frac{q d}{a^3} \Rightarrow d = \frac{4\pi\epsilon_0 Q^3 E}{2} = \frac{0.125 \times 10^{-30} \times 30 \times 10^5}{9 \times 10^9 \times 1.6 \times 10^{19}}$$

$$= 2.6 \times 10^{-16}$$

(147)

$$P = \alpha E \Rightarrow \alpha = \frac{P}{E} = \frac{e d}{E}$$

$$\alpha = 4\pi\epsilon_0 Q^3 = \frac{0.125 \times 10^{-30}}{9 \times 10^9}$$

# Magnetostatics

Here we have STATIC Magnetic field (not changing with time)

Static electric field produces from charge at rest. (Not moving). And its condition is

$$\nabla \times E = 0$$

Similarly to produce magnetic field we need current. i.e. To ~~pro~~ static magnetic field can be produced from current.

When Magnetic field not changing with time - Magnetostatic  
i.e. Current is not a fun<sup>n</sup> of time.

The current which is not changing with time  $\rightarrow$  Steady Current.

When flow of current is steady then it is steady current.

Defination of Steady Current :- The current flowing smoothly without pilling up charge anywhere called Steady Current.

If charge accumulate then M.F. will not be static.

If wire is uncharged. At the point in space, there is mag. field but not electric field will present.

Inside the wire, if current flows then electric field will definitely present.

If a charge is moving with constant velocity  $v$  then there will be static mag field & also electric field. Elec. field & mag field in this case do not depend on each other.

If  $v$  is changing with time then it is accelerated motion. then both elec. & mag. field depend on each other. (both depends on time)

If a wire is connected to a battery then a steady current will flow in wire (dc current)

Magnetic force :- Mag. force on a charge particle  $q$  moving with velocity  $v$  in mag. field  $B$  then

$$\vec{F} = q(\vec{v} \times \vec{B})$$

In electric field, we have force  $\vec{F} = q\vec{E}$

Magnetic force is also called Loxentz force.

Magnetic forces do no work, they only change the dir<sup>n</sup> of motion of charged particle.

If a charge particle  $q$  moving with  $v$  in  $\vec{B}$  then work done  $\&$  in the distance travelled  $d\vec{r}$  is

$$dW = \vec{F} \cdot d\vec{r}$$

$$dW = \vec{F} \cdot \frac{d\vec{r}}{dt} dt = q(\vec{v} \times \vec{B}) \cdot \vec{v} dt$$

$\vec{v} \cdot dt \rightarrow$  distance travelled

$\vec{v} \times \vec{B}$  will be the  $\perp$  vector to both  $\vec{v}$  &  $\vec{B}$ .

so  $dW = 0$

i.e. Power associated by mag. force is zero.

These type of forces are called Fictitious forces.

If in any problem, mag. force do work then there -  
 $\rightarrow$  by changing the mag. field there generate mag. force.  
 $\&$  then in that case mag. field do the work, not the mag. force.

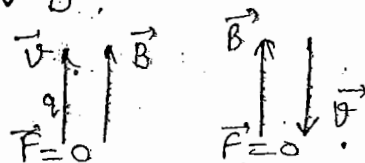
Path of the charged particle in mag. field :- Suppose a charge particle  $q$  moving with velocity  $\vec{v}$  in  $\vec{B}$  then force on it  $\vec{F} = q(\vec{v} \times \vec{B})$

then magnitude of force will depend on angle b/w  $\vec{v}$  &  $\vec{B}$  as  $|\vec{F}| = q v B \sin \theta$

$\theta \rightarrow$  angle b/w  $v$  &  $B$ .

Case 1 :- If  $\theta = 0, \pi$

$$F = 0$$



charged particle

It will move undeflected if  $v$  &  $B$  are parallel or antiparallel. [undeflected means straight line]

Case 2.

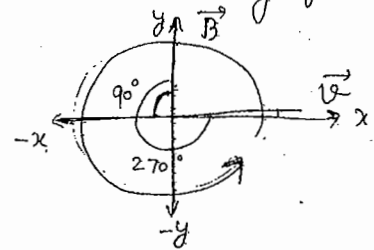
$$\theta = (90^\circ) \frac{\pi}{2}, \frac{3\pi}{2}$$

then charged particle will follow circular path & rotate in a plane which is perpendicular to the mag. field.

If a charge particle move in a circle. i.e.  $v$  &  $B$  are  $\perp$  to each other (angle b/w them is  $\frac{\pi}{2}$  or  $\frac{3\pi}{2}$ )

Then its motion is called

Cyclotron motion.



If particle do rotational motion then there will be 2 forces on it.  $\rightarrow$  Lorentz & centripital force.

$$qvB = \frac{mv^2}{r}$$

Momentum  $\boxed{p = mv = qBr}$  — (A)

Now frequency of rotation (Angular freq.):-

$$\omega = 2\pi f = \frac{2\pi}{T}$$

Particle should travel in a circle so

$$T = \frac{2\pi r}{v}$$

$$\therefore \omega = \frac{2\pi v}{2\pi r} \Rightarrow \omega = \frac{v}{r}$$

Compare the value of  $\frac{v}{r}$  with eq. (A),

ang. freq.  $\boxed{\omega = \frac{qB}{m}}$

freq.  $f = \frac{\omega}{2\pi} \Rightarrow \boxed{f = \frac{qB}{2\pi m}}$

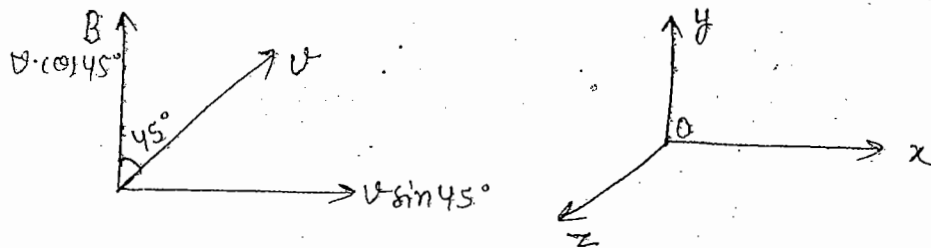
Time  $T = \frac{1}{f} \Rightarrow \boxed{T = \frac{2\pi m}{qB}}$

This time is required by a particle to complete one rotation of a circle.

Case 3:- When  $\theta \neq 90^\circ, \frac{\pi}{2}, \frac{3\pi}{2}$

Suppose angle  $\theta = 45^\circ$

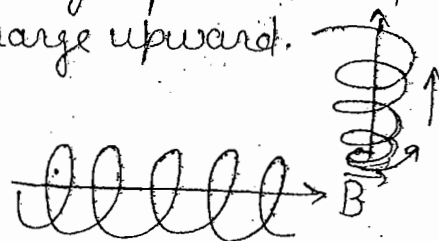
If a charge particle enter in mag. field  $\vec{B}$  so that it  $\vec{v}$  makes angle  $45^\circ$  with  $\vec{B}$ .



$v \sin \theta$  comp. will tend to rotate the charge particle and  
 $v \cos \theta$  " " " " move this charge upward.

This is called Helical Path.

$\vec{B}$  will lie along the axis of helix.



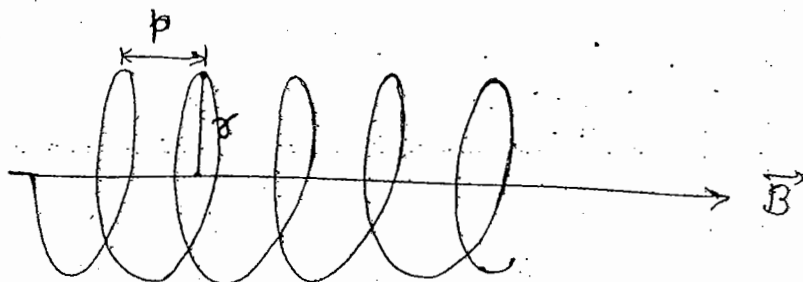
Ques 1:- An  $e^-$  enter in a uniform mag. field with magnitude  $0.3$  tesla, at an angle of  $45^\circ$  w.r to mag. field.

M.K.S. Unit of Mag. field  $\rightarrow$  Tesla  $1T = 1 \text{ weber/m}^2$

C.G.S. " " "  $\rightarrow$  Gauss

$$\boxed{1T = 10^4 G} \rightarrow \text{Relation b/w both units.}$$

Determine the radius  $r$  & pitch  $p$  of the electron's helical path. Assuming its speed is  $2 \times 10^6 \text{ m/s}$ .



$p \rightarrow$  pitch  
 $r \rightarrow$  radius

$$\theta = 45^\circ, v = 2 \times 10^6 \text{ m/sec}$$

$$v_{\perp} = v \sin 45^\circ = 2 \times 10^6 \times \frac{1}{\sqrt{2}} = \sqrt{2} \times 10^6$$

$$v_{\parallel} = v \cos 45^\circ = 2 \times 10^6 \times \frac{1}{\sqrt{2}} = \sqrt{2} \times 10^6$$

$$v_{\perp} = v_{\parallel} = \frac{\sqrt{2}}{\sqrt{2}} \times 10^6 \text{ m/sec}$$

$v_{\perp}$  is responsible for circular motion.

$v_{\parallel}$  " " " forward "

So Rotational motion is determined by  $v_{\perp}$ .  
 Translational " " "  $v_{\parallel}$ .

$$qv_{\perp} \times B = \frac{mv_{\perp}^2}{r}$$

$$\Rightarrow r = \frac{mv_{\perp}}{qB} = \frac{9.1 \times 10^{-31} \times \sqrt{2} \times 10^6}{1.6 \times 10^{-19} \times 0.3}$$

$$r = 26.81087 \times 10^6$$

$$\boxed{r = 26.8 \mu\text{m}}$$

To calculate the pitch, Ist calculate time for making a circle,

$$\Delta t = \frac{2\pi r}{v_{\perp}} \quad \left\{ \text{because circular motion } v_{\perp} \text{ is responsible} \right\}$$

Pitch  $p = v_{\parallel} \Delta t$

$$= v_{\parallel} \times \frac{2\pi r}{v_{\perp}} \quad (v_{\perp} = v_{\parallel} \text{ in this ques.})$$

$$p = 2\pi r = 2 \times 3.14 \times 26.8 = 168.304$$

$$\boxed{p = 169 \mu\text{m}}$$

Note:- • pitch of a helical path is constant in uniform magnetic field while it is not constant in Non uniform mag. field.

$$p \propto t \quad \& \quad t \propto \frac{1}{B}$$

$$\text{so } p \propto \frac{1}{B}$$

If non uniform, increase then pitch decrease.

• force will be  $F = qv_{\perp} B$ ,  $F \neq qv_{\parallel} B$

Motion of the charge particle in both Electric field & magnetic field:- We have a charge particle,  $q$  at rest.

In present case  $E \perp B$

$\vec{E}$  is along z-axis.

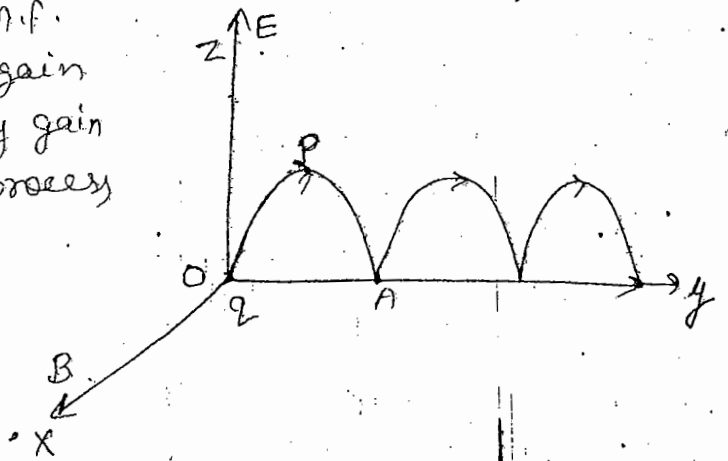
$\vec{B}$  " " X-axis.

charge is at rest placed at origin.

$\Rightarrow$  When charge particle is at rest  $\vec{E}$  will work on it & it will start motion. As  $v \uparrow$ ,  $B \uparrow$

At P, it lose its velocity so M.F. decreases & at A, vel. = 0. Again E.F. will act on it, velocity gain & process will go on, the process is repeated.

The path followed by the charged particle will be Cycloid.



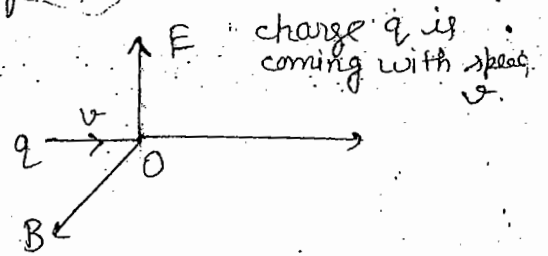
- If charge particle moving with velocity  $\vec{v}$  then electric field push the charge in upward dir<sup>n</sup>  
 Mag. " " " " downward "  
 so both are opposite.

generally strength of electric field dominant over speed.

$E \perp B$ ,  $qE = qvB$

$E = vB$

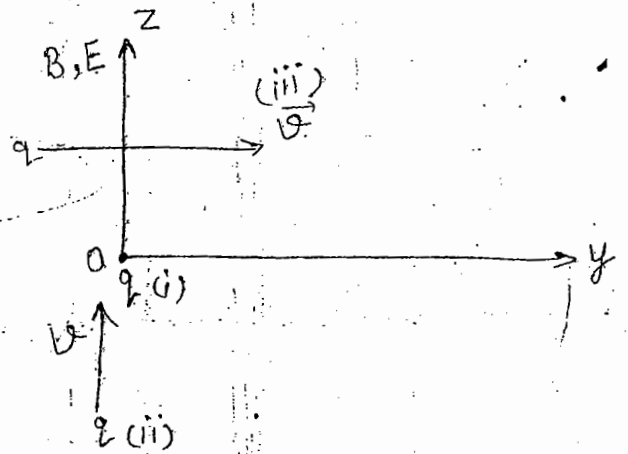
$v = \frac{E}{B}$



If strength of both  $\vec{E}$  &  $\vec{B}$  are same then it will move undeflected. i.e. in straight line.

- If E & B are parallel

- (i) If q is at rest then path will be straight line.
- (ii) If q is moving in z-dir<sup>n</sup> (|| dir<sup>n</sup>) then path is also straight line.
- (iii) If q is moving in x or y dir<sup>n</sup> ( $\perp$  dir<sup>n</sup>) then path will be spiral or helical.



$v \perp$  to  $\vec{E}$  &  $\vec{B}$ ,  $v$  along y dir<sup>n</sup> &  $\vec{E}$ ,  $\vec{B}$  along z-dir<sup>n</sup>  
 $\vec{E}$  push the charge particle in upward dir<sup>n</sup> &  $\vec{B}$  make the path helical in upward  $\hat{z}$  dir<sup>n</sup>.

## Currents 1-

Line Current:  $I = \frac{q}{t} = \lambda v$

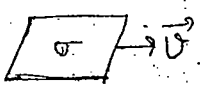
$\lambda \rightarrow$  line charge density,  $v \rightarrow$  velocity  
If any line charge  $\lambda$  moving with  $v$  velocity then current in it will be  $I = \lambda v$

Surface Current :- If a surface charge moving with then

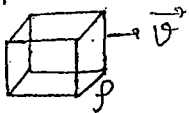
$$\vec{K} = \sigma \vec{v}$$

$\vec{K} \rightarrow$  surface current  
it is a vector quantity.

If any +ve charge particle moving with  $\vec{v}$  then the dir<sup>n</sup> of current will be in the dir<sup>n</sup> of motion of  $q$

  $\vec{K} = \sigma \vec{v} = \frac{I}{l_1}$  (current/unit length)

Volume Current :- If volume charge  $\rho$  move with  $v$  then produce vol. current.



$$\vec{J} = \rho \vec{v} = \frac{I}{a_1}$$
 (current/unit area)

## Continuous force in terms of three currents :-

$$\vec{F} = q(\vec{v} \times \vec{B})$$

$$= \int dq \left[ \frac{d\vec{l}}{dt} \times \vec{B} \right]$$

$$= \int \frac{dq}{dt} d\vec{l} \times \vec{B}$$

$$\vec{F} = I \int d\vec{l} \times \vec{B}$$

$$I = \frac{dq}{dt}$$

force on a current carrying wire,  
for a surface current,

$$\vec{F} = \int \sigma da (\vec{v} \times \vec{B})$$

$$= \int da (\sigma \vec{v} \times \vec{B})$$

$$\vec{F} = \int_s (\vec{K} \times \vec{B}) da$$



This is force on a surface element having current density  $\vec{K}$   
 Similarly for Volume,

$$\vec{F} = \int \rho d\tau (\vec{V} \times \vec{B})$$

$$\boxed{\vec{F} = \int_V (\vec{J} \times \vec{B}) d\tau}$$

This is force on a volume current.

\*  $\vec{K} = \frac{I}{a_{\perp}}$  current/unit length perpendicular to the flow of current  
 is Surface current.

\*  $\vec{J} = \frac{I}{a_{\perp}}$  current/unit area perpendicular to the flow of current  
 is Volume current.

Ques: (a) If current  $I$  is uniformly distributed over a wire of circular cross-section with radius  $a$ , find the volume current density  $\vec{J}$ .

(b) If current in the wire is proportional to the distance from the axis  $J = Kr$ . Find the total current,  $K$  is any constant.

(a)  $J = ?$

$$\vec{J} = \frac{I}{a_{\perp}} = \frac{I}{\pi a^2}$$

(Area  $\perp$  to flow of current  $a_{\perp} =$  area of circle of radius  $a$ )  
 cross section

(b)  $J = Kr$

$$I = ? \quad J = \frac{I}{a_{\perp}}$$

This current density is non-uniform so

$$\begin{aligned} I &= \int J \cdot da_{\perp} \\ &= \int_0^{2\pi} \int_0^a Kr \cdot r dr d\phi \\ &= K \left(\frac{r^3}{3}\right)_0^a 2\pi \end{aligned}$$

wire is a cylinder. so dir<sup>n</sup> of flow of current is  $z$  dir<sup>n</sup> along the length.

$$\boxed{I = \frac{2\pi Ka^3}{3}}$$

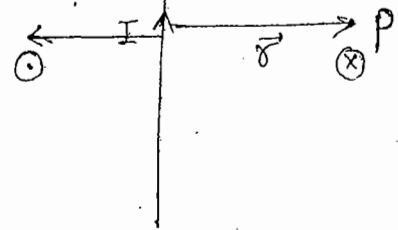
## Biot-Savart Law :-

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{I(d\vec{l} \times \vec{r})}{r^2}$$

The  $d\vec{l}$  is a vector along the dir<sup>n</sup> of current flow.

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{I(d\vec{l} \times \vec{r})}{r^3}$$

$$\text{dir}^n \text{ of } \vec{B} = d\vec{l} \times \vec{r}$$



⊗ → into the page

⊙ → out of the page

Wires are of cylindrical shape  
So dir<sup>n</sup> of current is  $\hat{z}$  &  
dir<sup>n</sup> of mag. field will be  $\hat{\phi}$ .

Mag. field curl around the wire.

If the dir<sup>n</sup> of current is  $\hat{\phi}$  then dir<sup>n</sup> of mag. field will be  $\hat{z}$ .

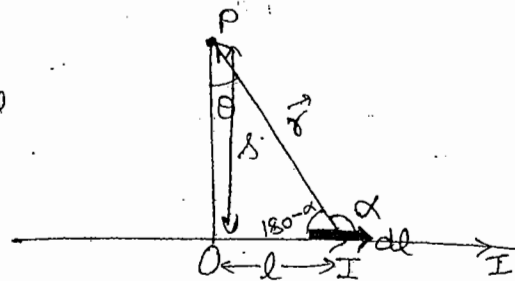
In Solenoid → Current is in  $\hat{\phi}$  & Mag. field is in  $\hat{z}$ .

## 12/8/2012 Application of Biot-Savart law :-

Q. Find the mag. field at a distance  $s$  from a straight wire carrying a steady current  $I$ .

Take an small element  $dl$ .  
dir<sup>n</sup> of element  $dl$  will be in the dir<sup>n</sup> of flow of current.

$$dB = \frac{\mu_0}{4\pi} I \frac{d\vec{l} \times \vec{r}}{r^3}$$



Complete mag. field for wire

$$B = \int dB = \frac{\mu_0}{4\pi} I \int \frac{d\vec{l} \times \vec{r}}{r^3}$$

$$= \frac{\mu_0 I}{4\pi} \int \frac{dl r \sin \alpha}{r^3}$$

$$= \frac{\mu_0 I}{4\pi} \int \frac{dl \sin \alpha}{r^2}$$

$r, \alpha \rightarrow$  unknown

$$\cos \theta = \frac{s}{r}$$

$$r = \frac{s}{\cos \theta}$$

$$90^\circ + 180^\circ - \alpha + 0 = 180^\circ \quad (\text{Total angles in } \Delta = 180^\circ)$$

$$\boxed{\alpha = 90^\circ + 0}$$

$$\therefore \sin \alpha = \sin(90^\circ + 0) = \cos 0$$

$$\begin{aligned} B &= \frac{\mu_0 I}{4\pi} \int \frac{\cos^2 \theta}{r^2} \times \cos \alpha \, dl \\ &= \frac{\mu_0 I}{4\pi} \int \frac{\cos^2 \theta}{r^2} \cos \theta \times r \sec^2 \theta \, d\theta \\ &= \frac{\mu_0 I}{4\pi r} \int_{\theta_1}^{\theta_2} \cos \theta \, d\theta \end{aligned}$$

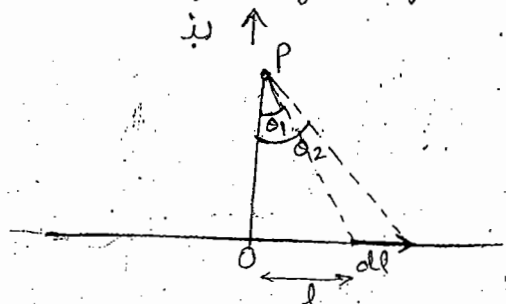
$$\begin{aligned} \tan \theta &= \frac{l}{s} \\ l &= s \tan \theta \\ dl &= s \sec^2 \theta \, d\theta \end{aligned}$$

$$\checkmark \boxed{B = \frac{\mu_0 I}{4\pi r} [\sin \theta_2 - \sin \theta_1]}$$

This is the mag. field of finite wire.

Dir<sup>n</sup> :  $\odot$  i.e.  $[\hat{\phi}]$

If length of element is  $dl$



for Infinitely long wire :-

$$\text{then } \theta_1 = -90^\circ, \theta_2 = +90^\circ$$

$$\boxed{B = \frac{\mu_0 I}{2\pi r} \hat{\phi}}$$

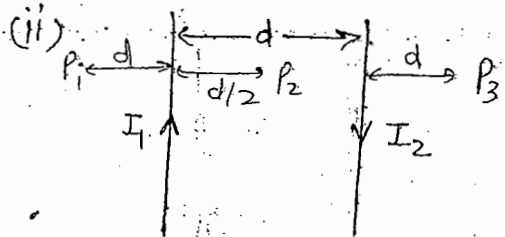
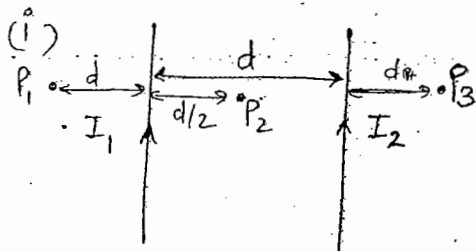
$\hat{\phi} \rightarrow$  Circumferential vector

for a infinitely long wire, we have electric field

$$\boxed{E = \frac{\lambda}{2\pi\epsilon_0 r}}$$

$$\text{Here } \mu_0 \leftrightarrow \frac{1}{\epsilon_0} \quad \& \quad I \leftrightarrow \lambda$$

Q. find the force per unit length in two parallel wire arrangement as shown in the figure.



Also find the mag. field at point  $P_1, P_2$  &  $P_3$ .

$$B = \frac{\mu_0 I}{2\pi r} \hat{\phi}$$

force on wire 2 will be due to mag. field of wire 1.

$$\vec{F}_2 = I_2 \int d\vec{l}_2 \times \vec{B}_1 \quad (\text{force on wire 2})$$

force per unit length is  $\vec{f}_2 = \vec{I}_2 \times \vec{B}_1$

$\vec{B}_1 \rightarrow$  mag. field on wire 1 at the position of 2.

$$\vec{B}_1 = \frac{\mu_0 I_1}{2\pi d} \quad (\text{into the page}) \quad \text{dir}^n \text{ of wire } \vec{B} \text{ on wire (2)} \rightarrow \otimes$$

in region of wire (1)  $\rightarrow \odot$

$$\vec{f}_2 = \frac{\mu_0 I_1 I_2}{2\pi d} \quad (\text{dir}^n \rightarrow \text{to the left})$$

force/unit length  $\propto I_1 \& I_2$   
 $\propto \frac{1}{d}$

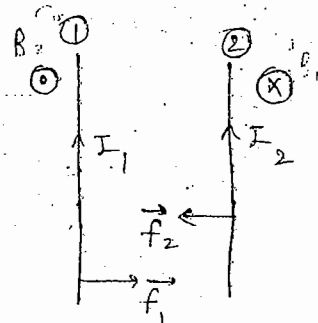
force on wire 1,

$$\vec{F}_1 = I_1 \int d\vec{l}_1 \times \vec{B}_2$$

$$\vec{f}_1 = \vec{I}_1 \times \vec{B}_2$$

$$B_2 = \frac{\mu_0 I_2}{2\pi d} \quad (\text{out of page})$$

$$\vec{f}_1 = \frac{\mu_0 I_1 I_2}{2\pi d} \quad (\text{to the right})$$

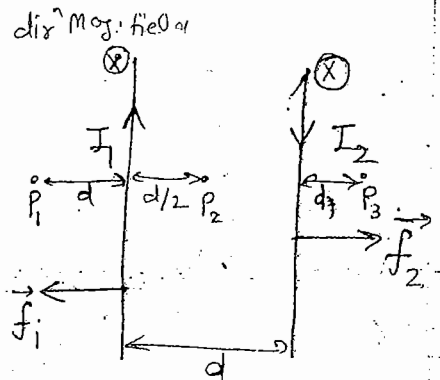


If current is in same dir<sup>n</sup> (for two wires) then force is attractive. This attraction is due to magnetic force.

Q (ii) Magnitude of force per unit length is same. Only dir<sup>n</sup> will be different.

dir<sup>n</sup> of Mag field on wire (2) due to (1) is  $\otimes$

" " " (1) " (2) "  $\otimes$



If currents are in opposite dir<sup>n</sup> the force is Repulsive

$$\vec{f}_1 = \frac{\mu_0 I_1 I_2}{2\pi d} \quad (\text{to the left})$$

$$\vec{f}_2 = \frac{\mu_0 I_1 I_2}{2\pi d} \quad (\text{to the right})$$

At  $P_1$ , Mag. field at any point is vector sum of  $\vec{B} = \vec{B}_1 + \vec{B}_2 + \dots$   
 $\vec{B}_1 \rightarrow \odot$  ,  $\vec{B}_2 \rightarrow \otimes$

$$\vec{B}_1 = \frac{\mu_0 I_1}{2\pi d} \text{ (out of the page)}$$

$$\vec{B}_2 = \frac{\mu_0 I_2}{2\pi(2d)} \text{ (into the page)}$$

Out mag. field is more than into mag. field so resultant mag. field will be in out of the page dirn.

$$\vec{B} = \vec{B}_1 + \vec{B}_2 \Rightarrow \vec{B} = \frac{\mu_0 I}{2\pi d} \left[ I_1 - \frac{I_2}{2} \right]$$

If current in 2 wires are same then

$$\vec{B}(P_1) = \frac{\mu_0 I}{4\pi d} \text{ (out of page)}$$

At  $P_2$ ,  $\vec{B}_1 \rightarrow \otimes$  ,  $\vec{B}_2 \rightarrow \otimes$

Resultant Mag. field

$$B = \frac{\mu_0}{2\pi} \left[ \frac{1}{d/2} (I_1 + I_2) \right]$$

$$B = \frac{\mu_0}{2\pi} \frac{2}{d} (I_1 + I_1)$$

If  $I_1 = I_2 = I$  then

$$B(P_2) = \frac{2\mu_0 I}{\pi d} \text{ (into the page)}$$

At  $P_3$ ,  $B_1 \rightarrow \otimes$  ,  $B_2 \rightarrow \odot$

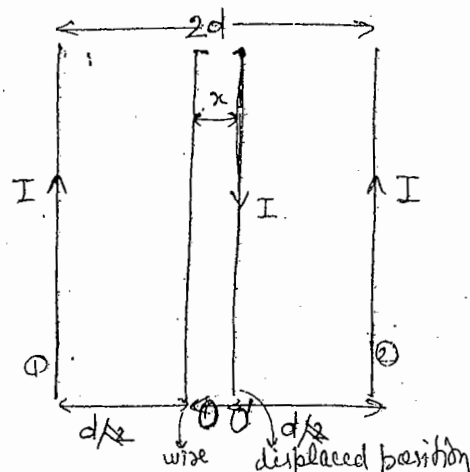
$$B_1 = \frac{\mu_0 I_1}{2\pi(2d)} , B_2 = \frac{\mu_0 I_2}{2\pi(d)}$$

$$B(P_3) = \frac{\mu_0}{2\pi d} \left[ -\frac{I_1}{2} + I_2 \right]$$

$I_1 = I_2 = I$

$$B(P_3) = \frac{\mu_0}{4\pi d} \text{ (out of page)}$$

Q. We have a 3 wire arrangement. Current in each wire is  $I$ . Mass per unit length of the middle wire is  $m$ . Earlier it was placed at mid point. Now it is displaced by  $x$ . Calculate its freq. of oscillation.



$$F \propto x$$

Here, force/unit length  $\propto$   
 $f \propto x$

If wire is placed at mid point then resultant force is zero.

But when it is displaced then force will be non-zero.

At present position,

$$\vec{B}_1 = \frac{\mu_0 I_1}{2\pi(d+x)} \quad , \quad \vec{B}_2 = \frac{\mu_0 I_2}{2\pi(d-x)} \quad (\text{out of page})$$

(into the page)

$\left\{ \begin{array}{l} B_1 \text{ is field at } \textcircled{1} \text{ due to wire } \textcircled{2} \\ B_2 \text{ " " " " " " " " } \end{array} \right.$

Resultant Mag. field,  $\vec{B} = \vec{B}_1 + \vec{B}_2$

$$B = \frac{\mu_0 I}{2\pi} \left[ \frac{1}{(d-x)} - \frac{1}{(d+x)} \right] \quad (\text{out of page})$$

$$B = \frac{\mu_0 I}{2\pi} \left[ \frac{d+x-d-x}{d^2-x^2} \right]$$

Here  $x^2$  is very small. This wire will perform simple harmonic motion (if  $x$  is not small then wire will not perform S.H.M.)  
 so neglect  $x^2$

$$B = \frac{\mu_0 I x}{\pi d^2} \quad (\text{out of page})$$

After displacement the motion of wire will be simple harmonic as it starts to oscillate.

force/unit length  $f = I \times B$

$$f = \frac{\mu_0 I^2 x}{\pi d^2}$$

$$f \propto x \quad \text{i.e. S.H.M.}$$

$$F = m \frac{d^2x}{dt^2} \quad \& \quad f = \frac{m}{l} \frac{d^2x}{dt^2}$$

Here mass per unit length is  $m$ . & @

$$f = m \frac{d^2x}{dt^2}$$

$$f = Kx$$

$$\frac{\mu_0 I^2 x}{\pi d^2} = Kx \Rightarrow K = \frac{\mu_0 I^2}{\pi d^2}$$

Both  $f$  &  $K$  are force per unit length  
 So freq. of Oscillation,  $\omega = \sqrt{\frac{K}{m}}$

$$\omega = \sqrt{\frac{\mu_0 I^2}{\pi d^2 m}}$$

$$\omega = \frac{I}{d} \sqrt{\frac{\mu_0}{\pi m}}$$

$$\text{Linear frequency} = \frac{\omega}{2\pi} = \frac{I}{2\pi d} \sqrt{\frac{\mu_0}{\pi m}}$$

$$\text{Time} = \frac{1}{\text{freq.}} \Rightarrow T = \frac{2\pi d}{I} \sqrt{\frac{\mu_0}{\pi m}}$$

Q. A Mag. field in some region is given by  $\vec{B} = kz \hat{x}$  where  $k$  is constant. Find the force on a square loop of sides  $a$  lying in the  $y$ - $z$  plane & centered at the origin if it carries a current  $I$  in the counter clockwise dir<sup>n</sup> when you look down the  $x$ -axis.

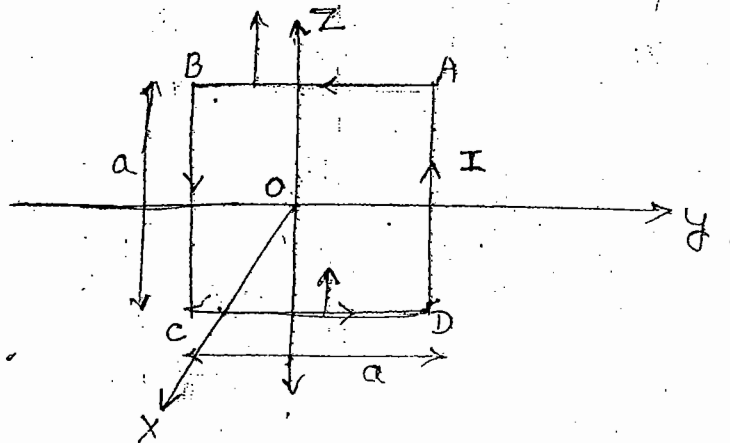
$$F = \int I d\vec{l} \times \vec{B}$$

$$= I \int d\vec{l} \times \vec{B}$$

for AB wire, Mag. field

$$B = \frac{ka}{2} \hat{x}$$

$$\vec{F}_{AB} = \frac{Ika^2}{2} \hat{z} \quad (\hat{y} \times \hat{x} = \hat{z})$$



On wire CD, Mag. field  $B = \frac{\mu_0 I a}{2} (-\hat{x})$

$$\vec{F}_{CD} = \frac{I \mu_0 I a^2}{2} \hat{z}$$

On AD upper half, Dir<sup>n</sup> of  $\vec{B} \rightarrow \hat{x}$

On BC " " " "  $\rightarrow \hat{x}$

On AD lower half Dir<sup>n</sup> of  $\vec{B} \rightarrow -\hat{x}$

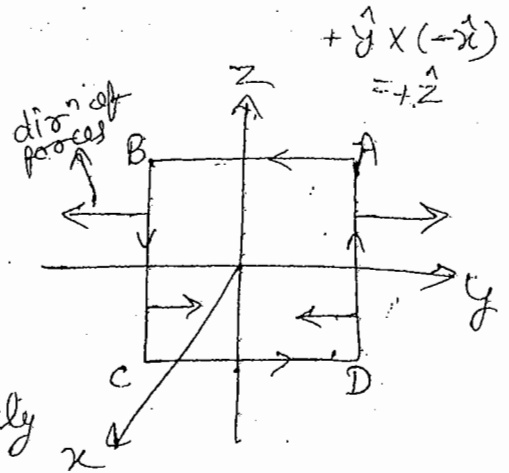
BC " " " "  $\rightarrow -\hat{x}$

forces on AD & BC are oppositely directed so

$$\vec{F}_{AD} = \vec{F}_{BC} = 0$$

[Dir<sup>n</sup> of mag. field is opposite, +z or -z]

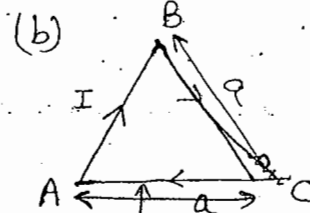
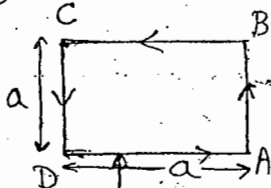
Resultant force  $\vec{F} = \left( \frac{I \mu_0 I a^2}{2} + \frac{I \mu_0 I a^2}{2} \right) \hat{z} \Rightarrow \boxed{\vec{F} = I \mu_0 I a^2 \hat{z}}$



If  $\vec{B} = k \hat{x}$  then Resultant  $F = 0$

Beoz dir<sup>n</sup> of of mag. field on upper & lower part is same here & in previous case it is different.

Q. 1-



due to this wire, there will be field on each wire of loop

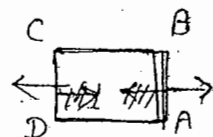
(a) Find the force on a square loop placed near an infinite straight wire. Both carries current I as shown in figure

(b) find the force on a equilateral triangle loop placed near infinite straight wire. Both carry current I.

(a) Dir<sup>n</sup> of  $\vec{B}$  to AB =  $\odot$

CD =  $\odot$

$$F_{AB} = F_{CD} = 0$$



$$\vec{F} = I \int d\vec{l} \times \vec{B}$$



$$F = I \int dl \times B$$

$$F_{DA} = I \frac{\mu_0 I a}{2\pi a}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi a}$$

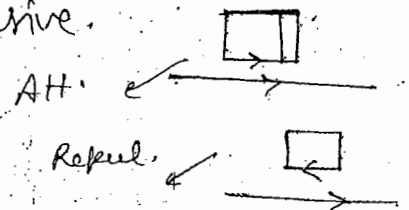
$$F_{DA} = \frac{\mu_0 I^2}{2\pi} \text{ (downward)}$$

$$F_{BA} = \frac{\mu_0 I^2 a}{2\pi(2a)} \Rightarrow F_{BA} = \frac{\mu_0 I^2}{4\pi} \text{ (upward)}$$

$$\text{Resultant force } \boxed{F = \frac{\mu_0 I^2}{4\pi}} \text{ (downward)}$$

If current in DA wire & below wire is same then attractive and if opposite the repulsive.

So this force is Attractive.



Q. (ii) Now wires are not parallel & perpendicular.

This loop is in x-y plane.

$$d\vec{l}_{AB} = dx \hat{x} + dy \hat{y}$$

$$d\vec{l}_{BC} = dx \hat{x} - dy \hat{y}$$

$$d\vec{l}_{CA} = -dx \hat{x}$$

$$d\vec{l} = d\vec{l}_{AB} + d\vec{l}_{BC} = 2dx \hat{x}$$

$$\text{Mag. field for part ABC, } \vec{B} = \frac{\mu_0 I}{2\pi y} \hat{z}$$

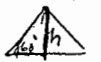
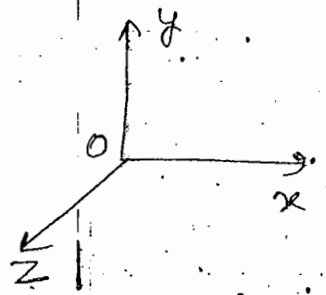
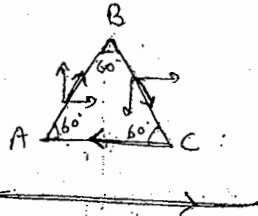
$$d\vec{F}_{ABC} = I (d\vec{l} \times \vec{B})$$

$$d\vec{F}_{ABC} = \frac{\mu_0 I^2}{2\pi y} 2dx (-\hat{y})$$

$$\text{Total force } \vec{F}_{ABC} = \int d\vec{F}_{ABC} = \frac{\mu_0 I^2}{\pi} \int \frac{dx}{y} (-\hat{y})$$

$$\tan \theta = \frac{y}{x} \Rightarrow \tan 60^\circ = \frac{y}{x} \Rightarrow \sqrt{3} = \frac{y}{x} \Rightarrow y = \sqrt{3}x$$

Convert y into x becoz in integration y is variable & integration is over x.



$$\begin{aligned} \sin 60^\circ &= \frac{h}{a} \\ \frac{\sqrt{3}}{2} &= \frac{h}{a} \\ \left\{ h &= \frac{\sqrt{3}}{2} a \right. \end{aligned}$$

$$\begin{aligned} \vec{F}_{ABC} &= \frac{\mu_0 I^2}{\pi} \int_{\frac{a}{\sqrt{3}}}^{\frac{a}{\sqrt{3}} + \frac{1}{2}} \frac{dx (-\hat{y})}{\sqrt{3} x} \\ &= \frac{\mu_0 I^2}{\pi \sqrt{3}} \int_{\frac{a}{\sqrt{3}}}^{\frac{a}{\sqrt{3}} + \frac{1}{2}} \frac{dx}{x} (-\hat{y}) \\ &= \frac{\mu_0 I^2}{\pi \sqrt{3}} \ln \left( \frac{\frac{a}{\sqrt{3}} + \frac{1}{2}}{\frac{a}{\sqrt{3}}} \right) (-\hat{y}) \end{aligned}$$

$$\vec{F}_{ABC} = \frac{\mu_0 I^2}{\pi \sqrt{3}} \ln \left( 1 + \frac{\sqrt{3}}{2} \right) (-\hat{y})$$

from going A → B → C  
x changes by a distance, a

y changes distance  $\frac{a}{2}$   
if we connect in y

As  $y = \sqrt{3}x \Rightarrow x = \frac{y}{\sqrt{3}}$   
when  $y = a$ ,  $x = \frac{a}{\sqrt{3}}$   
 $y = a + \frac{\sqrt{3}a}{2}$ ,  $x = \frac{(a + \frac{\sqrt{3}a}{2})}{\sqrt{3}}$

for CA wise,  $\vec{B} = \frac{\mu_0 I}{2\pi y} \hat{z}$  (out of the page)

So force  $\vec{F}_{CA} = \frac{\mu_0 I^2}{2\pi} (\hat{y}) \approx 0.15$

$\frac{\mu_0 I}{2\pi a}$   
If  $d\vec{l} \times \vec{B}$   
 $\frac{\mu_0 I^2 a}{2\pi}$

$\vec{F}_{CA}$  is greater than  $\vec{F}_{ABC}$  so Resultant force is in  $\hat{y}$  dir<sup>n</sup>. This force will be Repulsive.

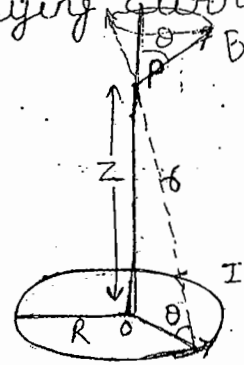
Q. Find the magnetic field at a distance z above the centre of a circular loop of radius R carrying current I.

We Use Biot-Savart law.

Take a small element  $d\vec{l}$ .

dir<sup>n</sup> of Mag. field  $\rightarrow d\vec{l} \times \vec{r}$

Inclination of  $\vec{r}$  w.r to this plane is  $\theta$ .

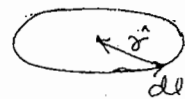


Here  $\vec{r}$  is not in this plane while it is tilted by an angle  $\theta$

so mag. field will also tilt by an angle  $\theta$ .

ie.  $\vec{r}$  tilt from horizontal =  $\vec{B}$  tilt from vertical

{ if we have to find  $\vec{B}$  at centre then  $\vec{r}$  will be  $\hat{z}$  & dir<sup>n</sup> of  $\vec{B}$  will be  $\hat{z}$  }



If we break the components of B then

sin $\theta$  comp. will cancel out coz sin $\theta$  comp. is rotating



only cos $\theta$  is responsible for  $\vec{B}$ .

cos $\theta$  comp. adds up so it is along upward dir<sup>n</sup>

So Net Mag. field will be in  $z$ -dir<sup>n</sup>.

$$B_z = B \cos \theta$$

$$B = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times \vec{r}}{r^3} = \frac{\mu_0 I}{4\pi} \int \frac{dl \cdot r \sin \theta}{r^3}$$

$$B = \frac{\mu_0 I}{4\pi} \int \frac{dl}{r^2} \quad \left\{ \begin{array}{l} \theta = 90^\circ \\ \vec{r} \text{ makes angle with horizontal natu} \\ dl \cdot \text{It is } 90^\circ \end{array} \right.$$

$$\cos \theta = \frac{R}{r} = \frac{R}{(R^2 + z^2)^{1/2}}$$

$$\begin{aligned} B_z &= \frac{\mu_0 I}{4\pi} \int \frac{dl}{(R^2 + z^2)^{1/2}} \cdot \frac{R}{(R^2 + z^2)^{1/2}} = \frac{\mu_0 I R}{4\pi} \int \frac{dl}{(R^2 + z^2)^{3/2}} \\ &= \frac{\mu_0 I R \times 2\pi R}{4\pi (R^2 + z^2)^{3/2}} \end{aligned}$$

$$B_z = \frac{\mu_0 I R^2}{2 (R^2 + z^2)^{3/2}} \quad \checkmark$$

Limiting Cases :-

(1) At the centre of the loop :-  $z = 0$

$$B_{\text{centre}} = \frac{\mu_0 I}{2R}$$

(2)  $z \gg R$  very far from the loop :- neglect  $R^2$  bcoz  $z$  is very large

$$B_z = \frac{\mu_0 I R^2}{2z^3} \times \frac{2\pi}{2\pi}$$

$$B_z = \frac{\mu_0 I 2\pi R^2}{4\pi z^3}$$

At far distances, Mag. field  $\propto \frac{1}{z^3}$   $z \rightarrow$  distance

(3) If loop contains  $N$  turns :-

$$B_z = N B_z$$

$$B_z = \frac{N \mu_0 I R^2}{2 (R^2 + z^2)^{3/2}}$$

(bcoz current will become  $N$  times)

Find the value of  $z$  at which mag. field is maximum.

$$\frac{dB}{dz} = 0$$

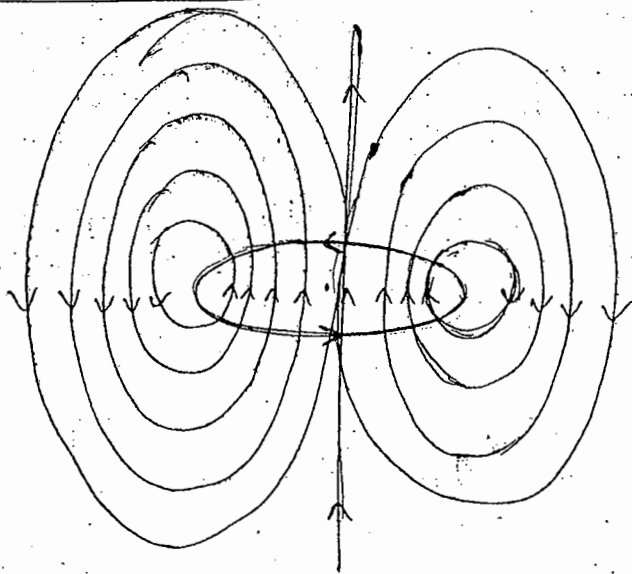
$$\frac{\mu_0 I R^2}{2} \cdot \frac{-3z}{(R^2 + z^2)^{5/2}} = 0$$

$$\Rightarrow z = 0$$

i.e. At the centre Mag field will be maximum

$$\text{Maxi. field } B = \frac{\mu_0 I R^2}{2 R^3} \Rightarrow \boxed{B_{\max} = \frac{\mu_0 I}{2 R}}$$

Magnetic field lines



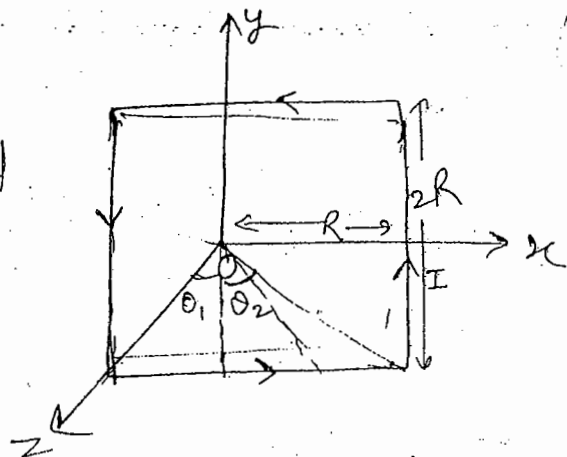
Q.(a) Find the magnetic field at the centre of a square loop which carries steady current  $I$ .  $R$  be the distance from centre to sides.

(b) Find the field at the centre of a  $N$  side polygon carrying a steady current  $I$ ,

for all the wires dir<sup>n</sup> of  $B$  is outside.

It is additive so Mag field at centre will be 4 times of Mag. field due to one wire, Mag. field for a finite wire

$$B = \frac{\mu_0 I}{4\pi R} [\sin\theta_2 + \sin\theta_1]$$



for lower wire,

$$B = \frac{\mu_0 I}{4\pi R} [\sin 45^\circ - (-\sin 45^\circ)]$$
$$= \frac{\mu_0 I}{4\pi R} 2 \sin 45^\circ = \frac{\mu_0 I}{4\pi R} 2 \times \frac{1}{\sqrt{2}}$$

$$\vec{B} = \frac{\mu_0 I \sqrt{2}}{4\pi R} \hat{z}$$

for all the sides i.e. for square loop

$B = 4$  times of ( $B$  for one wire)

$$\vec{B} = \frac{\sqrt{2} \mu_0 I}{\pi R} \hat{z}$$

(b) general formula

Mag. field for  $n$ -side polygon is

$$B = \frac{n \mu_0 I \sin\left(\frac{\pi}{n}\right)}{2\pi R}$$

$I \rightarrow$  Current

$n \rightarrow$  sides

$R \rightarrow$   $\perp$  distance from the mid point of wire

Now check it for Square loop

$$B = \frac{4 \mu_0 I \sin\left(\frac{\pi}{4}\right)}{2\pi R} = \frac{2 \mu_0 I}{\pi R} \frac{1}{\sqrt{2}}$$

$$\vec{B} = \frac{\sqrt{2} \mu_0 I}{\pi R} \hat{z}$$

Circle is  $\infty$  sides polygon &  $n \rightarrow \infty$

$$B = \frac{n \mu_0 I \cdot \frac{\pi}{n}}{2\pi R} \quad \theta \rightarrow 0 \quad \text{when } \theta = 0, \sin \theta \approx \theta$$

$$B = \frac{\mu_0 I}{2R}$$

\* We can not apply this formula for rectangle. This is valid only for regular polygon, & rectangle is not a regular polygon.

Q. Find the mag. field at the centre of a regular hexagon as shown in figure.

It is placed in y-z plane.

~~for square loop n=4~~

Mag. field for n side polygon

$$B = \frac{n \mu_0 I}{2 \pi R} \sin\left(\frac{\pi}{n}\right)$$

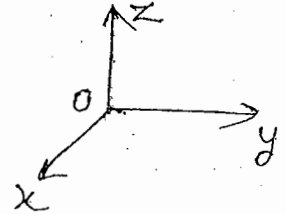
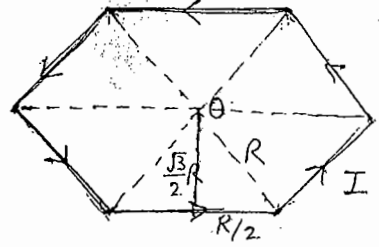
n = 6 for Hexagon

$$B = \frac{6 \mu_0 I}{2 \pi \left(\frac{\sqrt{3}}{2} R\right)} \sin \frac{\pi}{6} = \frac{23 \mu_0 I}{\sqrt{3} \pi R} \frac{1}{2}$$

$$B = \frac{\sqrt{3} \mu_0 I}{\pi R} (+\hat{z})$$

Mag. field due to all the wires is outward so dir<sup>n</sup> = + $\hat{z}$

$$\text{so } \boxed{B = \frac{\sqrt{3} \mu_0 I}{\pi R} (+\hat{z})}$$



~~Rad~~  
 distance R in the formula is the  $\perp$  distance from centre to wire

Q. A Current I flows down a wire of radius a.

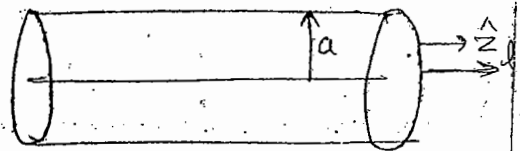
(a) If it is uniformly distributed over the surface. What is surface current density  $\epsilon K$ .

(b) If it is distributed in such a way that the volume current density is inversely proportional to the distance from the axis then find J.  $[K = \sigma \hat{z}]$

$$(a) K = \frac{I}{l_{\perp}}$$

$\frac{1}{2}$  length  $\perp$  to the flow of current =  $2\pi a$  (circumference of cross section of radius a)

$$\boxed{K = \frac{I}{2\pi a} \hat{z}}$$



$$(b) J \propto \frac{1}{s}$$

$$J = \frac{K}{s}$$

(distance from axis  $\rightarrow s$   
 vector away from axis  $\rightarrow \hat{s}$ )

$$\int \vec{J} \cdot d\vec{S}_\perp = I$$

$$\int_0^a \int_0^{2\pi} \frac{K}{s} \cdot s ds d\phi \hat{z} = I$$

$$\int_0^a \int_0^{2\pi} K ds d\phi = I$$

$$K (s^2)_0^a (2\pi) = I \Rightarrow I = 2\pi K a$$

$$K = \frac{I}{2\pi a}$$

$$\vec{K} = \frac{I}{2\pi a} \hat{z}$$

$$\text{So } \boxed{J = \frac{I}{2\pi a s} \hat{z}} \quad \underline{\underline{A_0}}$$

area element  $\Rightarrow$

$$d\vec{S}_\perp = s ds d\phi \hat{z}$$

Ques:- If phonograph records carries a uniform density of static electricity is  $\sigma$ , if it rotates at angular velocity  $\omega$ . What is the current density  $K$  at a distance  $r$  from the centre.

dir<sup>n</sup> of  $\omega \rightarrow \hat{z}$

Curl the fingers in the dir<sup>n</sup> of rotation.

Surface density,

$$\vec{K} = \sigma \vec{v} \quad \text{--- (1)}$$

dir<sup>n</sup> of  $\vec{K}$  will be same as of  $\vec{v}$ .

$$\vec{v} = \vec{\omega} \times \vec{r}$$

$$= \omega r [\hat{z} \times \hat{r}]$$

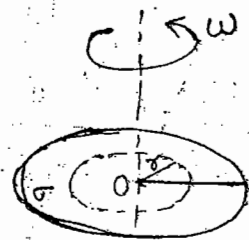
$\vec{v}$  will be tangential but  $\omega$  will be  $\perp$  to the plane

$$\boxed{\vec{v} = \omega r \hat{\phi}}$$

$$\theta = 90^\circ$$

{ In We write  $\vec{r}$  in cartesian then

$$\vec{z} \times \vec{r} = \sin\theta \hat{\phi} \text{ if } \theta = 90^\circ \text{ so } \hat{\phi}$$



$$(\vec{r} = r \hat{r})$$

dir<sup>n</sup> of  $\vec{v}$  will be  $\hat{\phi}$ .



$$\vec{K} = \sigma \vec{v}$$

$$\Rightarrow \boxed{\vec{K} = \sigma \omega r \hat{\phi}}$$

If  $R$  is the radius then current  $I = ?$

$$K = \frac{I}{L}$$

dir<sup>n</sup>  $\perp$  to the flow of current  $\rightarrow \hat{\phi}$   
element =  $dr$



Total current  $I = \int K dl$   
 $I = \int_0^R \sigma \omega r dr$

$$\boxed{I = \frac{\sigma \omega R^2}{2}}$$

Q.3 A uniformly charged solid sphere of radius  $R$  & total charge  $Q$  is centred at the origin & spinning at a constant angular velocity  $\omega$  about  $z$ -axis. Find the current density  $\vec{J}$  at  $r, \theta, \phi$  within the sphere.

$\vec{J}$  at  $r, \theta, \phi$ .

$$\vec{J} = \rho \vec{v}$$

$$\rho = \frac{Q}{V} = \frac{Q}{\frac{4}{3}\pi R^3}$$

As the sphere is uniformly charged otherwise we can not write like this.

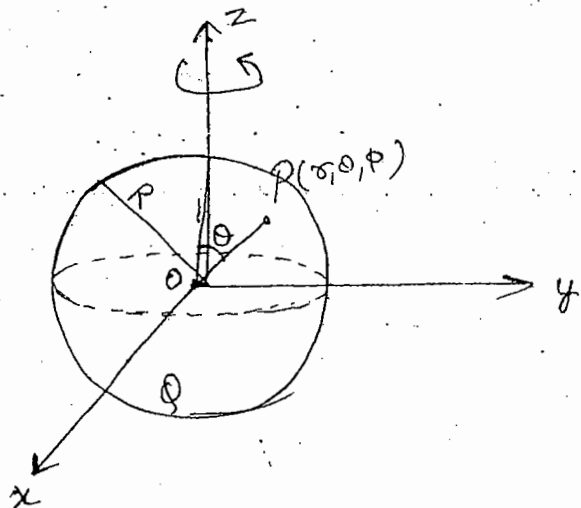
dir<sup>n</sup> of  $\omega \rightarrow \hat{z}$

$$\vec{\omega} = \omega \hat{z}$$

$$\begin{aligned} \vec{v} &= \vec{\omega} \times \vec{r} \\ &= \omega r (\hat{z} \times \hat{r}) \\ &= \omega r \sin\theta \hat{\phi} \end{aligned}$$

$$\vec{J} = \rho \omega r \sin\theta \hat{\phi}$$

$$\vec{J} = \frac{Q}{\frac{4}{3}\pi R^3} \omega r \sin\theta \hat{\phi}$$



$$\begin{aligned} \hat{z} \times \hat{r} &= (\cos\theta \hat{r} - \sin\theta \hat{\theta}) \times \hat{r} \\ &= -\sin\theta (\hat{\theta} \times \hat{r}) \\ &= \sin\theta \hat{\phi} \end{aligned}$$



Total Current = ?

$$I = \int \vec{J} \cdot d\vec{S}$$

$$dS_{\phi} = r d\sigma d\phi$$

$$I = \int_0^R \int_0^{\pi} \rho \omega r \sin\theta r d\sigma d\phi$$

$$I = \rho \omega \frac{R^3}{3} (\cos\theta)_0^{\pi} = \frac{\rho \omega R^3}{3} (1+1)$$

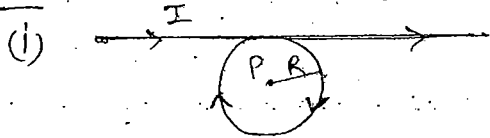
$$I = \frac{2}{3} \omega \rho R^3$$

$$I = \frac{2}{3} \omega R^3 \frac{Q}{\frac{4}{3}\pi R^3} = \frac{Q \omega}{2\pi}$$

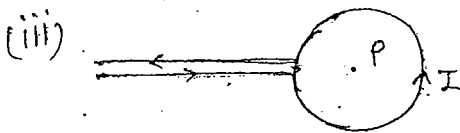
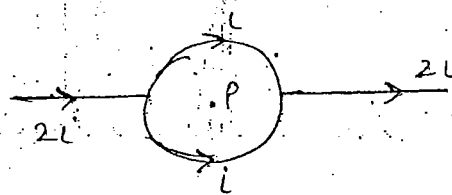
$$I = \frac{Q \omega}{2\pi}$$

This total current is due to volume charge density. There may be some current at surface also but there is not given  $\sigma$  &  $A$ . If given then Total current will be due to surface current density + vol. current density.

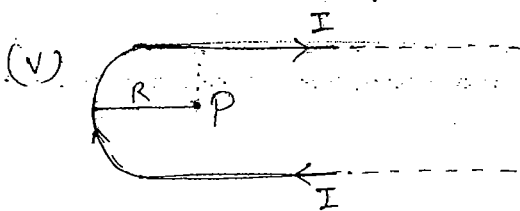
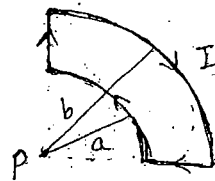
Q. Find the mag. field at point P.



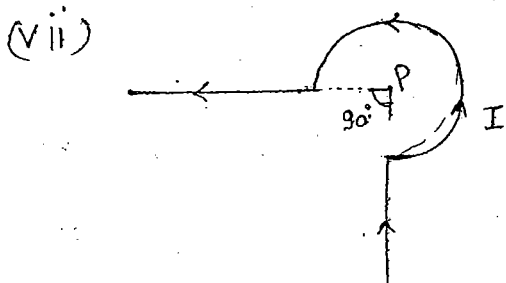
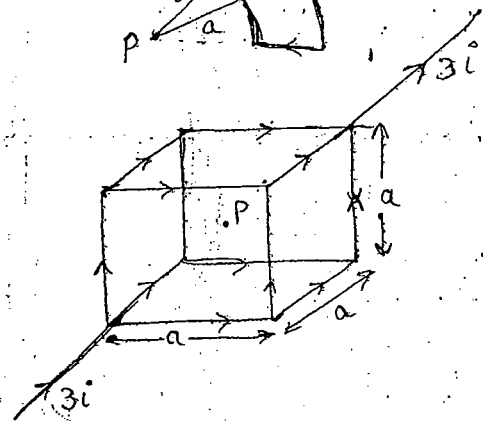
(ii)



(iv)



(vi)



(i) Mag. field of circular loop =  $\frac{\mu_0 I}{2R}$  (inward)  
 In the wire,  $\vec{B} = \frac{\mu_0 I}{2\pi R}$  (inward) (bcz of circle)

$$\text{Total Mag. field} = \frac{\mu_0 I}{2R} + \frac{\mu_0 I}{2\pi R}$$

$$\boxed{B_p = \frac{\mu_0 I}{2R} \left(1 + \frac{1}{\pi}\right)}$$

Due to  $\perp$  bend in wire, Mag. field  $\uparrow$  Otherwise in straight wire it is  $\mu_0 I / 2\pi R$ .

(ii) Due to lower half =  $\frac{\mu_0 I}{4R}$  out of page  
 upper " =  $\frac{\mu_0 I}{4R}$  into the page

$$\text{for Half Circle } \vec{B} = \frac{1}{2} \left( \frac{\mu_0 I}{2R} \right)$$

$$\text{Total } \vec{B} \text{ at } P = \frac{\mu_0 I}{4R} - \frac{\mu_0 I}{4R}$$

$$\boxed{B = 0}$$

Due to the wires no contribution. So Total  $B = 0$   
 ( $B = \frac{\mu_0}{4\pi} I \int \frac{d\vec{l} \times \vec{r}}{r^3}$ )  $\angle$  b/w  $d\vec{l}$  &  $\vec{r} = 0$

(iii) Dir<sup>n</sup> of  $\vec{B}$  = outward (for circle)

$$\vec{B} = \frac{\mu_0 I}{2R}$$

Due to wire  $\Rightarrow B = 0$

$$\text{Total } \boxed{B = \frac{\mu_0 I}{2R}}$$

(iv)  $\frac{1}{4}$ th part of circle

for a radius part  $B = \frac{1}{4} \frac{\mu_0 I}{2a} = \frac{\mu_0 I}{8a}$  (out of page)

" b "  $B = \frac{\mu_0 I}{8b}$  (into " )

Contribution of  $B$  is only due to curved path.  
 due to other 2 path  $B = 0$  ( $\angle$  b/w  $\vec{r}$  & surface = 0)

$$\text{Total } \boxed{B = \frac{\mu_0 I}{8} \left[ \frac{1}{a} - \frac{1}{b} \right]} \text{ (out of page)}$$

(v) It is a combination of half circle & 2 semi  $\infty$  wires.

Due to all 3 paths dir<sup>n</sup> of  $\vec{B}$  is into the page.

$$\theta_2 = 90^\circ$$

$$\theta_1 = 0$$

for lower wire,

$$B = \frac{\mu_0 I}{4\pi R} [\sin\theta_2 - \sin\theta_1]$$

$$= \frac{\mu_0 I}{4\pi R}$$

for upper half  $\infty$  wire,

$$B = \frac{\mu_0 I}{4\pi R}$$

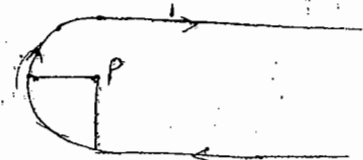
$$\text{So Total } B \text{ due to both wires} = \frac{\mu_0 I}{4\pi R} + \frac{\mu_0 I}{4\pi R} = \frac{\mu_0 I}{2\pi R}$$

$$\text{Due to curved wire } \vec{B} = \frac{\mu_0 I}{4R}$$

$$\text{So Total Mag. field at } P, B = \frac{\mu_0 I}{4R} + \frac{\mu_0 I}{2\pi R}$$

$$B = \frac{\mu_0 I}{2R} \left[ \frac{1}{2} + \frac{1}{\pi} \right]$$

Mag. field Depends on the shape of wire

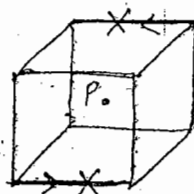


point P is from mid point of wire

(vi) Same Current flow in all the wires of same type as the resistance of wires are same.

So Mag. field = 0

(In these 2 surfaces B is same, distance from P is same, only dir<sup>n</sup> of B is different so they cancel out.)



for Diagonally opposite sides,  $\vec{B}$  have opposite dir<sup>n</sup> so B will cancel out.

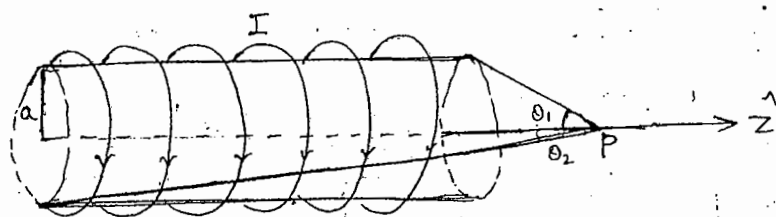
$$\text{So } \boxed{\text{Total } B = 0}$$

(vii) Circular path  $\rightarrow \frac{3}{4}$  circle

$$B = \frac{3}{4} \times \frac{\mu_0 I}{2R} \Rightarrow B = \frac{3\mu_0 I}{8R} \text{ (out of page)}$$

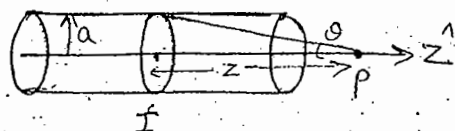
Due to wires  $\Rightarrow B = 0$

Q. Find the mag. field at a point on the axis of a tightly wound solenoid consisting of a small  $n$  turns/unit length  $l$  carrying current  $I$ . Express your answer in terms of  $\theta_1$  &  $\theta_2$  (finite Solenoid).



The mag-field of a single circle is

$$B = \frac{\mu_0 I a^2}{2(a^2 + z^2)^{3/2}}$$



There are many circles bounded tightly by with each other.

Total no. of turns =  $n$ , length  $dz$ .

• total no. of turns in length  $dz = n dz$

• Total current in this thickness =  $I n dz$

from Biot-Savart law,

$$dB = \frac{\mu_0 I}{4\pi} \int \frac{dl \times \vec{r}}{r^3}$$

$$dB = \frac{\mu_0 I n dz}{4\pi}$$

$$dB = \frac{\mu_0 I^2 n dz}{2(a^2 + z^2)^{3/2}}$$

$$\text{dir}^n \text{ of } B \rightarrow \hat{z}$$

$$B = \int dB$$

$$= \frac{\mu_0 a^2 n I}{2} \int \frac{dz}{(a^2 + z^2)^{3/2}}$$

$$= \frac{\mu_0 a^2 n I}{2} \int \frac{-a \operatorname{cosec}^2 \theta d\theta}{a^3 (1 + \cot^2 \theta)^{3/2}}$$

$$= \frac{\mu_0 a^2 n I}{2} \int \frac{-a \operatorname{cosec}^2 \theta d\theta}{a^3 \operatorname{cosec}^3 \theta}$$

$$= \frac{\mu_0 n I}{2} \int_{\theta_1}^{\theta_2} -\sin \theta d\theta$$

$$\text{Rel}^n \text{ b/w } \theta \text{ \& } z$$

$$\tan \theta = \frac{a}{z}$$

$$z = a \cot \theta$$

$$dz = -a \operatorname{cosec}^2 \theta d\theta$$

As  $dz \uparrow$ , there will be two ends.  $\theta$  limits from  $\theta_1$  to  $\theta_2$

$$B = \frac{\mu_0 n I}{2} \left[ \cos \theta_2 \right]_{\theta_1}^{\theta_2}$$

$$B = \frac{\mu_0 n I}{2} \left[ \cos \theta_2 - \cos \theta_1 \right] \hat{z}$$

Limiting Case :-

(i) Mag. field of a infinite solenoid :-

$$\theta_1 = 180^\circ$$

$$\theta_2 = 0^\circ$$

$$\vec{B} = \mu_0 n I \hat{z}$$

Mag. field inside the solenoid is constant.

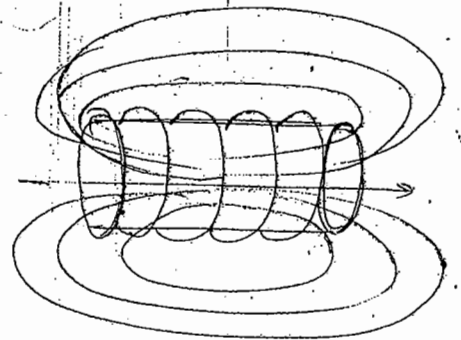
{ for a finite solenoid, mag. field inside the solenoid is still  $\vec{B} = \mu_0 n I \hat{z}$

(ii) Outside the solenoid :-

$$B_{out} = 0$$

Practically  $B$  at pt. P is not zero but very weak. so theoretically we assume it is zero.

Beoz mag. field lines of upper & lower are opposite.



for a short solenoid,  $\theta_1 = \theta_2$  so  $B = 0$ .

(iii) At End point :-  $\theta_2 = 0^\circ$ ;  $\theta_1 = 90^\circ$

$$B_{end} = \frac{\mu_0 n I}{2}$$

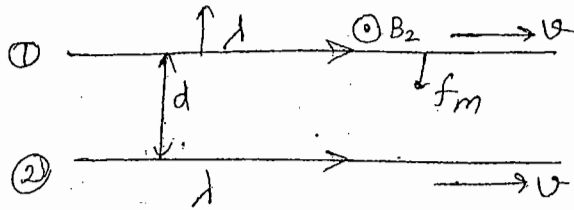
Mag field at the end of solenoid is half of the field inside the solenoid.

• Dir<sup>n</sup> of wire & solenoid are interchangeable.

dir<sup>n</sup> of  $m \cdot f.$   $\rightarrow \hat{z}$  } solenoid  
 current  $\rightarrow \hat{\phi}$

$I \rightarrow \hat{z}$  } wire  
 $m \cdot f. \rightarrow \hat{\phi}$

Q. Suppose 2  $\infty$  line charges  $\lambda$  a distance  $d$  apart moving at a constant speed  $v$ . Calculate the value of  $v$  (speed) in order for mag. attraction to balance electrical repulsion.



If  $\lambda$  &  $\lambda$  are +ve charges, there must be the electrical repulsion.  
 But current is flowing in same dir<sup>n</sup> (current will be in same dir<sup>n</sup> as  $v$ ) so there will be mag. attraction.

Electric force  $\vec{F}_e = q \vec{E}$

wires are  $\infty$  line charges. So force per unit length

$$f_e = \lambda E$$

force/unit length for wire (1)  $f_{e1} = \lambda_1 E_2$

$$f_{e1} = \frac{\lambda_1 \lambda}{2\pi\epsilon_0 d} = \frac{\lambda^2}{2\pi\epsilon_0 d} \quad \text{(upward)} \quad \text{--- (1)}$$

same force will be on wire (2) but in opposite dir<sup>n</sup> but we are interested only in magnitude.

Magnetic force  $F_m = q (\vec{v} \times \vec{B})$

$$f_{m1} = \lambda_1 (\vec{v}_1 \times \vec{B}_2) \quad \text{(downward)}$$

$$B_2 = \frac{\mu_0 I}{2\pi d} \quad \text{(out of page)} = \frac{\mu_0 \lambda v}{2\pi d}$$

$$I = \frac{q}{t}$$

$$= \lambda v$$

$$f_{m1} = \lambda_1 v_1 B_2$$

$$\theta = 90^\circ$$

$$f_{m1} = \frac{\mu_0 \lambda^2 v^2}{2\pi d} \quad \text{--- (2)}$$

These 2 forces must balance each other so

$$\frac{\mu_0 \lambda^2 v^2}{2\pi d} = \frac{\lambda^2}{2\pi\epsilon_0 d}$$

$$v^2 = \frac{1}{\mu_0 \epsilon_0}$$

$$\Rightarrow v = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\mu_0 = 4\pi \times 10^{-7} \Rightarrow v = \frac{1}{\sqrt{4\pi \epsilon_0 \times 10^{-7}}} = \frac{1}{\sqrt{\frac{1}{9 \times 10^9} \times 10^{-7}}}$$

$$v = 3 \times 10^8 \text{ m/s}$$

$$v = c \text{ m/s}$$

- If  $v < c$  then electric force will be dominant.

$$v \uparrow, B_m \uparrow$$

AMPERE'S Law :- This law is valid only in Magnetostatic  
 In Electrostatics  $\rightarrow$  Coulomb law  $\leftrightarrow$  Biot-Savart law  
 Gauss law  $\leftrightarrow$  Ampere's law

$$\oint B \cdot dl = \mu_0 I_{enc} \Rightarrow \text{Integral form of Ampere's law.}$$

By using Stokes theorem, closed line integral can be written as open surface integral.

$$\Rightarrow \int_S (\nabla \times \vec{B}) \cdot d\vec{S} = \mu_0 \int_S \vec{J} \cdot d\vec{S}$$

$$\Rightarrow \int_S (\nabla \times \vec{B} - \mu_0 \vec{J}) \cdot d\vec{S} = 0$$

$$\oint_S \boxed{\nabla \times \vec{B} = \mu_0 \vec{J}} \Rightarrow \text{Differential form}$$

Compare with Electrostatics

$$\nabla \cdot \vec{E} = \rho/\epsilon_0$$

$$\nabla \times \vec{E} = 0$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{B} = \mu_0 \vec{J}$$

$$\text{Curl } \vec{B} \neq 0$$

So Mag. field is not a Conservative field, and  
 Physical significance of  $\nabla \cdot \vec{B} = 0$  is Non existence of  
 magnetic monopole.

$\int_S \nabla \cdot \vec{B} = 0$  Integral form of  $\nabla \cdot \vec{B} = 0$  is

$$\oint_S \vec{B} \cdot d\vec{S} = 0$$

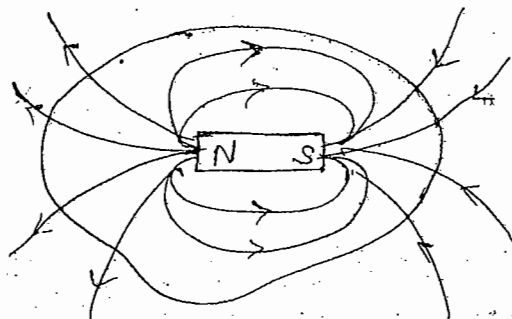
(by using Gauss law)

It is also called

Gauss law in Magnetostatic  $\Rightarrow \nabla \cdot \vec{B} = 0$  or  $\oint_S \vec{B} \cdot d\vec{S} = 0$

If we have a close surface & put a magnet into this closed surface then mag. flux passing through this surface this  $= 0$ .

Mag. field lines originates at North pole & terminates at south pole.



line enter in south pole = line leaving north pole

Net no. of field lines coming or going  $= 0$

So Magnetic monopoles do not exist.

Theoretically Mag. monopoles exist but No experimental proof till now.

Note If we want to find out the mag. field from Ampere's law then there should be symmetry in problem.

Ques:- Find the magnetic field at a distance  $r$  from a long straight wire carrying a steady current  $I$ .

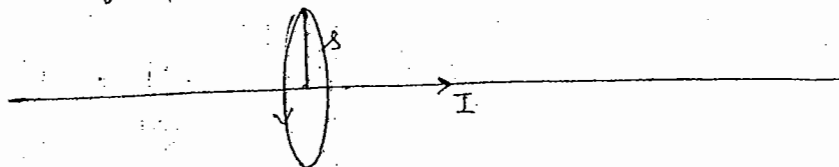
(If we have a short wire then the dir<sup>n</sup> of  $\vec{B}$  will be complex)

i.e. there will be complexity.  $\xrightarrow{I} \cdot P$  dir<sup>n</sup> of  $\vec{B}$  at  $P \rightarrow$  outward

but  $\xrightarrow{I} \cdot P$   $\rightarrow$  complexity. (at  $P$  in this case, we can't define dir<sup>n</sup> of  $\vec{B}$ )

So wire should be long or infinite.

Sketch a Amperical loop s.t. point should be lie on the circumference of loop.





$$I_{enc} = I$$

Ampere's law  $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I$

$$B \cdot 2\pi r = \mu_0 I$$

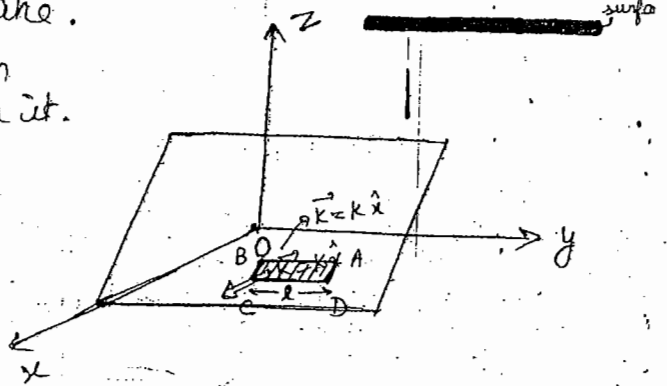
$$\boxed{\vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}}$$

Find the mag. field of an infinite uniform surface current  $\vec{K} = K \hat{x}$  flowing over  $x$ - $y$  plane.

Amperical loop should be chosen s.t. current must pass through it. surface is very thin.

$$\oint \vec{B} \cdot d\vec{\ell} = \int_{AB} + \int_{BC} + \int_{CD} + \int_{DA}$$

If we put too many wires together then they make a surface.



$$\int_{AB} \vec{B} \cdot d\vec{\ell} = B \cdot l \cos 0 = Bl$$

$$\int_{BC} \vec{B} \cdot d\vec{\ell} = B \cdot l \cos 90 = 0$$

$$\int_{CD} \vec{B} \cdot d\vec{\ell} = B \cdot l \cos 0 = Bl$$

$$\int_{DA} \vec{B} \cdot d\vec{\ell} = B \cdot l \cos 90 = 0$$

$$\text{So } Bl + 0 + Bl + 0 = \mu_0 I_{enc}$$

$$K = \frac{I}{l} \Rightarrow \frac{I}{l} = K \Rightarrow I = Kl$$

$$\text{So } 2Bl = \mu_0 Kl \Rightarrow B = \frac{\mu_0 K}{2}$$

$$\boxed{\vec{B} = \frac{\mu_0 K}{2} (-\hat{y}), z > 0 \text{ (upper surface)}}$$

$$\boxed{\vec{B} = \frac{\mu_0 K}{2} (+\hat{y}), z < 0 \text{ (lower surface)}}$$

This mag. field is independent of distance.

If we replace  $\mu_0 \rightarrow \frac{1}{\epsilon_0}$  &  $K \rightarrow \sigma$  then, we get

$$\vec{E} = \frac{\sigma}{2\epsilon_0} (+\hat{z}), z > 0$$

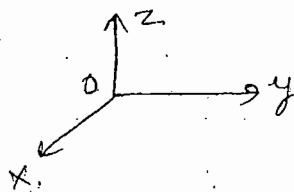
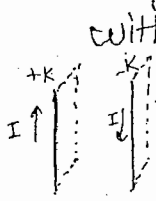
$$\vec{E} = \frac{\sigma}{2\epsilon_0} (-\hat{z}), z < 0$$

So  $\vec{E}$  &  $\vec{B}$  are equivalent.

Right hand Palm on surface  
Thumb in the dir<sup>n</sup> of current  
Finger will tell the dir<sup>n</sup> of  $\vec{B}$

ie. for upper surface  
dir<sup>n</sup> of  $\vec{B} \Rightarrow -\hat{y}$   
lower surface  $\Rightarrow +\hat{y}$

Q. If we have 2 parallel surfaces one carries surface current  $+K$  & another carries surface current  $-K$ . Find the mag. field in region I, II, III with dir<sup>n</sup>.



	(I)	(II)	(III)
$+K \hat{z}$	$\frac{\mu_0 K}{2} \hat{x}$	$-\frac{\mu_0 K}{2} (+\hat{x})$	$-\frac{\mu_0 K}{2} \hat{x}$
$-K \hat{z}$	$-\frac{\mu_0 K}{2} \hat{x}$	$-\frac{\mu_0 K}{2} \hat{x}$	$+\frac{\mu_0 K}{2} \hat{x}$

In (I) region,

$$\vec{B} = \frac{\mu_0 K}{2} \hat{x} - \frac{\mu_0 K}{2} \hat{x}$$

$$\vec{B} = 0$$

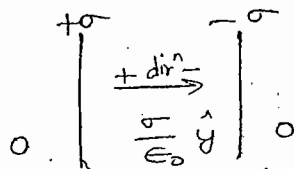
(III) region,  $\vec{B} = 0$

(II) region,  $\vec{B} = -\frac{\mu_0 K}{2} \hat{x} - \frac{\mu_0 K}{2} \hat{x}$

$$\boxed{\vec{B} = \mu_0 K (-\hat{x})}$$

i.e. If 2 plates have equal & opposite surface current then mag. field in b/w plates is non-zero, & outside is zero.

similar as Ele. field

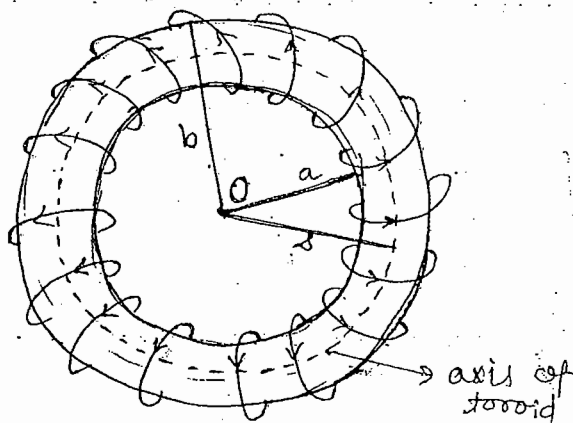


Q. Mag. field of a toroidal coil [Toroid is endless solenoid]

If Toroid contains  $N$  no. of total turns then Magnetic field inside the toroidal coil is

$$\boxed{\vec{B}_{in} = \frac{\mu_0 N I}{2\pi r} \hat{\phi}}, \quad a < r < b$$

$$\boxed{\vec{B}_{out} = 0}, \quad r > b \text{ or } r < a$$

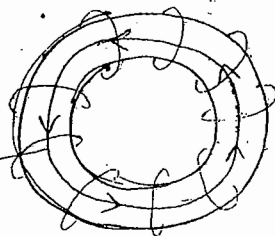


Mag field of a solenoid is along  $\rightarrow \hat{z}$

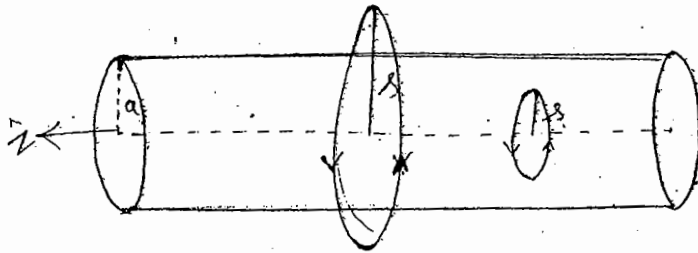
but " " " " toroid "  $\rightarrow \hat{\phi}$

$r$  is measured from origin

dir<sup>n</sup> of  $\vec{B}$  of inside the Toroid



Q. A steady current  $I$  flows down a long cylindrical wire of radius  $a$ . find the mag. field both inside & outside the wire if (a) current is uniformly distributed over the entire surface of the wire. (b) current is distributed in such a way that  $J \propto s$ .



(a)  $I_{enc} = 0$  (Inside)

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I$$

$$\Rightarrow \boxed{B_{in} = 0}$$

Outside 1-  $I_{enc} = I$

$$\oint_{out} \vec{B} \cdot d\vec{l} = \mu_0 I \Rightarrow B_{out} \cdot 2\pi s = \mu_0 I$$

$$\boxed{\vec{B}_{out} = \frac{\mu_0 I}{2\pi s} \hat{\phi}}$$

(b)  $J \propto s$

$$J = k s$$

$$I = \int \vec{J} \cdot d\vec{S} = \int_0^{2\pi} \int_0^a k s s ds d\phi$$

$$I = k \left( \frac{s^3}{3} \right)_0^a (2\pi) = k \frac{a^3}{3} 2\pi$$

$$\boxed{k = \frac{3I}{2\pi a^3}}$$

$$\boxed{J = \frac{3I s}{2\pi a^3}}$$

Inside 1-  $I_{enc} = \int_0^{2\pi} \int_0^s J \cdot ds = \int_0^{2\pi} \int_0^s \frac{3I}{2\pi a^3} s \cdot ds d\phi$

$$I_{enc} = \frac{I s^3}{a^3}$$

$$\oint B_{in} \cdot d\vec{l} = \mu_0 I_{enc} \Rightarrow B_{in} \cdot 2\pi s = \mu_0 \frac{I s^3}{a^3}$$

$$\boxed{B_{in} = \frac{\mu_0 I s^2}{2\pi a^3} \hat{\phi}}$$

Outside :-  $I_{enc} = I$

$$\vec{B}_{out} = \frac{\mu_0 I}{2\pi s} \hat{\phi}$$

[same as part a]

Note :- If  $J \propto s^n$  then

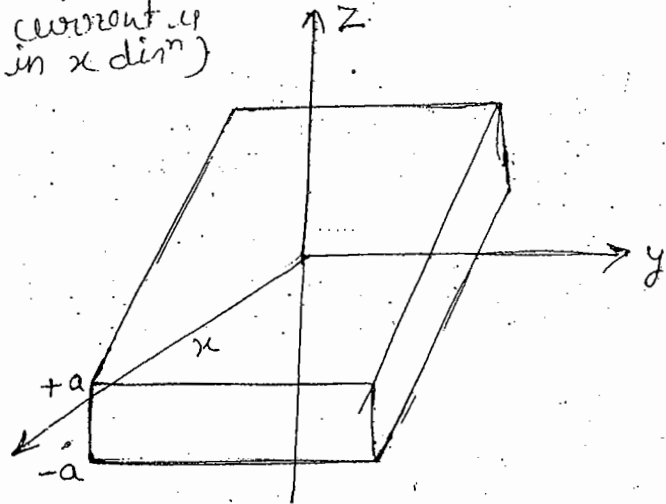
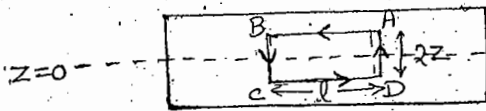
$$B_{in} \propto s^{n+1}, B_{out} \propto \frac{1}{s}$$

$$\rho \propto s^n$$

$$E_{in} \propto s^{n+1}, E_{out} \propto \frac{1}{s}$$

Q. A thick slab extending from  $z = -a$  to  $z = +a$  carries a uniform volume current  $\vec{J} = J\hat{x}$ . Find the magnetic field as a function of  $z$  both inside & outside the slab.

$$\vec{J} = J\hat{x} \quad (\text{i.e. current in } x \text{ dir})$$



$$\vec{B} \rightarrow -\hat{y} \quad \text{for } z > 0$$

$$\vec{B} \rightarrow \hat{y} \quad z < 0$$

Inside current enclosed by the loop

$$I = J A_{\perp}$$

$$I = J 2z l$$

Inside Mag. field

$$\oint \vec{B} \cdot d\vec{l} = \int_{AB} \vec{B} \cdot d\vec{l} + \int_{BC} \vec{B} \cdot d\vec{l} + \int_{CD} \vec{B} \cdot d\vec{l} + \int_{DA} \vec{B} \cdot d\vec{l}$$

$$= Bl + 0 + Bl + 0 = 2Bl$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$2Bl = \mu_0 J 2z l \Rightarrow B = \mu_0 J z$$

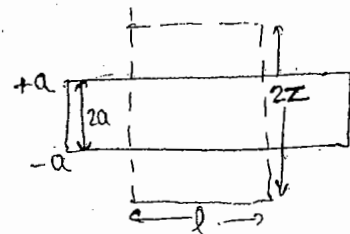
$$\vec{B}_{in} = \mu_0 J z (-\hat{y}), \quad z > 0$$

$$\vec{B}_{in} = \mu_0 J z (+\hat{y}), \quad z < 0$$

so Mag. field inside is linearly  $\uparrow$  (as it depends on  $z$ )

Outside  $I = J \cdot 2al$

$$\oint \vec{B} \cdot d\vec{l} = 2Bl$$



$$2Bl = \mu_0 \cdot J 2al$$

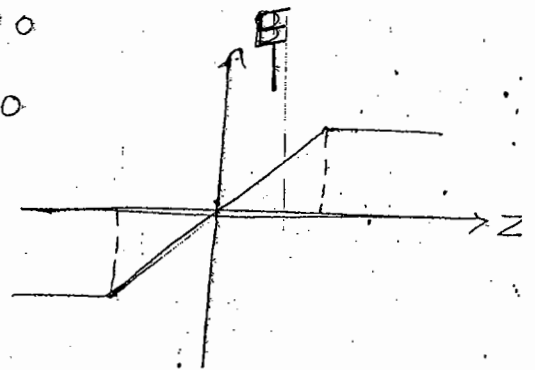
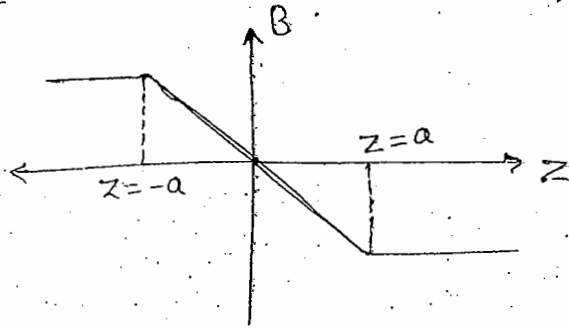
$$B_{out} = \mu_0 J a \text{ (constant)}$$

Outside mag. field is constant.

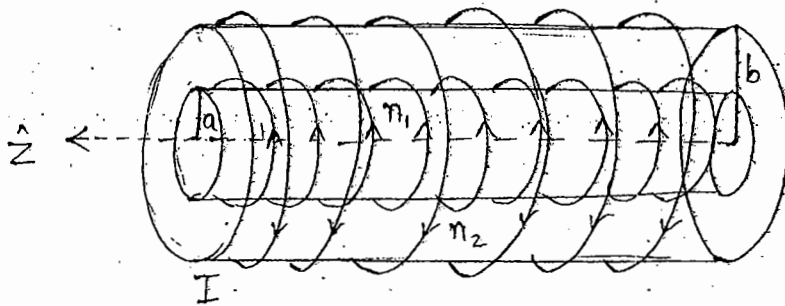
$$B_{out} = \mu_0 J a (-\hat{y}) \quad , z > 0$$

$$B_{out} = \mu_0 J a (+\hat{y}) \quad , z < 0$$

Plot: similar as electric field.



Q. :- Two long Co-axial solenoids each carry current  $I$  but in opposite dir<sup>n</sup> as shown in the figure. The inner solenoid radius  $a$  has  $n_1$  turns per unit length and outer one radius  $b$  has  $n_2$  turns per unit length. Find mag. field in 3 regions.



- (i)  $s < a$
- (ii)  $a < s < b$
- (iii)  $s > b$

(i)  $s < a$ , region is inside both the solenoid.

for inner solenoid  $S_1 \rightarrow \vec{B} = \mu_0 n_1 I \hat{z}$   
 outer  $S_2 \rightarrow \vec{B} = -\mu_0 n_2 I \hat{z}$

$$\vec{B} = \mu_0 (n_1 - n_2) I \hat{z}$$

(ii)  $a < s < b$ ,

$B = 0$  for  $S_1$   
 $B = \mu_0 n_2 I (-\hat{z})$  for  $S_2$

$$\vec{B} = \mu_0 n_2 I (-\hat{z})$$

(iii)  $s > b$

$B_{total} = 0$  for both  $S_1$  &  $S_2$  as  $I_{enc} = 0$

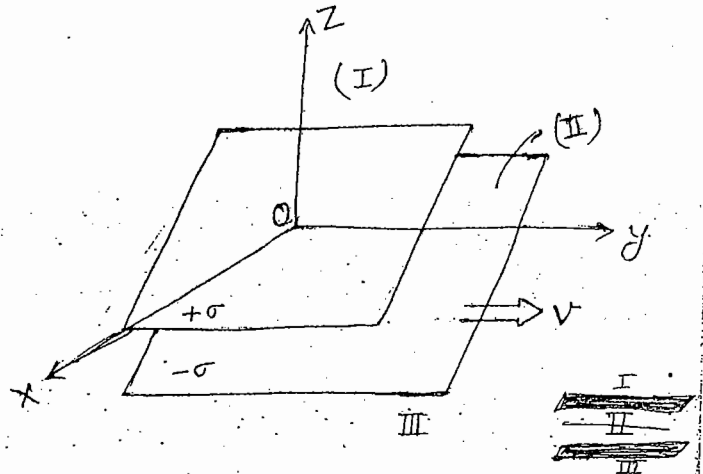
Q. A large parallel plate capacitor with uniform surface charge  $\sigma$  on the upper plate &  $-\sigma$  on lower plate moving with constant speed  $v$ . (a) find  $\vec{B}$  b/w the plates & outside the plates.

(b) find the mag force per unit area (pressure) on the upper plate with dir<sup>n</sup>

(c) What should be the value of  $v$  to balance such that magnetic attraction repulsion balances the electrical attraction.

(a)  $\vec{K}_{\text{upper}} = \sigma v \hat{y}$

$\vec{K}_{\text{lower}} = \sigma v (-\hat{y})$



Due to upper plate  $\vec{B}$  in region

I  $\rightarrow \frac{\mu_0 k}{2} \hat{x}$

II  $\rightarrow -\frac{\mu_0 k}{2} \hat{x}$

III  $\rightarrow -\frac{\mu_0 k}{2} \hat{x}$

Due to lower plate,  $\vec{B}$  in

I  $\rightarrow -\frac{\mu_0 k}{2} \hat{x}$ , II  $\rightarrow -\frac{\mu_0 k}{2} \hat{x}$ , III  $\rightarrow \frac{\mu_0 k}{2} \hat{x}$

for  $+\sigma$ , dir<sup>n</sup> of  $K$  is same as  $v$   
for  $-\sigma$ , opposite to  $v$

So in region (I),  $\vec{B} = 0$ , in (III),  $\vec{B} = 0$

In Region (II),  $\vec{B} = -\frac{\mu_0 k}{2} \hat{x} - \frac{\mu_0 k}{2} \hat{x}$

$\vec{B} = -\mu_0 k \hat{x} = \mu_0 k (-\hat{x})$

$\vec{B} = \mu_0 \sigma v (-\hat{x})$

Magnitude of  $K = \sigma v$

(b) Magnetic force,  $\vec{F} = q(\vec{v} \times \vec{B})$

In terms of surface current  $\vec{F}_m = \int (\vec{K} \times \vec{B}) \cdot d\vec{a}$

Mag. force/unit area  $\vec{F}_{mU} = (\vec{K} \times \vec{B})$

mag. repulsion  $\leftarrow \vec{F}_m = \frac{\mu_0 \sigma^2 v^2}{2} (+\hat{z})$

dir<sup>n</sup> of  $B$  due to  $\sigma = \vec{B} \rightarrow \hat{x}$

dir<sup>n</sup> of  $\vec{K}_U \rightarrow \hat{y}$ , dir<sup>n</sup> of  $B_L \rightarrow -\hat{x}$

So  $f_m \rightarrow \hat{y} \times (-\hat{x}) = +\hat{z}$

lly  $\vec{F}_m$  for lower plate  $\vec{F}_m = \frac{\mu_0 \sigma^2 v^2}{2} (-\hat{z})$

(c)  $\vec{F} = q\vec{E}$   
 $f_{e, \text{upper}} = \sigma_u \vec{E}_d = \sigma \frac{\sigma}{2\epsilon_0} (-\hat{z})$   
 $\frac{\mu_0 \sigma^2 v^2}{2} = \frac{\sigma^2}{2\epsilon_0}$

$$\Rightarrow v^2 = \frac{1}{\epsilon_0 \mu_0} \Rightarrow \boxed{v = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = c}$$

The speed for which  $d$  remains constant (when attractive force = repulsion forces) ( $d \rightarrow$  distance b/w 2 plates)

Magnetic Vector Potential ( $\vec{A}$ ): As for electrostatic field,

$$\boxed{\nabla \times \vec{E} = 0} \Rightarrow \vec{E} = -\nabla V$$

$V \rightarrow$  scalar pot<sup>n</sup>

$$\& \boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}} \Rightarrow \boxed{\nabla^2 V = -\frac{\rho}{\epsilon_0}}$$

if we put the  $v$  in  $\nabla \times E$  then it still 0 bec  $\text{curl}(\text{grad}) = 0$

But here,  $\nabla \times \vec{B} = \mu_0 \vec{J}$  &  $\nabla \cdot \vec{B} = 0$

Poisson's eq<sup>n</sup> in electrostatics.

if  $\nabla \cdot \vec{B} = 0$  then  $B$  can be written as

$$\checkmark \boxed{\vec{B} = \nabla \times \vec{A}} \text{ as } \text{div}(\text{curl}) = 0$$

Put the value of  $B$  in  $\nabla \times \vec{B} = \mu_0 \vec{J}$ , we get

$$\nabla \times \nabla \times \vec{A} = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} = \mu_0 \vec{J}$$

In Magnetostatic, We choose a conditions that

$$\nabla \cdot \vec{A} = 0$$

Hence  $\checkmark \boxed{\nabla^2 \vec{A} = -\mu_0 \vec{J}}$

This is called Poisson's eq<sup>n</sup> in Magnetostatic.

\* If  $\vec{B}$  is given & we have to find  $\vec{A}$  then

$$\checkmark \boxed{\vec{A} = \frac{1}{2}(\vec{B} \times \vec{r})}$$

This is conditionally true. Its cond<sup>n</sup> is  $\vec{B}$  should be uniform i.e.  $\boxed{\nabla \times \vec{B} = 0}$

i.e. If  $\nabla \times \vec{B} = 0$  only then we can use this formula of  $\vec{A}$  where  $\vec{r}$  is a position vector.

$$\nabla^2 \vec{A} = -\mu_0 \vec{J} \quad \text{in Magnetostatic}$$

$$\begin{aligned} \vec{A} &= \frac{\mu_0}{4\pi} \int \frac{I d\vec{l}}{r} \\ &= \frac{\mu_0}{4\pi} \int \frac{\vec{K} da}{r} \\ &= \frac{\mu_0}{4\pi} \int \frac{\vec{J} d\tau}{r} \end{aligned}$$

These formulas are applicable only if current is not extended to  $\infty$ .

eg. If we have a  $\infty$  current carrying wire then these formulas can not be applicable.

\* Dir<sup>n</sup> of A is  $\perp$  to dir<sup>n</sup> of B always.

generally it matches with dir<sup>n</sup> of current (parallel or antiparallel). If I in  $\hat{x}$  dir<sup>n</sup> then  $\vec{A}$  can be in  $\hat{x}$  or  $-\hat{x}$  but can never be in  $\hat{y}$  or  $\hat{z}$ .

$$\nabla^2 V = -\rho/\epsilon_0 \quad \text{in E.S.}$$

$$V = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r}$$

$$\begin{aligned} V &= \frac{1}{4\pi\epsilon_0} \int \frac{\rho d\tau}{r} \\ &= \frac{1}{4\pi\epsilon_0} \int \frac{\sigma da}{r} \\ &= \frac{1}{4\pi\epsilon_0} \int \frac{\rho d\tau}{r} \end{aligned}$$

These formulas are valid only if charge is localised i.e. charge is not extended to  $\infty$ .

Q. Find the mag. vector potential of an  $\infty$  solenoid with  $n$  turns per unit length, radius  $R$  & current  $I$ .  
Here current is extended to  $\infty$  i.e. Not localised so can't use above formula to find  $\vec{A}$ .

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I \quad (\text{Ampere's law})$$

Mag flux passing through any surface  $S$

$$\Phi_m = \int_S \vec{B} \cdot d\vec{S} = \int_S (\nabla \times \vec{A}) \cdot d\vec{S}$$

$$= \oint \vec{A} \cdot d\vec{l} \quad (\text{from Stokes's theorem})$$

Mag. field inside the solenoid,

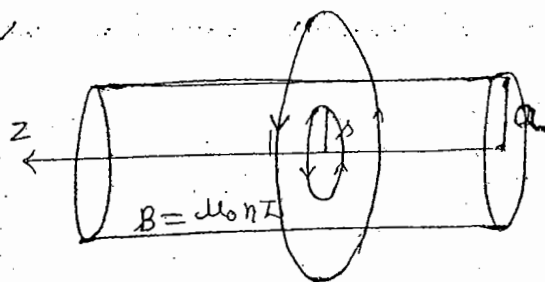
$$B = \mu_0 n I$$

$$\Phi_m = B \cdot \pi s^2$$

$$= \mu_0 n I \cdot \pi s^2 = \oint \vec{A} \cdot d\vec{l}$$

$$\mu_0 n I \pi s^2 = A \cdot 2\pi s$$

$$\Rightarrow \boxed{\vec{A}_{in} = \frac{\mu_0 n I s}{2} \hat{\phi}}$$





Outside :-

$$\begin{aligned}\phi_m &= B \cdot \pi a^2 \\ &= \mu_0 n I \cdot \pi a^2 = \oint \vec{A} \cdot d\vec{l} \\ &= A_{out} \cdot 2\pi a\end{aligned}$$

$$\Rightarrow \vec{A}_{out} = \frac{\mu_0 n I a^2}{2a} \hat{\phi}$$

Mag. vector pot<sup>n</sup> inside & outside the solenoid = Non-zero  
While Mag. field inside  $\rightarrow$  Non-zero, outside  $\rightarrow$  zero.

&  $\vec{A}_{out} \propto \frac{1}{s}$  dir<sup>n</sup> matches with current

Note :-  $\nabla \times$  is Not necessary that if  $\vec{B} = 0$  then  $\vec{A} = 0$

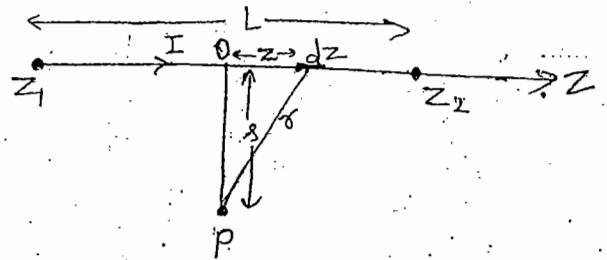
17/8/2012

Q. Find the magnetic vector potential of a finite segment of straight wire carrying current  $I$ . Put the wire along  $z$ -axis from  $z_1$  to  $z_2$ .

We have to find mag. vector pot<sup>n</sup> at point  $P$  which is at a distance  $s$  from wire.

This is a finite wire

$$\text{So } \vec{A} = \frac{\mu_0}{4\pi} \int \frac{I d\vec{l}}{r}$$



Take a small element, its length is  $dz$  which is at a distance  $z$  from mid point of wire  $O$ .

$$\vec{A} = \frac{\mu_0}{4\pi} \int_{z_1}^{z_2} \frac{I dz}{(s^2 + z^2)^{1/2}} = \frac{\mu_0}{4\pi} \int_{-L/2}^{L/2} \frac{I dz}{(s^2 + z^2)^{1/2}}$$

This is standard integral. It gives

$$\vec{A} = \frac{\mu_0 I}{4\pi} \ln \left[ z + \sqrt{z^2 + s^2} \right]_{-L/2}^{L/2}$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \ln \left[ \frac{L/2 + \sqrt{\frac{L^2}{4} + s^2}}{-L/2 + \sqrt{\frac{L^2}{4} + s^2}} \right]$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \ln \left[ \frac{L/2 + (\frac{L^2}{4} + s^2)^{1/2}}{-L/2 + (\frac{L^2}{4} + s^2)^{1/2}} \right]$$

\* This is mag. vector pot<sup>n</sup> at  $P$  from mid point of wire.

⇒ If wire is very very long  $L \gg s$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \ln \left[ \frac{\sqrt{\frac{L}{2} \left[ 1 + \left( 1 + \frac{4s^2}{L^2} \right)^{1/2} \right]}}{\sqrt{\frac{L}{2} \left[ -1 + \left( 1 + \frac{4s^2}{L^2} \right)^{1/2} \right]}} \right]$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \ln \left[ \frac{1 + 1 + \frac{2s^2}{L^2}}{\cancel{1} + \cancel{1} + \frac{2s^2}{L^2}} \right] = \frac{\mu_0 I}{4\pi} \ln \left[ \frac{2 + \frac{2s^2}{L^2}}{\frac{2s^2}{L^2}} \right]$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \ln \left[ \frac{L^2}{s^2} + 1 \right]$$

$L \gg s$  then  $\frac{L}{s} \gg 1$  &  $\frac{L^2}{s^2} \gg \gg 1$  so neglect 1 as compare to  $L^2/s^2$  so

$$\vec{A} = \frac{\mu_0 I}{4\pi} \ln \left( \frac{L}{s} \right)^2$$

$$\boxed{\vec{A} = \frac{\mu_0 I}{2\pi} \ln \left( \frac{L}{s} \right) \hat{z}} \quad (\text{dir}^n \text{ same as current})$$

This is the mag. vector pot<sup>n</sup> of a very long wire at pt. P which is at a distance  $s$  from mid point O of wire.

Q. Find the current density corresponding to a vector pot<sup>n</sup>  $\vec{A} = K \hat{\phi}$  where  $K$  is constant in cylindrical co-ordinates

$J = ?$

$$\vec{A} = K \hat{\phi}$$

$$\left\{ \nabla^2 \vec{A} = -\mu_0 \vec{J} \right. \quad (\text{it may give wrong ans}) \quad \left. \begin{array}{l} \vec{A} \\ \downarrow \\ \vec{B} \\ \downarrow \\ \vec{J} \end{array} \right\}$$

$$\frac{1}{s^2} \frac{\partial^2 A_\phi}{\partial \phi^2} = -\mu_0 \vec{J} \Rightarrow \frac{1}{s^2} \frac{\partial^2}{\partial \phi^2} (K \hat{\phi}) = -\mu_0 \vec{J}$$

first find  $\vec{B}$  & then  $\vec{J}$

$$\begin{aligned} \vec{B} &= \nabla \times \vec{A} = \frac{1}{s} \begin{vmatrix} \hat{s} & s\hat{\phi} & \hat{z} \\ \frac{\partial}{\partial s} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_s & sA_\phi & A_z \end{vmatrix} \\ &= \frac{1}{s} \begin{vmatrix} \hat{s} & s\hat{\phi} & \hat{z} \\ \frac{\partial}{\partial s} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & sA_\phi & 0 \end{vmatrix} = \frac{1}{s} \left[ \frac{\partial}{\partial s} (sA_\phi) \hat{z} - \frac{\partial A_\phi}{\partial z} \hat{s} \right] \\ &= \frac{1}{s} \left[ \frac{\partial}{\partial s} (sK) \hat{z} \right] \end{aligned}$$

$$\vec{B} = \frac{1}{s} k \hat{z} \quad \text{or} \quad \boxed{\vec{B} = \frac{k}{s} \hat{z}}$$

We have  $\nabla \times \vec{B} = \mu_0 \vec{J}$

$$\vec{J} = \frac{1}{\mu_0} (\nabla \times \vec{B})$$

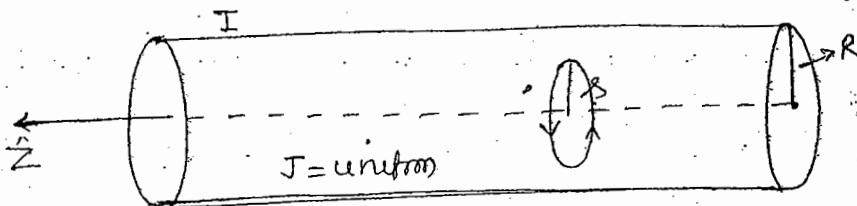
$$\vec{J} = \frac{1}{\mu_0} \begin{vmatrix} \hat{s} & s\hat{\phi} & \hat{z} \\ \frac{\partial}{\partial s} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ B_s & sB_\phi & B_z \end{vmatrix} = \frac{1}{\mu_0} \left[ -\frac{\partial}{\partial s} (B_z) \hat{\phi} + \frac{1}{s} \frac{\partial}{\partial \phi} (s B_z) \hat{s} \right]$$

$$\vec{J} = -\frac{1}{\mu_0} \frac{\partial}{\partial s} \left( \frac{k}{s} \right) \hat{\phi} = \frac{1}{\mu_0} \frac{k}{s^2} \hat{\phi}$$

$$\boxed{\vec{J} = \frac{k}{\mu_0 s^2} \hat{\phi}}$$

Q. Find the mag. vector pot<sup>n</sup> inside & outside the infinite wire if its radius is R and total current I is uniformly distributed over the cross-section. Assume that vector pot<sup>n</sup> vanishes on the surfaces of the wire.

We have a thick wire of radius R & current I is flowing  $\hat{z}$  in z dir<sup>n</sup>.



If wire is infinite then we can not apply directly

$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{J} dl}{r} \quad (\text{This can be used only if current is localised})$$

When current extended to itself to  $\infty$  then we'll find A through B.  $\oint \vec{A} \cdot d\vec{l} = \phi_m$

• Inside

To find  $\vec{B}_{in}$ , take a Ampirical loop inside the wire ( $\vec{J} = \text{uniform}$ ) & By Ampere's law  $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$

$J = I/A_{\perp} = I/\pi R^2$  } current is distributed over the whole cross-section

Current enclosed by the loop

$$I_{enc} = \int_0^s J \cdot ds = J \cdot \pi s^2 = \frac{I}{\pi R^2} \pi s^2$$

$$I_{enc} = \frac{I s^2}{R^2}$$

So  $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$

$$B \cdot 2\pi s = \mu_0 \frac{I s^2}{R^2}$$

$$\vec{B}_{in} = \frac{\mu_0 I s}{2\pi R^2} \hat{\phi}$$

for a uniformly charged  $\infty$  thick wire, then mag. field inside is  $\propto s$ . i.e. if  $\vec{J} = \text{uniform}$

then  $B_{in} \propto s$

• Outside :-

$$I_{enc} = \int_0^R J \cdot ds = \frac{I}{\pi R^2} \pi R^2$$

$$I_{enc} = I$$

So  $B \cdot 2\pi s = \mu_0 I$

$$\vec{B}_{out} = \frac{\mu_0 I}{2\pi s} \hat{\phi}$$

Now find Mag. Vector pot<sup>n</sup>,

$$\oint \vec{A} \cdot d\vec{l} = \int_S \vec{B} \cdot d\vec{s} = \phi_m$$

We can not use this formula bcoz  $\vec{B}$  is in  $\hat{\phi}$  dir<sup>n</sup> & Amperical loop and is also in  $\hat{\phi}$  dir<sup>n</sup> so no flux will pass through the loop. So

We use  $\vec{B} = \nabla \times \vec{A}$

$$\vec{B} = \frac{1}{s} \begin{vmatrix} \hat{s} & s\hat{\phi} & \hat{z} \\ \frac{\partial}{\partial s} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_s & sA_{\phi} & A_z \end{vmatrix}$$

$$B \hat{\phi} = \frac{1}{s} \left( \frac{\partial A_s}{\partial z} - \frac{\partial A_z}{\partial s} \right) \hat{\phi}$$

$\frac{\partial A_s}{\partial z} \rightarrow$  Mag. vector pot<sup>n</sup> is in s dir<sup>n</sup> & variation with z.

$\frac{\partial A_z}{\partial s} \rightarrow$  " " " " " "

If current is along z then mag. vector pot<sup>n</sup> must be in z-dir<sup>n</sup>.  $\frac{\partial A_s}{\partial z} = 0$

$$B_{\hat{\phi}} = \left(0 - \frac{\partial A_z}{\partial s}\right) \hat{\phi}$$

$$B_{in} = - \frac{\partial A_{in}}{\partial s} \Rightarrow - \frac{\partial A_{in}}{\partial s} = \frac{\mu_0 I s}{2\pi R^2}$$

$$A_{in} = \int \frac{\mu_0 I s}{2\pi R^2} ds + C$$

$$A_{in} = - \frac{\mu_0 I}{2\pi R^2} \frac{s^2}{2} + C$$

Now apply boundary cond<sup>n</sup>s -

At  $s=R$  (at surface)  $A=0$

$$\Rightarrow C = \frac{\mu_0 I R^2}{4\pi R^2}$$

$$\text{so } \boxed{\vec{A}_{in} = \frac{\mu_0 I}{4\pi R^2} (R^2 - s^2) \hat{z}}$$

Now,

$$B_{out} = - \frac{\partial A_{out}}{\partial s} = \frac{\mu_0 I}{2\pi s}$$

$$A_{out} = - \frac{\mu_0 I}{2\pi} \ln s + C$$

$$A_{out} = - \frac{\mu_0 I}{2\pi} \ln(s) + C$$

$$\text{At } s=R \Rightarrow A=0 \Rightarrow C = \frac{\mu_0 I}{2\pi} \ln(R)$$

$$\text{so } \boxed{\vec{A}_{out} = \frac{\mu_0 I}{2\pi} \ln\left(\frac{R}{s}\right) \hat{z}}$$

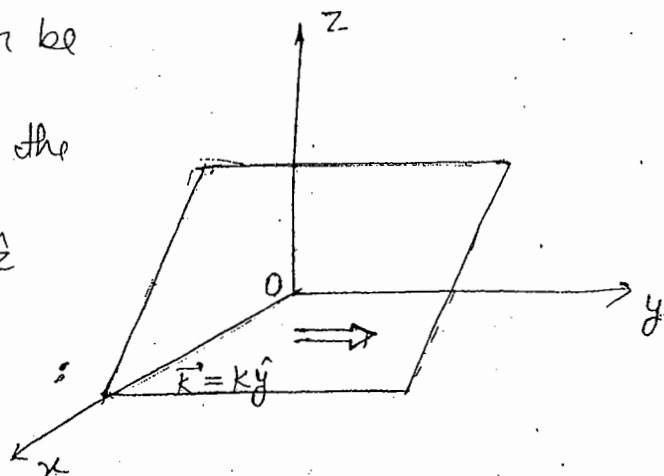
Q. Find the mag. vector pot<sup>n</sup> above & below the plane having uniform surface current,  $\vec{K} = K \hat{y}$  flowing over the x-y plane.  $K \propto$  dimension.

dir<sup>n</sup> of mag. field can never be  $\perp$  to the plane (x-y plane) ( $\hat{z}$ )

Also can not be parallel to the dir<sup>n</sup> of current ( $\hat{y}$ )

So dir<sup>n</sup> of  $\vec{B}$  can't be  $\hat{z}$

or  $\hat{y}$ . So it may be  $+\hat{x}$  or  $-\hat{x}$ .



$$\vec{B} = \frac{\mu_0 K}{2} \hat{x} \quad (z > 0)$$

$$\vec{B} = \frac{\mu_0 K}{2} (-\hat{x}) \quad (z < 0)$$

We have to find  $A = ?$

$$\vec{B} = \nabla \times \vec{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$

$$= \hat{x} \left[ \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right]$$

if current is in y-dir<sup>n</sup> so there will be no variation of  $A_z$  with y.

$$\vec{B} = \hat{x} \left( 0 - \frac{\partial A_y}{\partial z} \right)$$

$$z > 0, \quad \frac{\mu_0 K}{2} = - \frac{\partial A_y}{\partial z}$$

$$A = - \frac{\mu_0 K z}{2} + C$$

Assuming the B-C, at  $z=0$  (at surface)  $A=0$   
 $\Rightarrow C=0$

$$\text{So } \boxed{\vec{A} = - \frac{\mu_0 K z}{2} \hat{y}} \quad (z > 0)$$

$$z < 0, \quad \boxed{\vec{A} = \frac{\mu_0 K z}{2} \hat{y}} \quad (z < 0)$$

# Magnetic Boundary Conditions

B.C.s on Mag. field :- Whenever electric field crosses surface charge  $\sigma$  it suffers a discontinuity.

lly, whenever ~~surfa~~ mag. field crosses surface current  $K$  it suffers discontinuity.

We have a surface current

$$\vec{K} = K \hat{x}$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \Leftrightarrow \oint \vec{E} \cdot d\vec{s} = \frac{q_{enc}}{\epsilon_0} \Rightarrow$$

$$E_{above}^{\perp} - E_{below}^{\perp} = \frac{\sigma}{\epsilon_0}$$

$$\vec{\nabla} \times \vec{E} = 0 \Leftrightarrow \oint \vec{E} \cdot d\vec{l} = 0$$

$$\Rightarrow E_{above}^{\parallel} = E_{below}^{\parallel}$$

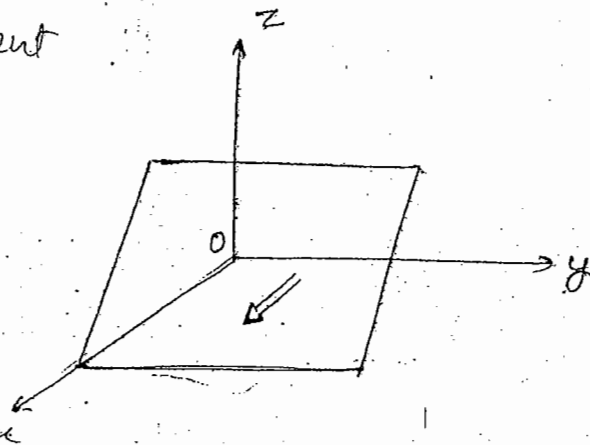
Similarly, for Mag. field,

$$\vec{\nabla} \cdot \vec{B} = 0 \Leftrightarrow \oint \vec{B} \cdot d\vec{s} = 0 \Rightarrow$$

$$B_{above}^{\perp} = B_{below}^{\perp}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \Leftrightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} \Rightarrow$$

$$B_{above}^{\parallel} - B_{below}^{\parallel} = \mu_0 K$$



Conclusion - Tangential component of electric field is continuous but Normal comp. of Mag. field is Continuous. Also, Normal comp. of  $\vec{E}$  is discontinuous by the amount  $\frac{\sigma}{\epsilon_0}$  & tangential " "  $\vec{B}$  " " " "  $\mu_0 K$ .

In electrostatic, scalar pot<sup>n</sup>  $V$  & in Magnetostatic vector pot<sup>n</sup> is  $\vec{A}$ .

$$V_{above} = V_{below}$$

$$A_{above} = A_{below}$$

$$\frac{\partial V_{above}}{\partial n} - \frac{\partial V_{below}}{\partial n} = -\frac{\sigma}{\epsilon_0}$$

$$\frac{\partial A_{above}}{\partial n} - \frac{\partial A_{below}}{\partial n} = -\mu_0 K$$

$n$   $\rightarrow$  vector normal to the surface

$\frac{\partial V_{above}}{\partial n} \rightarrow$  E-field normal to the surface.

18/8/2012

Multipole Expansion of  $\vec{A}$  :-

$$A(\vec{r}) = \frac{\mu_0 I}{4\pi} \left[ \underbrace{\frac{1}{r} \oint dI}_{\text{monopole}} + \underbrace{\frac{1}{r^2} \oint r \cos \theta dI}_{\text{dipole}} + \underbrace{\frac{1}{r^3} \oint r^2 \left( \frac{3}{2} \cos^2 \theta - \frac{1}{2} \right) dI}_{\text{Quadrupole}} + \dots \right]$$

$\oint dI = 0$  So Monopole term = 0

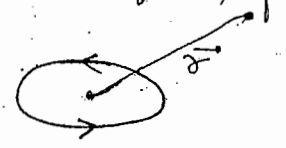
Dipole term is given by  $\vec{A}_{\text{dipole}} = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2}$

where  $m$  is magnetic dipole mom (or magnetic moment) &  $\vec{r}$  it will behave like a dipole

If we have a current loop & we have to find mag. vector pot<sup>n</sup> at point P then  $\vec{r}$  be the distance from centre of dipole to the point P

Magnetic Mom. = Current  $\times$  area

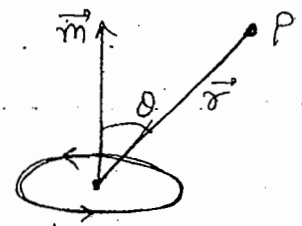
$$\vec{m} = I \vec{a}$$



Its dir<sup>n</sup> will be the dir<sup>n</sup> of  $\vec{a}$ .

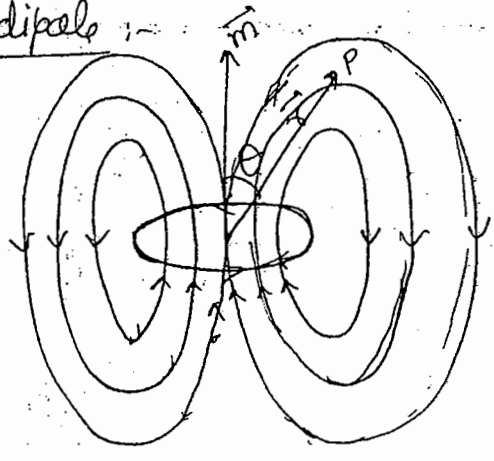
(Curl the fingers in the dir<sup>n</sup> of current & thumb will tell the dir<sup>n</sup> of mag. moment.)

$$\vec{A}_{\text{dip}} = \frac{\mu_0}{4\pi} \frac{m \sin \theta \hat{\phi}}{r^2}$$



As Electric dipole mom. always directed along z-dir<sup>n</sup>. Here loop will be in x-y plane & mag. mom.  $\vec{m}$  is along z-axis & it will make  $\theta$  angle with  $\vec{r}$ ,

Field lines of Mag. dipole :-



$$\begin{aligned} \vec{m} &= m \hat{z} \\ \text{dir}^n \Rightarrow \vec{m} \times \hat{r} & \\ \hat{z} \times \hat{r} &= \sin \theta \hat{\phi} \\ \text{ie. dir}^n \text{ of } \vec{A} &= \hat{\phi} \end{aligned}$$



dir<sup>n</sup> of  $\vec{A}$  matches with dir<sup>n</sup> of current.

$$\vec{B} = \nabla \times \vec{A}$$

$$B = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & r \hat{\theta} & r \sin \theta \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_\theta & r \sin \theta A_\phi \end{vmatrix}$$

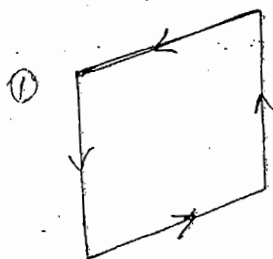
$$\vec{B} = \frac{1}{r^2 \sin \theta} \left[ \hat{r} \left\{ \frac{\partial}{\partial \theta} r \sin \theta A_\phi - \frac{\partial}{\partial \phi} r A_\theta \right\} - r \hat{\theta} \left\{ \frac{\partial}{\partial r} r \sin \theta A_\phi - \frac{\partial}{\partial \phi} A_r \right\} \right]$$

$$\vec{B} = \frac{\mu_0 M}{4\pi r^3} [2 \cos \theta \hat{r} + \sin \theta \hat{\theta}]$$

Similar as  $\vec{E}$ ,  $\vec{E} = \frac{p}{4\pi \epsilon_0 r^3} [2 \cos \theta \hat{r} + \sin \theta \hat{\theta}]$

Q. Find the mag. dipole moment of a bookend-shape loop. All sides have length  $w$  and current  $I$ .

Separate both loop. & find the mag. mom. of each loop.



This loop is in  $x$ - $z$  plane so dir<sup>n</sup> of mag. mom. is  $\hat{y}$ .

$$\vec{m}_1 = I w^2 \hat{y}$$

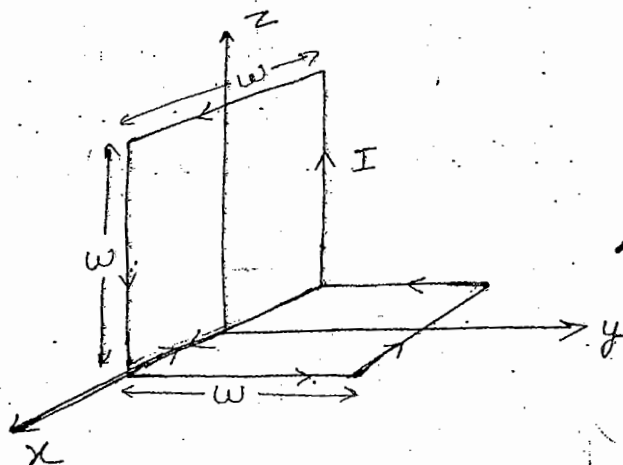
Again for 2nd loop, loop is in  $x$ - $y$  plane so dir<sup>n</sup> of mag. mom. is  $\hat{z}$ .

$$\vec{m}_2 = I w^2 \hat{z}$$

So total mag. mom., vector sum of  $\vec{m}_1$  &  $\vec{m}_2$ .

$$\vec{m} = \vec{m}_1 + \vec{m}_2 \Rightarrow \vec{m} = I w^2 (\hat{y} + \hat{z})$$

$$|\vec{m}| = \sqrt{2} I w^2$$



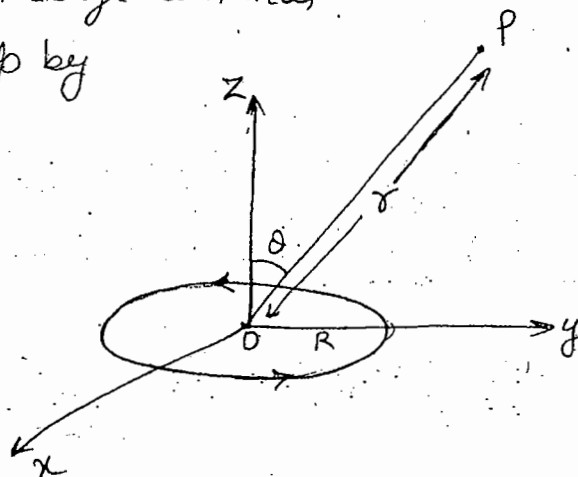
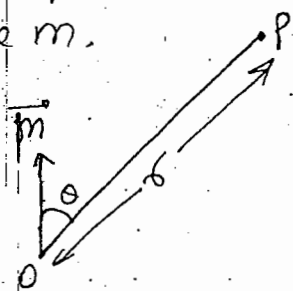
\* Magnetic dipole mom. is always independent on choice of origin beoz mag. monopole mom. is always 0.

Q. A circular loop of wire with radius  $R$  lies in the  $x$ - $y$  plane centred at the origin & carries a current  $I$  running counter clockwise as viewed from  $z$ -axis.

(a) find mag. dipole moment.

(b) Approximate mag. field at large distances

We can replace the whole loop by a single  $m$ .



Mag. dipole mom.

$$\vec{m} = I \vec{a}$$

$$\vec{m} = I \pi R^2 \hat{z}$$

Mag. field at point P,

$$\vec{B} = \frac{\mu_0 m}{4\pi r^3} [2 \cos\theta \hat{r} + \sin\theta \hat{\theta}]$$

$$\vec{B} = \frac{\mu_0 I \pi R^2}{4\pi r^3} [2 \cos\theta \hat{r} + \sin\theta \hat{\theta}]$$

• Magnetic vector pot<sup>n</sup> at the axis of loop,  $\theta = 0$

$$\vec{A} = \frac{\mu_0}{4\pi r^{3/2}} \frac{m \sin\theta}{r^2} \hat{\phi}$$

$$\vec{A}_{\text{axis}} = 0$$

Q. A phonograph record of radius  $R$  carrying a uniform surface charge  $\sigma$  is rotating at a constant angular velocity  $\omega$ . Find its magnetic dipole moment.

$$\vec{v} = \vec{\omega} \times \vec{r}$$

$$= \omega r \sin\theta \hat{\phi}$$

$$\{\hat{z} \times \hat{r} = \sin\theta \hat{\phi}\}$$

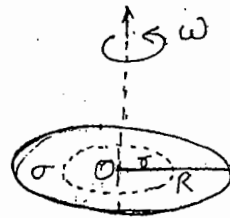
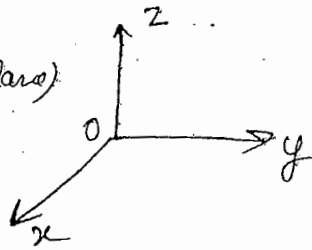
$$\vec{v} = \omega r \hat{\phi}$$

( $\theta = 90^\circ$ ) in x-y plane

$$\vec{k} = \sigma \vec{v}$$

$$\vec{k} = \sigma \omega r \hat{\phi}$$

Surface Current



$$\text{Total current } I = \int_0^R k \cdot d\sigma \quad \left\{ \begin{array}{l} \hat{r}, \hat{\theta}, \hat{\phi} \\ \text{No change in } \hat{\theta} \end{array} \right.$$

$$\text{Magnetic Mom. } \vec{m} = I \vec{a}$$

Area vector,  $\perp$  to the flow of current ( $\theta$  is not changing)

$$d\sigma = r \sin\theta d\phi dr$$

$$= r d\phi dr \quad (\theta = 90^\circ)$$

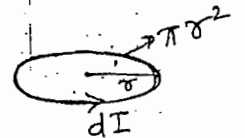
$$= 2\pi r dr$$

$$I = \int_0^R \sigma \omega r dr \quad \left\{ \vec{m} = \frac{\sigma \omega R^2}{2} \times \pi R^2 \text{ is wrong} \right.$$

$I$  is func<sup>n</sup> of  $r$ . At the different point of disc, the value of current will be different & corresponding mag mom. will be different.

Total current in the ring of radius  $r$ ,

$$dI = \sigma \omega r dr$$



$$\text{Mag. Mom. } \vec{m} = I \vec{a}$$

$$\vec{m} = \int \vec{a} \cdot dI$$

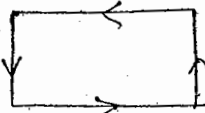
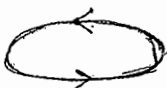
$$\vec{m} = \int_0^R \sigma \omega r dr \cdot \pi r^2 \hat{z}$$

$$\vec{m} = \frac{\sigma \omega \pi R^4}{4} \hat{z}$$

The disc is made up of small rings then mag. mom. in ring =  $dI \cdot a$ .  
When disc is form then  
Mag. mom. =  $\int dI \cdot a$


Note - dir<sup>n</sup> of length vector is always along the line while the " " area " " perpendicular to the area.

Mag. dipole is a current loop, it may be of any shape - circular, square, rectangular --- etc.



$$\oint dI = \text{Net displacement} = 0$$

So closed loop behaves like Mag. Monopole dipole.

- In 8 (eight shape), there are 2 loops. so we have to separate these 2 loops & then find  $\vec{m}$  of each. 
- Definet wise carrying current  $I$  not form a loop do not behave like magnetic dipole.

## Force & Torque on a magnetic dipole

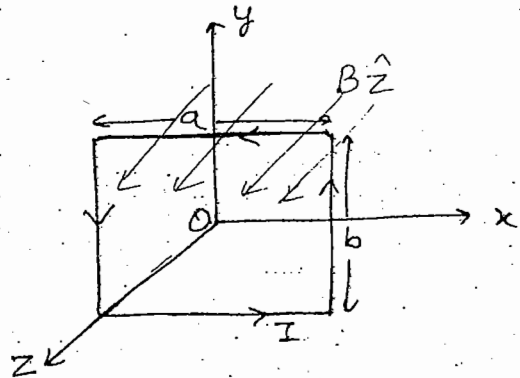
Magnetic dipole experiences no force (0 force) in a uniform magnetic field but it experiences Non-zero torque in uniform magnetic field.

Let us consider a mag. dipole of rectangular shape

Its mag. mom,

$$\vec{m} = I \cdot ab \hat{z}$$

$$\vec{m} = Iab \hat{z}$$



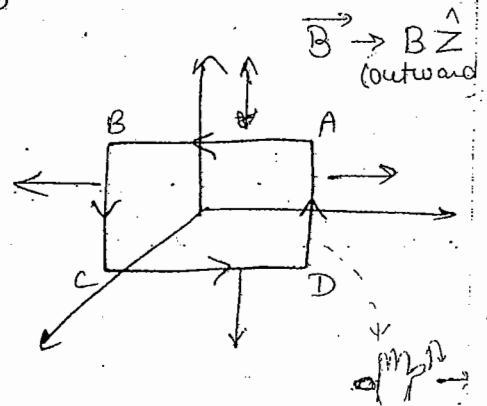
If we apply uniform mag. field  $\vec{B}$  along  $\hat{z}$ , then force on this current loop

$$\vec{F} = I \oint (d\vec{l} \times \vec{B})$$

Sum of total forces for AB, BC, CD, DA will cancel out. So

$$\vec{F} = 0$$

Thus there is No force on the mag. dipole in Uniform mag. field

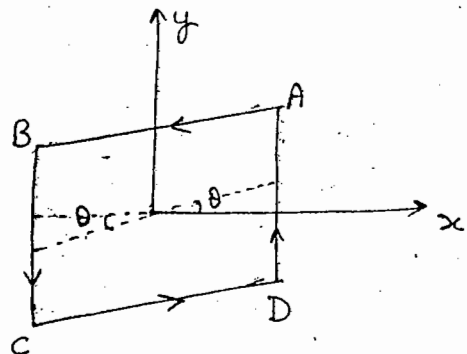
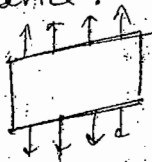


Now Torque :- Rotate the loop s.t. angle b/w  $\vec{m}$  &  $\vec{B}$  is  $\theta$ .

(Earlier angle b/w  $\vec{m}$  &  $\vec{B}$  was zero as  $\vec{m} = Iab\hat{z}$  &  $\vec{B} = B\hat{z}$ )

Now line AD & BC are not at the same value of  $x$ .

forces of line AB & CD will cancel out beoz their line of action is same.



But forces along BC & AD will not cancel out bcoz their line of action is not same, it is different.

$$\boxed{\vec{F}_{AB} + \vec{F}_{CD} = 0}$$

If line of action is different (not same) then they produce Torque.

For line BC & ADA, the angle b/w current & mag. field is always  $90^\circ$ .

$$|\vec{F}_{BC}| = |\vec{F}_{DA}| = I b B$$

$$\begin{cases} F = I \int dl \times B \\ = I B \int dl \\ = I B b \end{cases}$$

Now Torque  $\vec{N} = \vec{r} \times \vec{F}$

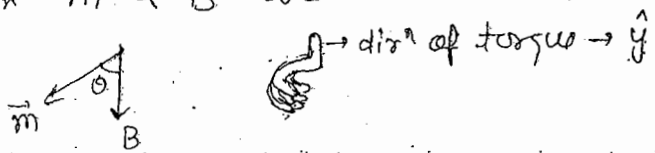
$$N = I b B \frac{a}{2} \sin\theta + I b B \frac{a}{2} \sin\theta$$

$$N = I a b B \sin\theta = m B \sin\theta$$

$$\boxed{\vec{N} = \vec{m} \times \vec{B}} \hat{y}$$

$$N = \vec{p} \times \vec{E}$$

\*  $\vec{m}$  &  $\vec{B}$  are in x-z plane so dir<sup>n</sup> of  $\vec{N}$  will be  $\hat{y}$ .



Torque will try to rotate the plane s.t.  $\vec{B}$  &  $\vec{m}$  are parallel. & when  $\vec{m}$  &  $\vec{B}$  are become parallel then

$$\vec{m} \uparrow \uparrow \vec{B} \quad \text{Torque} = 0$$

Force & Torque in Non-Uniform mag. field :-

$$\boxed{\vec{F}_{\text{Non-uniform}} = \vec{\nabla} (\vec{m} \cdot \vec{B})} \neq (\vec{m} \cdot \vec{\nabla}) \vec{B}$$

$$\left\{ \vec{F}_{\text{Non-unifm}} = (\vec{p} \cdot \vec{\nabla}) \vec{E} = \nabla (\vec{p} \cdot \vec{E}) \right.$$

conditionally true  
cond<sup>n</sup> if  $\vec{p}$  is not a  
fun<sup>n</sup> of position  $x$

bcoz in magnetostatic  $\vec{\nabla} \times \vec{B} \neq 0$

electrostatic  $\vec{\nabla} \times \vec{E} = 0$

Torque  $\tau = \boxed{\vec{N} = \vec{m} \times \vec{B} + \vec{r} \times \vec{F}_{\text{non-uniform}}}$

## Potential Energy of a Magnetic Dipole :-

In Electrostatic relation, Replace  $P$  by  $m$  &  $E$  by  $B$ ;

$$U = -\vec{P} \cdot \vec{E}$$

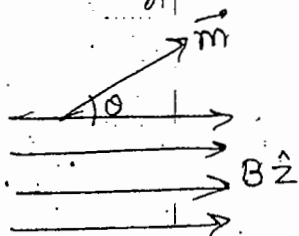
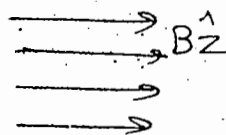
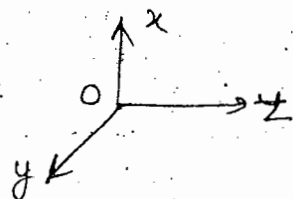
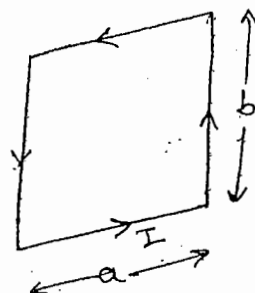
i.e.  $\boxed{U = -\vec{m} \cdot \vec{B}}$

Suppose, we have a loop & current is flowing in this loop is  $I$ .

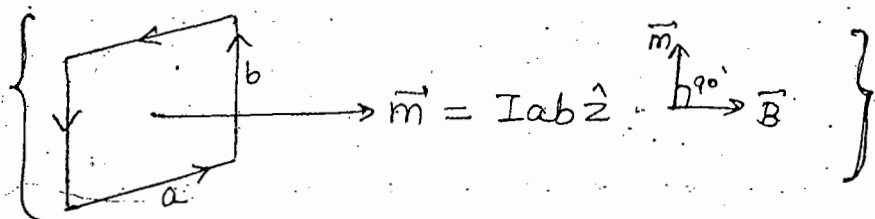
Mag. field is along  $z$ -dir<sup>n</sup>.

If loop is straight then work done to take the loop from  $\infty$  to the mag field is zero, as  $\vec{m}$  &  $\vec{B}$  are in same dir<sup>n</sup>.

But Now loop is tilted by the angle  $\theta$ . So work done is Non-zero as angle b/w  $\vec{m}$  &  $\vec{B}$  is  $\theta$ .



$$dW = N d\theta$$



Now angle changes from  $90^\circ$  to  $\theta$ , so Work done

$$U = W = \int_{\pi/2}^{\theta} m B \sin \theta d\theta = -mB [\cos \theta]_{\pi/2}^{\theta} = -mB \cos \theta$$

This work will store as P.E.

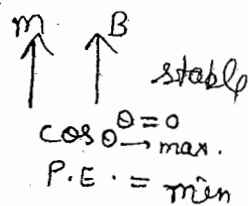
$$\boxed{U = -\vec{m} \cdot \vec{B}}$$

When  $\angle$  b/w  $\vec{m}$  &  $\vec{B}$  is  $0$  i.e.  $U = -mB$  then P.E. will be minimum.

This will be the stable configuration.

As torque rotate the plane then flux changes & it will induce electromagnetic field will do work.

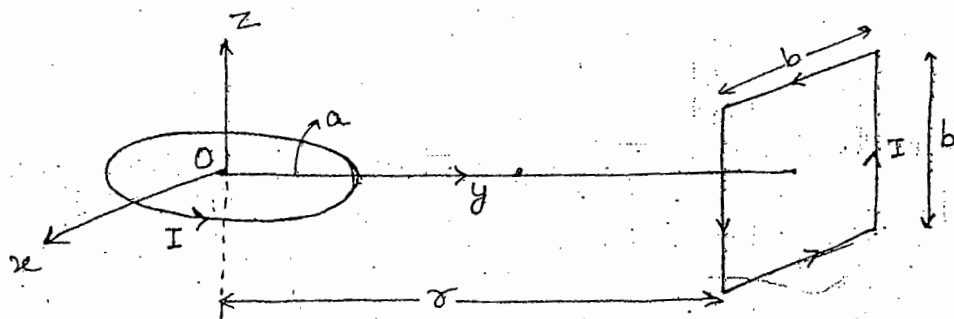
(Mag. force does not do work)



# Magnetic Dipole Interaction Energy :-

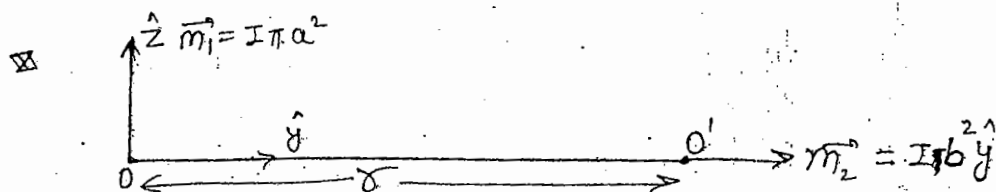
$$U = \frac{\mu_0}{4\pi r^3} [\vec{m}_1 \cdot \vec{m}_2 - 3(\vec{m}_1 \cdot \hat{r})(\vec{m}_2 \cdot \hat{r})]$$

Q. Calculate the torque & the interaction energy for 2 loops as shown in the figure.



When  $r > a, b$  then these 2 loops can be replaced by their mag. moment.

These 2 loops are equivalent to 2 dipoles.



Mag field of loop 2 applies a torque on loop 1.

$$\vec{N}_1 = \vec{m}_1 \times \vec{B}_2$$

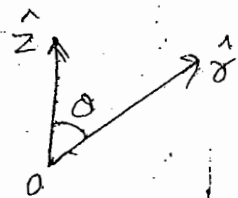
Magnetic field on loop (2) at a distance  $r$

$$\vec{B}_2 = \frac{\mu_0 m_2}{4\pi r^3} [2\cos\theta \hat{r} + \sin\theta \hat{\theta}]$$

$$\vec{B}_2 = \frac{\mu_0 m_2}{4\pi r^3} [-2\hat{r}(-\hat{y})]$$

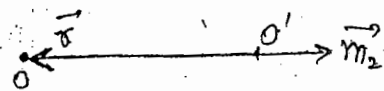
$$\vec{B}_2 = \frac{2\mu_0 m_2}{4\pi r^3} \hat{y}$$

$$\vec{B}_2 = \frac{2\mu_0 I b^2}{4\pi r^3} \hat{y}$$



$$\theta = 180^\circ$$

$$\hat{r} = -\hat{y}$$



$\hat{r}$  is always away from the origin.

On loop 2,  $\vec{N}_2 = \vec{m}_2 \times \vec{B}_1$

Torque  $\vec{N}_1 = \vec{m}_1 \times \vec{B}_2$

$$\vec{N}_1 = I \pi a^2 \frac{2 \mu_0 I b^2}{4 \pi r^3} (\hat{z} \times \hat{y})$$

$$\boxed{\vec{N}_1 = \frac{\mu_0 I^2 a^2 b^2}{2 r^3} (-\hat{x})}$$

Torque on loop 2,  $\vec{N}_2 = \vec{m}_2 \times \vec{B}_1$   
 $m_2 = I b^2 \hat{y}$

$$\vec{B}_1 = \frac{\mu_0 m_1}{4 \pi r^3} [2 \cos \theta \hat{r} + \sin \theta \hat{\theta}]$$

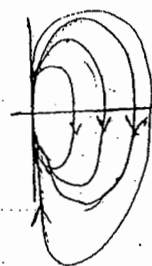
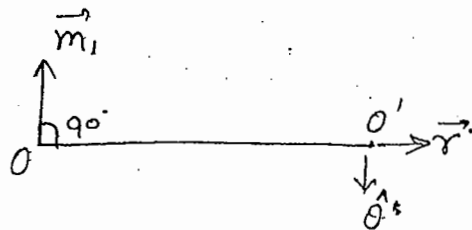
$$\vec{B}_1 = \frac{\mu_0 I \pi a^2}{4 \pi r^3} \hat{\theta}$$

$$\hat{\theta} = -\hat{z}$$

$$\vec{B}_1 = \frac{\mu_0 I \pi a^2}{4 \pi r^3} (-\hat{z})$$

$$\vec{N}_2 = \vec{m}_2 \times \vec{B}_1$$

$$\boxed{\vec{N}_2 = \frac{\mu_0 I^2 a^2 b^2}{4 r^3} (-\hat{x})}$$



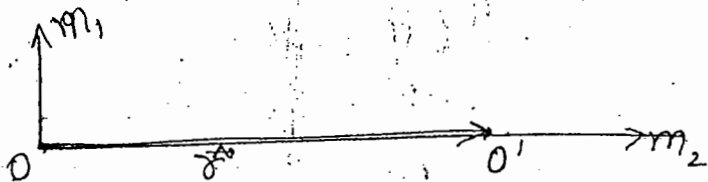
At equatorial line dir<sup>n</sup> of B is ↓ (this is  $\hat{\theta}$  dir<sup>n</sup>)

$$\{ \hat{y} \times (-\hat{z}) = -\hat{x} \}$$

### Interaction Energy :-

$$U = \frac{\mu_0}{4 \pi r^3} [ \vec{m}_1 \cdot \vec{m}_2 - 3(\vec{m}_1 \cdot \hat{r})(\vec{m}_2 \cdot \hat{r}) ]$$

Mutual angle b/w  $\vec{m}_1$  &  $\vec{m}_2$  is  $90^\circ$ .



$\vec{r}$  can be from O to O'  
 or can be from O' to O

$$(\vec{m}_1 \cdot \hat{r}) = 0$$

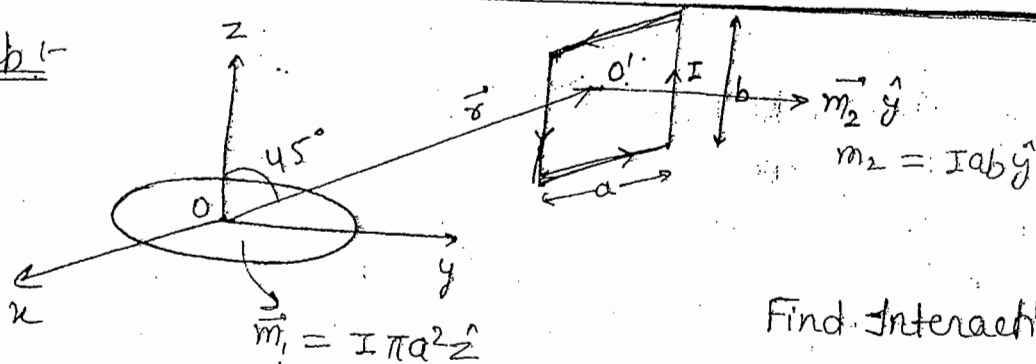
$$(\vec{m}_2 \cdot \hat{r}) \neq 0$$

$$\text{So } U = \frac{\mu_0}{4 \pi r^3} [ m_1 m_2 \cos 90^\circ - 3(0) \cdot 0 ]$$

$$\boxed{U = 0}$$



Prob 1-



Find Interaction Energy?

$$U = \frac{\mu_0}{4\pi r^3} [ \vec{m}_1 \cdot \vec{m}_2 - 3(\vec{m}_1 \cdot \hat{r})(\vec{m}_2 \cdot \hat{r}) ]$$

$$\vec{m}_1 \cdot \vec{m}_2 = m_1 m_2 \cos 90^\circ = 0$$

( $\angle$  b/w  $m_1$  &  $m_2 = 90^\circ$ )

$$\vec{m}_1 \cdot \hat{r} = m_1 \cos 45^\circ = \frac{m_1}{\sqrt{2}} = \frac{I \pi a^2}{\sqrt{2}}$$

$$\vec{m}_2 \cdot \hat{r} = m_2 \cos 45^\circ = \frac{m_2}{\sqrt{2}} = \frac{I a b}{\sqrt{2}}$$

$$\therefore U = \frac{\mu_0}{4\pi r^3} \left[ 0 - \frac{3\pi I^2 a^3 b}{2} \right]$$

$$U = -\frac{3\mu_0 I^2 a^3 b}{8\pi r^3} \Rightarrow U = -\frac{3\mu_0 I^2 a^3 b}{8\pi r^3}$$

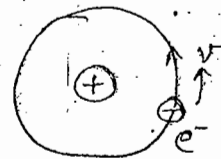
Bound Currents:- There are 2 types of currents:-

free currents - are due to motion of free charges.

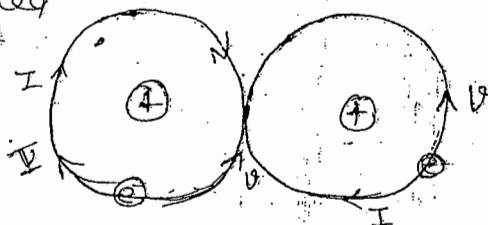
If inside the metal free charges are moving under pot<sup>n</sup> then current arises.

Bound currents - arises due to the motion of bound charges.

$e^-$  perform a orbital motion & this motion is equivalent to magnetic dipole. If a  $e^-$  is moving with velocity  $v$  around nuclei & correspond to a current. Now it'll act as a current dipole. It is the bound current.



If another atom is placed near this atom. The current b/w them cancel out & Net current will be on surface.



Then it is called Surface bound Current & if any atom is missing in b/w, there will be current Non-zero then net current will exist in volume. It is called Volume bound current.

$\vec{K}_b \rightarrow$  Surface bound current

$\vec{J}_b \rightarrow$  Volume bound current

As  $\vec{P}$  is polarisation i.e. dipole mom. per unit volume.  
Similarly in magnetostatic,

Magnetisation ( $M$ ) - Magnetic mom.  $\vec{m}$  per unit volume.

As  $\sigma_b = \vec{P} \cdot \hat{n}$ ,  $\rho_b \neq$

$\rho_b = -\nabla \cdot \vec{P}$

if  $P$  is uniform then  $\rho_b = 0$

$P$  is Non uniform then  $\rho_b \neq 0$

In Magnetostatics, Total current will be surface current if magnetisation is uniform.

If Magnetisation is

$$\vec{K}_b = \vec{M} \times \hat{n}$$

Non-uniform then  $K_b$  &  $J_b$  both

$K_b \rightarrow$  surface bound current

contribute, Volume bound current

$$\vec{J}_b = \nabla \times \vec{M}$$

Div of Curl is zero so

$$\nabla \cdot \vec{J}_b = 0$$

Ques An infinitely long circular cylinder carries a uniform magnetization  $M$  parallel to its axis. Find surface & volume bound current & also find mag. field inside & outside the cylinder.

$\vec{M}$  is uniform, not depending on space coordinate

No free current is present.

First find bound current, Using Ampere's law

$$I_{enc} = I_b + I_f$$

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

Vol. bound current,  $J_b = 0$  coz  $\vec{M}$  is uniform.

Surface bound Current,

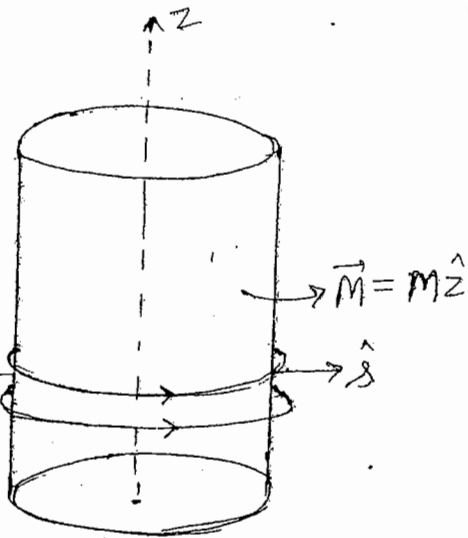
$$\vec{K}_b = \vec{M} \times \hat{n}$$

$\perp$  vector to  $\vec{M}$  will be  $\hat{s}$ .

$$\vec{K}_b = M (\hat{z} \times \hat{s})$$

$$\vec{K}_b = M \hat{\phi}$$

Magnetisation is like mag. field.  
 (arises from bound current)      (arises from current (bound as well as free))



$B \xrightarrow{\text{determines from}} I_b + I_f$

$M \rightarrow I_b$

$H \rightarrow I_f$  (free current)

mag. field intensity

Note :- Curl the fingers in the dir<sup>n</sup> of bound current, thumb will tell the dir<sup>n</sup> of Magnetisation.

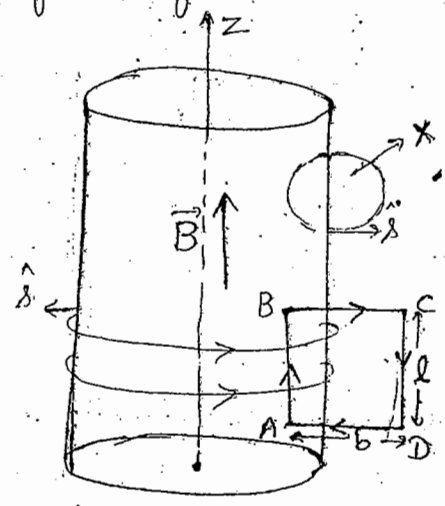
There is no free current so total current will be bound current.

It is like a solenoid. So to find the current of this infinitely long cylinder we must draw a Ampirical loop. Ampirical loop should be s.t. current passes through the loop. So loop should be  $\perp$  to the flow of current.

Take a rectangle as ampirical loop.

(If we take a ~~or~~ circular loop then  $d\ell$  will be different at each point of loop so  $B \cdot d\ell$  will be variable. So we can not take a circle as ampirical loop).

Dir<sup>n</sup> of loop will be according to the dir<sup>n</sup> of mag. field  $\vec{B}$ .



$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{enc}$$

$$\oint \vec{B} \cdot d\vec{\ell} = \int_{AB} \vec{B} \cdot d\vec{\ell} + \int_{BC} \vec{B} \cdot d\vec{\ell} + \int_{CD} \vec{B} \cdot d\vec{\ell} + \int_{DA} \vec{B} \cdot d\vec{\ell}$$

$\downarrow$   $\angle$  b/w them is  $90^\circ$   $\parallel$   $0$      
  $\downarrow$  out of cylinder No current  $\parallel$   $0$      
  $\downarrow$   $\angle$  b/w them is  $90^\circ$   $\parallel$   $0$

Note :- Bound Current can never be in the dir<sup>n</sup> of Magnetisation.

$$\oint \vec{B} \cdot d\vec{l} = \int_{AB} \vec{B} \cdot d\vec{l} = B l$$

$$\text{Surface current} = \frac{\text{Total current}}{\text{Length } l \text{ to the flow}} \Rightarrow \frac{I}{l} = M$$

$$I = M \cdot l$$

$$B l = \mu_0 M l$$

$$\boxed{\vec{B} = \mu_0 \vec{M} \hat{z}}$$

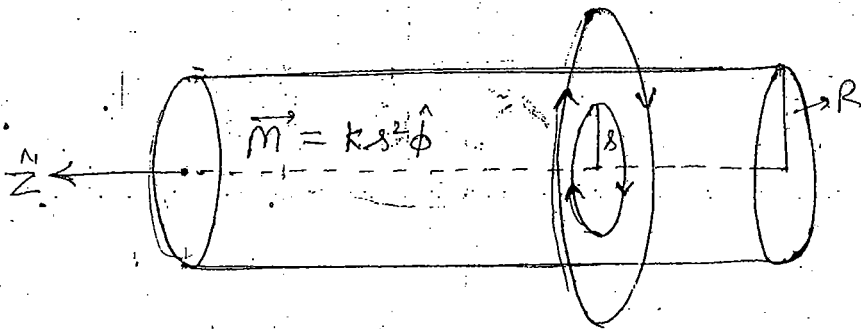
Mag. field through bound current, in terms of surface current (K) is

$$\boxed{B = \mu_0 K}$$

for n no. of loops,  $\vec{B} = \mu_0 n I$

$$\left. \begin{aligned} B &= \mu_0 \frac{n I}{\text{Total current / unit length}} \\ &\text{i.e. surface current} \end{aligned} \right\}$$

Ques: A long circular cylinder of radius R carries a magnetisation  $\vec{M} = k s^2 \hat{\phi}$  where k is the constant & s is the distance from the axis,  $\hat{\phi}$  is the azimuthal vector. Find the mag. field due to  $\vec{M}$  inside & outside the cylinder.



If  $\vec{M}$  is in the  $\hat{\phi}$  then bound current will be in  $\hat{z}$  &  $\hat{M}$  " "  $\hat{z}$  " " " "  $\hat{\phi}$ .

Vol. bound current,

$$\vec{J}_b = \nabla \times \vec{M}$$

$$= \frac{1}{s} \begin{vmatrix} \hat{s} & s \hat{\phi} & \hat{z} \\ \frac{\partial}{\partial s} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ M_s & s M_{\phi} & M_z \end{vmatrix}$$

$$= \frac{1}{s} \begin{vmatrix} \hat{s} & s \hat{\phi} & \hat{z} \\ \frac{\partial}{\partial s} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & s k s^2 & 0 \end{vmatrix}$$

$$(M_{\phi} = k s^2)$$

$$= \frac{1}{s} \hat{z} \left[ \frac{\partial}{\partial s} (K s^3) \right] = \frac{1}{s} K 3 s^2 \hat{z}$$

$$\vec{J}_b = 3K s \hat{z}$$

Surface bound current,

$$\vec{K}_b = \vec{M} \times \hat{n}$$

$$= K s^2 (\hat{\phi} \times \hat{s}) \Big|_{s=R}$$

$$= K R^2 (-\hat{z})$$

(unit vector normal to surface  $\Rightarrow \hat{n} = \hat{s}$ )

$$(\hat{\phi} \times \hat{s} = -\hat{z})$$

$$\vec{K}_b = -K R^2 \hat{z}$$

Surface bound current & vol. bound current are oppositely directed.

Magnetic field inside:-

Only volume bound current will contribute. Take a circular Amperical loop.

Current Enclose by the circular loop,

$$I_b(\vec{J}_b) = \int \vec{J}_b \cdot d\vec{S}_1$$

$$= \int_0^s \int_0^{2\pi} 3K s \, s \, ds \, d\phi$$

$$= 3K \frac{s^3}{3} \cdot 2\pi$$

$dS_1 = s \, ds \, d\phi$  (z is not changing)

$I_b(\vec{J}_b) = 2\pi K s^3$ . The Amperical loop will enclose this current.

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$B \cdot 2\pi s = 2\pi K s^3 \mu_0$$

$$\vec{B}_{in} = \mu_0 K s^2 \hat{\phi}$$

Magnetic field Outside :- both volume & surface bound currents will contribute.

$$\rightarrow I_b(\vec{J}_b) = \int_0^R \int_0^{2\pi} 3K s \, s \, ds \, d\phi$$

$$I_b(\vec{J}_b) = 2\pi K R^3$$

$$\rightarrow I_b(\vec{K}_b) = K_b \times \perp \text{ length}$$

$$= -K R^2 2\pi R \hat{z} \Rightarrow I_b(\vec{K}_b) = -2\pi K R^3$$

$$\text{Total bound current} = 2\pi KR^3 - 2\pi KR^3$$

$$\boxed{I_b(\text{Total}) = 0}$$

$$\text{So } \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}}$$

$$\Rightarrow \boxed{B_{\text{out}} = 0}$$

So Mag field outside

## Ampere's law in Magnetised Material :- The

division of materials is based on how they respond to external ~~field~~ magnetic field.

If a material is placed in mag field & there is no change in its property then this material is called Non-magnetic material.

Because Every magnetic material respond to mag field i.e. On placing it in mag field its properties changes.

$$\nabla \times \vec{B} = \mu_0 \vec{J}$$

$$\text{Total } \vec{J} = \vec{J}_b + \vec{J}_f$$

$$\therefore \nabla \times \vec{B} = \mu_0 (\vec{J}_b + \vec{J}_f)$$

$$\Rightarrow \frac{1}{\mu_0} (\nabla \times \vec{B}) = \nabla \times \vec{M} + \vec{J}_f$$

$$\nabla \times \left( \frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_f$$

$$\boxed{\nabla \times \vec{H} = \vec{J}_f}$$

$$\begin{cases} \frac{B}{\mu_0} - M = H \\ B = \mu_0 (M + H) \end{cases}$$

This is the differential form of Ampere's law in magnetisation material,

$H \rightarrow$  Magnetic field intensity

Its M.K.S. unit  $\rightarrow$  A/m {ampere/meter}

$\vec{J}_f \rightarrow$  free current density

Now, Take surface integral of both the sides,

$$\int_S (\nabla \times \mathbf{H}) \cdot d\mathbf{s} = \int_S \mathbf{J} \cdot d\mathbf{s}$$

$$\oint \mathbf{H} \cdot d\mathbf{l} = I_{f \text{ enc.}} \rightarrow \text{Integral form}$$

In Magnetostatics  $\rightarrow$   $\mathbf{H}$ , determined only by the free current. It includes bound current in itself. Similar as  $\mathbf{D}$  in electrostatics.

Ques - In previous Question,  $M = K s^2 \hat{\phi}$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$$\left. \begin{array}{l} \vec{H}_{in} = 0 \\ \vec{H}_{out} = 0 \end{array} \right\} \text{ because there is no free current inside} \\ \text{ \& outside. (only bound current)}$$

so  $\vec{B}_{in} = \mu_0 \vec{M}_{in}$

$$\vec{B}_{in} = \mu_0 K s^2 \hat{\phi}$$

$$\vec{B}_{out} = \mu_0 \vec{M}_{out} = \mu_0 \times 0$$

$$\vec{B}_{out} = 0$$

$$\vec{B} = \mu \vec{H}$$

$\mu \rightarrow$  permeability of the medium.

Permeability - It is defined as

Relative permeability  $\mu_r = \frac{\mu}{\mu_0}$  as  $\epsilon_r = \frac{\epsilon}{\epsilon_0}$

$\mu_r$  decide, the type of material.  
 $\mu_0 \rightarrow$  permeability in free space.

for Diamagnetic Material,  $\mu_r < 1$

Paramag. "  $\mu_r > 1$

ferromag. "  $\mu_r \gg 1$ .

Physical Meaning - If we have a hollow cylinder, wrapped <sup>conducting</sup> wires over it. Current flow is constant. It'll become a solenoid. Current flowing in conductor is free current. Mag. field intensity  $\mathbf{H}$  inside will be Non-zero.

It is hollow before. Now if we place a iron rod inside it then, (Iron is ferromag. material)

$\vec{H} \parallel$  → No change bcoz it totally determine by free current  
 &  $\vec{B}$  increases bcoz of bound current

In free space  $\vec{B} = \mu_0 \vec{H}$

If we place a rod then The magnetisation will be in the dir<sup>n</sup> of mag field then

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$$\vec{B} = \mu \vec{H} \Rightarrow B = \mu_r \mu_0 H$$

⇒ If  $\mu_r < 1$  then  $B \uparrow$   
 $\mu_r > 1$  then  $B \uparrow$  or  $B \downarrow$  depending upon material  
 while  $\vec{E} \downarrow$

⇒ Polarisation is always in the dir<sup>n</sup> of external E-field

$$E_{ext} \uparrow - P \uparrow$$

But for a mag. material

We have a dia mag. material & apply H then

$$H_{ext} \uparrow \quad M \downarrow$$

for para mag.  $H_{ext} \uparrow \quad M \uparrow$

### Magnetic Susceptibility

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$$\chi_m = \frac{M}{H} \quad \Rightarrow \quad \mu H = \mu_0 (H + \chi_m H)$$

$$\frac{\mu}{\mu_0} = 1 + \chi_m$$

$$\boxed{\mu_r = 1 + \chi_m}$$

$$\epsilon_r = 1 + \chi_e$$

$\epsilon_r > 1$  always but  $\mu_r > 1$  or maybe  $\mu_r < 1$

$\mu_r < 1$  i.e.  $\chi_m < 0$  then Dia mag. material.

$\mu_r \geq 1$  i.e.  $\chi_m > 0$  " Para " "



If Magnetisation is proportional to first power of  $H$ , then these types of materials are called Linear Magnetic Materials. i.e.  $M \propto H$

definition of susceptibility  $\chi_m = \frac{M}{H}$  is true <sup>only</sup> for linear mag. material

Dia, para are linear mag. material but ferro mag. material is not linear.

$$\chi_m \neq \frac{M}{H} \quad (\text{for ferro})$$

for ferro mag. material  $\chi_m = \frac{\partial M}{\partial H}$

for ex 1 -  $M = \tanh\left(\frac{\mu H}{KT}\right)$

$M$  is not linearly depending on  $H$ , bcoz  $\tanh x \approx x$  only for small value of  $x$ . [i.e.  $x < 1$ ]

It is ferro mag. material.

Ques:- A long Copper rod of radius  $R$  carries a uniformly distributed free current  $I$ . find the  $H$  inside & outside the rod.

Current  $I = J \times (\text{Area})$

$$I = J \pi R^2$$

$$J = \frac{I}{\pi R^2}$$

Inside :-  $\pi R^2$

$$I_{enc} = \int \vec{J} \cdot d\vec{S} = J \cdot \text{area} \quad (J \text{ is uniform})$$

$$= \frac{I}{\pi R^2} \pi s^2$$

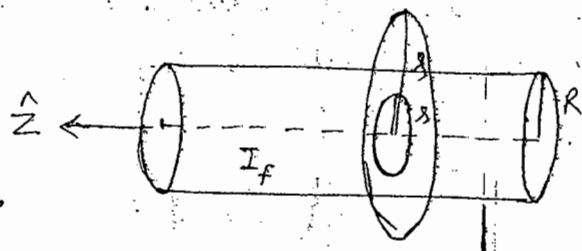
$$I_{enc} = \frac{I s^2}{R^2}$$

$$\oint \vec{H} \cdot d\vec{l} = I_{f \text{ enc}}$$

$$H \cdot 2\pi s = \frac{I s^2}{R^2}$$

$$\Rightarrow \vec{H} = \frac{I s}{2\pi R^2} \hat{\phi}$$

dir<sup>n</sup> of  $H$  is same as  $B$ .



So  $H_{in} \propto I$

Outside 1-  $I_{enc} = I$

$$H \cdot 2\pi s = I$$

$$\vec{H} = \frac{I}{2\pi s} \hat{\phi}$$

If permeability of that medium is  $\mu$  then mag field will be  $B = \mu H \Rightarrow$

$$\vec{B}_{in} = \frac{\mu I s}{2\pi R^2} \hat{\phi}$$

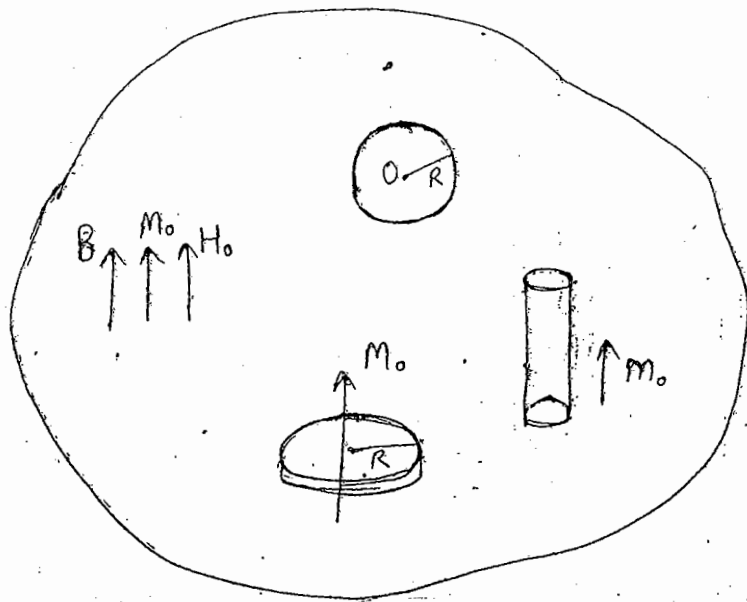
(but can't determine  $B_{in}$  here bcoz  $\mu$  is not given)  
We can determine  $B_{out}$  bcoz outside permeability is  $\mu_0$

So 
$$\vec{B}_{out} = \frac{\mu_0 I}{2\pi s} \hat{\phi}$$

Ques\* - A infinitely long cylinder of radius  $R$  carries a magnetisation  $\vec{M} = k s \hat{z}$  parallel to its axis where  $s$  is the distance from the axis of the cylinder. There is no free charge anywhere. Find surface & volume bound currents. Also find mag field inside & outside the cylinder by using 2 different methods  $\rightarrow$  (i) by bound currents & (ii) by  $H$ .

Ques - Suppose the field inside a large piece of magnetic material is  $\forall B_0$  such that  $H_0 = \frac{B_0}{\mu_0} - M$ .

- Now a small spherical cavity is hollowed out of the material, find the mag field at the centre of the cavity
- Do the same for a long needle shaped cavity parallel to  $M$ .
- Do the same for a <sup>wafers</sup> wafer shaped cavity  $\perp$  to  $\vec{M}$ .

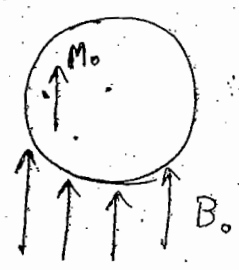


When  $B$  &  $M$  are in same dir<sup>n</sup> then mag. field inside the material will decrease - (Para & ferro mag. material.  $B$  &  $M$  are in same dir<sup>n</sup> but in dia dir<sup>n</sup> of  $B$  &  $M$  are opposite)

Sphere In free space of material sphere

$$\vec{B} = \vec{B}_0 - \frac{2}{3} \mu_0 \vec{M}_0 \quad \text{ie. } B_{in} = \frac{2}{3} \mu_0 \vec{M}_0$$

This is the mag. field of uniformly magnetised sphere,



$B_{in} = \frac{2}{3} \mu_0 \vec{M}_0$  (Vol. current in + = surface current in)

$E_{in} = -\frac{1}{3} \frac{P_0}{\epsilon_0}$



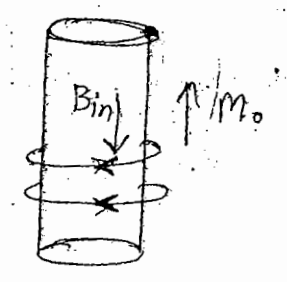
also Mag. field inside the spherical cavity

$$\vec{B}_0 - \frac{2}{3} \mu_0 \vec{M}_0$$

Middle shape :-

$$\vec{B} = \vec{B}_0 + \vec{B}_{in}$$

In free space, Magnetisation = 0  
 Outside Magnetisation  $M_0$  then we have to place  $-M$  mag. inside the cavity to make the total mag. zero. (Magnetisation  $\rightarrow$  by superposition)



Mag. field inside the cavity :-

$$\vec{B}_{in} = \vec{B}_0 - \mu_0 \vec{M}_0$$

{ If Thumb  $\rightarrow \vec{B}_0$   
 fingers tell the dir<sup>n</sup> of current

- \* If the length of rod is long  $\rightarrow$  more effect of surface current (in magnetostatics)
- if length of rod is long (in electrostatic)  $\rightarrow$  surface charges are far apart & effect will be less.

Disc (Wafer shape)  $\rightarrow$  current will flow on the surface of disc  $\rightarrow$  Total current = surface current  $\times$   $\perp$  length

In disc, amount of bound charge is very less bcoz  $\perp$  length  $\rightarrow$  so bound current  $\rightarrow 0$ , Mag. field  $\left. \begin{array}{l} \vec{B} = \vec{B}_0 \\ \left\{ E = E_0 + \frac{\rho}{\epsilon} \right\} \end{array} \right\}$

In case of disc, induced mag. field = 0 bcoz length is very small,  $\vec{B}_{in} = 0$

so total mag. field  $\boxed{\vec{B} = \vec{B}_0}$

Ques \*  $\vec{M} = K_s \hat{z}$

Volume bound current

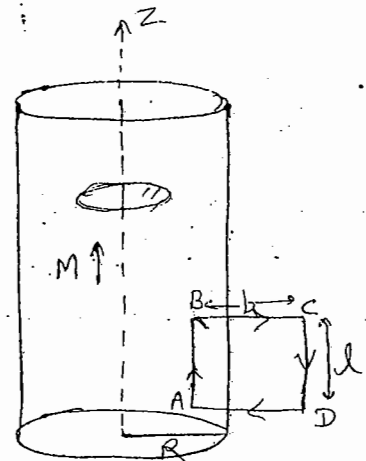
$$\begin{aligned} \vec{J}_b &= \nabla \times \vec{M} \\ &= \frac{1}{s} \begin{vmatrix} \hat{s} & s\hat{\phi} & \hat{z} \\ \frac{\partial}{\partial s} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & 0 & K_s \end{vmatrix} \\ &= -\frac{1}{s} s\hat{\phi} \frac{\partial}{\partial s} (K_s) \end{aligned}$$

$$\boxed{\vec{J}_b = -K \hat{\phi}}$$

Surface bound current

$$\begin{aligned} \vec{K}_b &= \vec{M} \times \hat{n} \\ &= K_s (\hat{z} \times \hat{s}) = K_s \hat{\phi} \end{aligned}$$

$$\boxed{\vec{K}_b = K_s \hat{\phi}} \Rightarrow \boxed{\vec{K}_b = KR \hat{\phi}}$$



$\int ds \cdot dz$

Magnetic field inside by bound current

$$I_b(\vec{J}_b) = \int \vec{J}_b \cdot d\vec{S}_1 = \int_0^l \int_0^{2\pi} -K ds dz = -K s dz$$

$$\oint B \cdot dl = \int_{AB} B \cdot dl + \int_{BC} B \cdot dl + \int_{CA} B \cdot dl + \int_{DA} B \cdot dl$$

$$= B l + 0 + 0 + 0 = B l$$

$$\text{So } \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$B \cdot l = \mu_0 (+K s l)$$

$$\boxed{B = +\mu_0 K s \hat{z}}$$

by H, There is no free charge.  $\therefore \vec{H}_{in} = 0$

$$\vec{B}_{in} = \mu_0 (\vec{H}_{in} + \vec{M}_{in})$$

$$\vec{B}_{in} = \mu_0 (0 + K s \hat{z})$$

$$\boxed{\vec{B}_{in} = \mu_0 K s \hat{z}}$$

Magnetic field outside by bound current,

$$I_b(\vec{r}_b) = \int_0^R \int_0^l -K s ds dz = -K R l$$

$$I_b(\vec{K}_b) = K_b \times l_{\perp} = K R \times l = K R l$$

$$I_{enc} = 0$$

$$\text{So } \boxed{B_{out} = 0}$$

By H,  $H_{out} = 0$

$$\text{so } B_{out} = \mu_0 M_{out}$$

$$B_{out} = \mu_0 \times 0 \Rightarrow \boxed{B_{out} = 0}$$

## Boundary Conditions on $\vec{H}$ :-

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow B_{\text{above}}^{\perp} = B_{\text{below}}^{\perp}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \Rightarrow B_{\text{above}}^{\parallel} - B_{\text{below}}^{\parallel} = \mu_0 K$$

Tangential comp. of mag. field is discontinuous by the amount  $\mu_0 K$ .

$$\vec{\nabla} \cdot \vec{H} = -\vec{\nabla} \cdot \vec{M}$$

$$H_{\text{above}}^{\perp} - H_{\text{below}}^{\perp} = M_{\text{below}}^{\perp} - M_{\text{above}}^{\perp}$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \mu_0 \vec{\nabla} \cdot (\vec{H} + \vec{M}) = 0$$

$$\vec{\nabla} \cdot \vec{H} = -\vec{\nabla} \cdot \vec{M}$$

$\vec{\nabla} \cdot \vec{H}$  can be 0 only if  $\vec{H}$  is not uniform.

$$\vec{\nabla} \times \vec{H} = \vec{J}_f \quad J_f \rightarrow \text{free vol. charge density}$$

$$H_{\text{above}}^{\parallel} - H_{\text{below}}^{\parallel} = K_f$$

Tangential comp. of  $H$  is discontinuous by the amount  $K_f$  (free current)

If there exist a boundary whose permeability are different (i.e. mag. properties are different) for such a boundary

①	$\mu_1$
dielectric	②
	$\mu_2$

$$K_f = 0$$

then tangential comp. of  $H$  i.e.  $H_{\text{above}}^{\parallel} = H_{\text{below}}^{\parallel} = 0$

Ques :- At the interface b/w two linear magnetic materials the mag. field lines bend. Show that

$$\frac{\tan \theta_2}{\tan \theta_1} = \frac{\mu_2}{\mu_1}$$

Assuming that, there is no free current at the boundary.

If no free current then boundary cond<sup>n</sup>s are  $H^{\parallel}$  &  $B^{\perp}$  are continuous.

$B^{\perp} \rightarrow$  always continuous

$H^{\parallel} \rightarrow$  conditionally "

i.e. B.C.s are  $H_1^{\parallel} = H_2^{\parallel}$

$$B_1^{\perp} = B_2^{\perp}$$

$$B_1'' = \mu_1 H_1''$$

$$B_2'' = \mu_2 H_2''$$

Now  $B_1^\perp = B_2^\perp$

$$\Rightarrow B_1 \cos \theta_1 = B_2 \cos \theta_2 \quad (1)$$

$$\& H_1'' = H_2''$$

$$\Rightarrow H_1 \sin \theta_1 = H_2 \sin \theta_2$$

$$\Rightarrow \frac{B_1 \sin \theta_1}{\mu_1} = \frac{B_2 \sin \theta_2}{\mu_2} \quad (2)$$

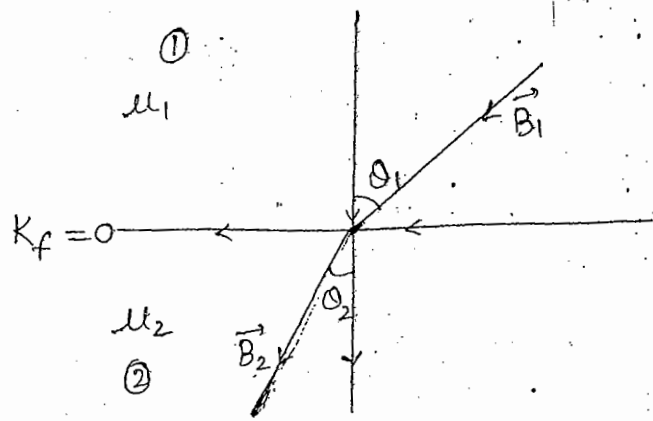
Dividing (2) by (1)  $\Rightarrow$

$$\frac{B_1}{\mu_1} / B_1 \tan \theta_1 = \frac{B_2}{\mu_2} / B_2 \tan \theta_2$$

$$\frac{1}{\mu_1} \tan \theta_1 = \frac{1}{\mu_2} \tan \theta_2$$

$$\Rightarrow \frac{\tan \theta_2}{\tan \theta_1} = \frac{\mu_2}{\mu_1} = \frac{\epsilon_2}{\epsilon_1} \quad (\text{for electric lines})$$

for magnetic lines.



Ques 1:- Given  $\mu_r = 2$  in region (1)  
 $\mu_r = 1$  in region (2)

Apply a mag. field which is tilted by some angle &  $H_2$  exist in region (2)

$$\vec{H}_2 = 2\hat{x} - 2\hat{y} + 6\hat{z}$$

Find (i)  $\vec{B}_1$  (ii)  $\vec{H}_1$

No free current at the surface i.e.  $K_f = 0$

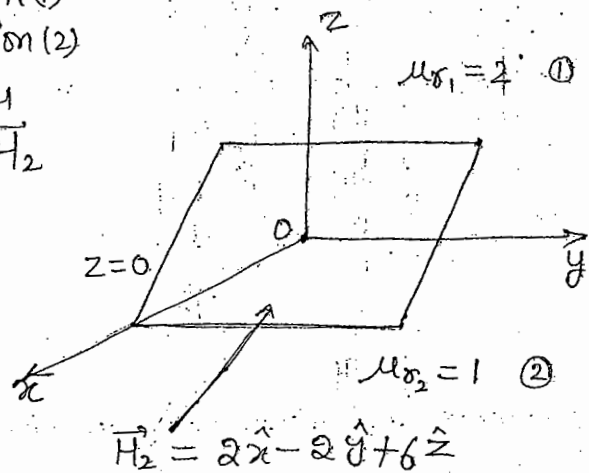
If  $K_f = 0$  then B.C. are

$$H_1'' = H_2'' \quad \& \quad B_1^\perp = B_2^\perp$$

$$H_2 = 2\hat{x} - 2\hat{y} + 6\hat{z}$$

$$\Rightarrow H_{2n} = 6\hat{z} \quad \& \quad H_{2t} = 2\hat{x} - 2\hat{y}$$

$$B_1^\perp = B_2^\perp \Rightarrow B_{1n} = B_{2n} \Rightarrow B_{1n}$$



$$\textcircled{1} \quad [H_1'' = H_2''] \Rightarrow H_{1t} = H_{2t} = 2\hat{x} - 2\hat{y} = H_1''$$

$$B_1^\perp = B_2^\perp \Rightarrow B_{1n} = B_{2n}$$

$$\mu_1 H_{1n} = \mu_2 B_{2n} \quad \text{---} \textcircled{2}$$

$$B_2^\perp = \mu_2 H_2^\perp \quad \text{---} \textcircled{3}$$

$$= \mu_0 \mu_{r_2} H_2^\perp$$

$$B_2^\perp = \boxed{6 \mu_0 \hat{z}} = B_1^\perp$$

$$B_1^\perp = \mu_1 H_1^\perp = \mu_0 2 H_1^\perp \Rightarrow H_1^\perp = 3\hat{z}$$

$$\text{So } \vec{H}_1 = H_1'' + H_1^\perp$$

$$\boxed{\vec{H}_1 = 2\hat{x} - 2\hat{y} + 3\hat{z}}$$

$$\textcircled{1} \Rightarrow \frac{B_1''}{\mu_1} = H_2'' = H_1''$$

$$\frac{B_1''}{\mu_0 \mu_{r_1}} = H_2''$$

$$B_1'' = 2 \mu_0 H_2''$$

$$B_1'' = \mu_0 (4\hat{x} - 4\hat{y})$$

$$\boxed{\vec{B}_1 = \mu_0 (4\hat{x} - 4\hat{y} + 6\hat{z})}$$

Note :-

$$\vec{B}_1 = \mu_1 \vec{H}_1$$

$$= \mu_0 \mu_{r_1} \vec{H}_1$$

$$\vec{B}_1 = \mu_0 (4\hat{x} - 4\hat{y} + 6\hat{z})$$

Ques  $\textcircled{1}$  A long wire has a circular cross-section with radius  $a$  the current density in the wire is  $J(r) = J_0 \left( \frac{a^2 - r^2}{a^2} \right)$  where  $r$  is the distance from

the axis. Calculate :-

(i) Total current in the wire

(ii) Mag. field inside & outside the wire

#



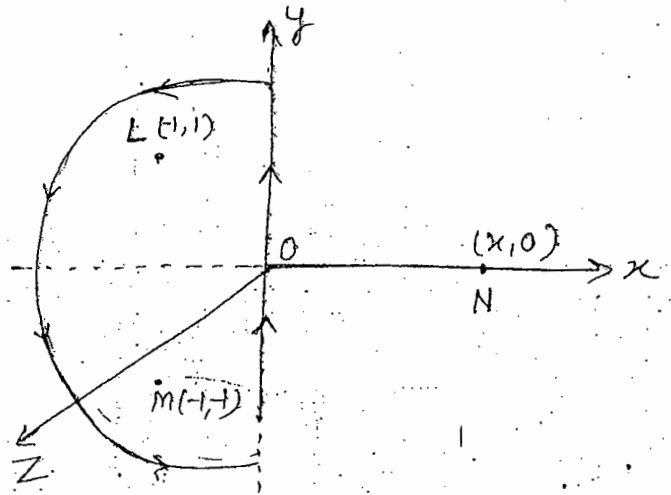
Q.2.1- Consider 2 infinitely long wires parallel to z-axis carrying the same current  $I$ . One of the wires passes through the point L with co-ordinates  $(-1, 1)$  and the other through point M with co-ordinates  $(-1, -1)$  in the x-y plane as shown in the figure. The dir<sup>n</sup> of the current in both the wires is in +ve z-dir<sup>n</sup>.

Find:

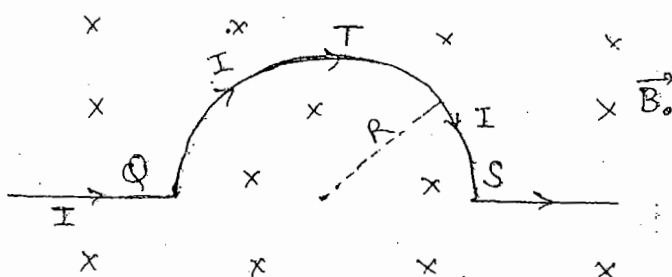
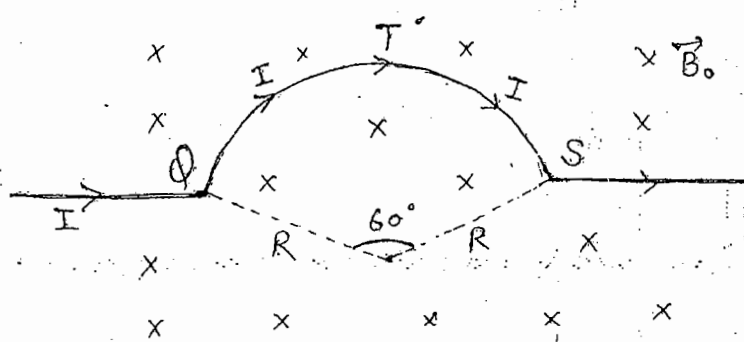
(i) the value of  $\oint \vec{B} \cdot d\vec{l}$  for a loop shown in the figure.

(ii) A 3rd long wire carrying current  $I$  also perpendicular to the x-y plane is placed at the point N with co-ordinate  $(x, 0)$  s.t. mag. field at the origin is doubled.

Find the value of  $x$  & dir<sup>n</sup> of the current in 3rd wire.



Q.2.2:- A circular Arc QTS is kept in an external magnetic field  $\vec{B}_0$  as shown in the figure. The arc carries a current  $I$ . Find the force on the arc.



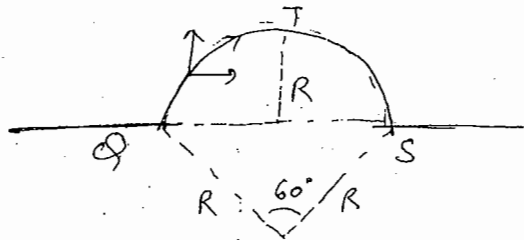
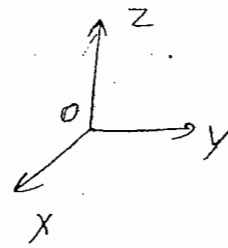
mag. field  $\rightarrow$  into the page

Q.3:- (i)  $d\vec{l}_1 = dy\hat{y} + dz\hat{z}$   
 $d\vec{l}_2 = dy\hat{y} + (-dz\hat{z})$   
 $d\vec{l}_1 + d\vec{l}_2 = 2dy\hat{y}$

$$\vec{F} = I \int d\vec{l} \times \vec{B}$$

$$= I 2B \int_0^{R/2} dy \hat{z}$$

$$\boxed{\vec{F} = I B R \hat{z}}$$



(ii)  $\vec{F} = I \int d\vec{l} \times \vec{B}$   
 $= I 2B \int^R dy \hat{z}$

$$\boxed{\vec{F} = 2 I B R \hat{z}}$$

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# Electrodynamics

In Electrodynamics,  
changing electric & magnetic field with time.

Now, the fields are time variable.

Static mag. field is produced by steady current.  
" electric " " " " charge at rest.

Steady Current - charges are not accumulating anywhere.

If current  $I$  is the fun<sup>n</sup> of time then Magnetic field will also be the fun<sup>n</sup> of time.

$$I(t) \rightarrow B(t)$$

& If Mag. field is time dependent then Mag. field & elec. field are dependent on each other.

Time dependent mag. field can produce time dependent Elec. field  
" " Elec. " " " " " Mag. "

$$I(t) \rightarrow B(t) \rightarrow E(t)$$

## Electromotive force (emf) :-

Electromotive force is work done per unit charge.  
emf is denoted by  $\mathcal{E}$ ,

$$\mathcal{E} = -\int \vec{E} \cdot d\vec{l}$$

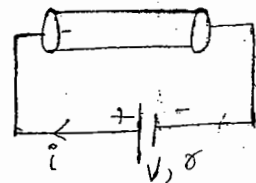
$\vec{F} \cdot d\vec{l}$  is work done per unit charge

$\vec{E} \cdot d\vec{l}$  Work done per unit charge

If we have a wire connected to battery then it is conducting & battery supply the force then free charge in wire are in motion & produce work. This work is done by battery. This work done is emf,

If battery pot<sup>n</sup> is  $V - iR$

Internal resistance is  $r$



then By Battery do work by this pot<sup>n</sup>  $V - iR$ . So emf or work done per unit charge is  $\Rightarrow$  emf  $\mathcal{E} = V - iR$

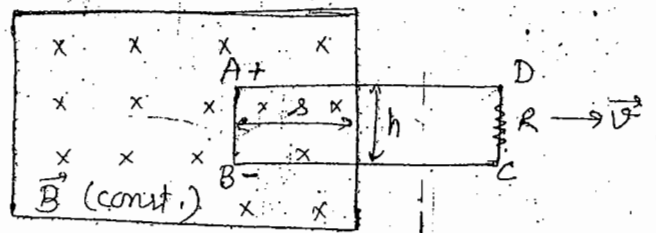
### Motional Electromotive force (emf) :-

Generators uses motional emf concept to generate power. This type of emf arises when a conducting loop moves in a constant mag. field i.e.  $\vec{B}$  remains constant with time.

Let us consider a wooden block, in this we have a closed loop. A resistance is connected with loop.

If someone is pulling the loop then mag. flux changes.

Mag. flux passes through a closed surface is always zero.



$$\Phi_m = \int_s \vec{B} \cdot d\vec{s}$$

$$\left\{ \Phi_m = \oint \vec{B} \cdot d\vec{s} = 0 \right.$$

$$\mathcal{E} = - \frac{d\Phi_m}{dt}$$

This is closed loop but open surface bcoz closed surface bound some volume.

It works on Faraday's law.

Acc. to Faraday law,

changing flux always induces the emf & dir<sup>n</sup> of emf is s.t. it oppose the change.

If flux is  $\uparrow$  then dir<sup>n</sup> of emf is s.t. try to  $\downarrow$  it. i.e. we take -ve sign.

i.e.

$$\boxed{\mathcal{E} = - \frac{d\Phi_m}{dt}}$$

$\rightarrow$  Faraday's law

$\Rightarrow$  Change in flux can be of 3 types

(i) either change  $\vec{B}$ , or (ii) change area  $ds$  or (iii) change the angle b/w  $\vec{B}$  &  $d\vec{s}$ .

$$\Phi_m = \int_s B ds \cos \theta$$

In case of Motional emf,

$B$  is always constant.

So flux can be changed due to either by changing area or by change angle b/w them.

If we pull the loop out then  $s$  will vary so area will change.

To find motional emf, we use formula,

$$\mathcal{E} = \oint \vec{f}_{\text{mag}} \cdot d\vec{l}$$

$\vec{f}_{\text{mag}} \rightarrow$  Magnetic force per unit charge.

$\Rightarrow$  In the present case, when loop is pulled with vel.  $\vec{v}$  then amount of emf = ? Current in resistance & dir = ?

If a charge is moving with vel.  $\vec{v}$  in mag. field  $\vec{B}$  then force on charge

$$\vec{f}_{\text{mag}} = \vec{v} \times \vec{B} \quad \text{if charge is +ve}$$

$$f_{\text{mag}} = \vec{B} \times \vec{v} \quad \text{if " " -ve}$$

Here Consider charge is +ve. For +ve charge the dir<sup>n</sup> of  $\vec{f}_{\text{mag}}$  will be upward.

& force on  $e^-$  will be downward.

A  $\rightarrow$  +ve

B  $\rightarrow$  -ve

Current will flow due to motion of charges.

Now part AB will behave like a battery. & Current will flow from +ve to -ve terminal. i.e. A  $\rightarrow$  B.

If AB is perfect conducting wire then its resistance = 0.

Hence AB part of loop is only contributing to the emf.

$$\begin{aligned} \mathcal{E} &= \int \vec{f}_{\text{mag}} \cdot d\vec{l} \\ &= v B \int dl \end{aligned}$$

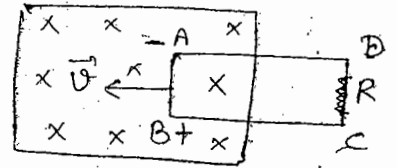
$$V = \mathcal{E} = v B h$$

& current  $V = i R \Rightarrow i = \frac{V}{R}$

$$i = \frac{v B h}{R}$$

& dir<sup>n</sup> of flow is from D → C

- If loop is pulling in opposite dir<sup>n</sup> force on +ve charge downward  
" " e<sup>-</sup> upward,



then A → -ve & B → +ve

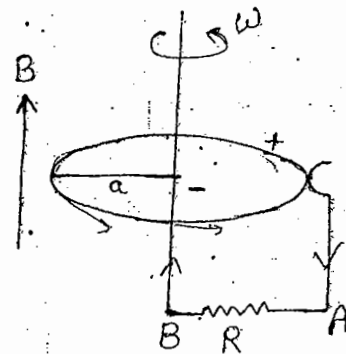
& Now current will flow from C → D.

Ques:- A metal disc of radius 'a' rotates with angular velocity  $\omega$  about vertical axis through a uniform mag field  $\vec{B}$  pointing in the upward dir<sup>n</sup>. A circuit is made by connecting one end of the resistor to the axle & other two to the sliding contact which touches the outer edge of the disc. Find the current in the resistor with dir<sup>n</sup>.

If charges are not in motion then no change in flux & there will be No emf.

Emf induces due to motion of charges.

In present case due to the motion of charges, their area is changing bcoz disc is rotating & charges are displacing from their position.



$$\vec{\omega} = \omega \hat{z}$$

$$\vec{v} = \vec{\omega} \times \vec{r} = \omega r (\hat{z} \times \hat{r})$$

$$\vec{v} = \omega r \hat{\phi}$$

$\vec{r}$  → radius vector of the disc having dir<sup>n</sup>  $\hat{r}$ .

for charges on the circumference the speed  $v$  is constant (same)  
but for all other charges speed is different.

force per unit charge,

$$\begin{aligned}\vec{f}_{\text{mag}} &= \vec{v} \times \vec{B} \\ &= \omega r \hat{\phi} \times B \hat{z} \\ &= \omega r B (\hat{\phi} \times \hat{z})\end{aligned}$$

$$\boxed{\vec{f}_{\text{mag}} = \omega r B \hat{r}}$$

Bcoz of this force, charges move towards outer edge  
so outer edge become +ve terminal of battery +  
centre " " -ve " "

$$\mathcal{E} = \int_0^a \omega B r dr$$

$$\boxed{\mathcal{E} = \frac{\omega B a^2}{2}}$$

The Current flow,  $I = \frac{\mathcal{E}}{R}$

$$I = \frac{\omega B a^2}{2R}$$

Dir<sup>n</sup> of the current will be  $A \rightarrow B$

- If disc rotate oppositely then dir<sup>n</sup> of  $v$  will be opposite & dir<sup>n</sup> of force opposite & then +ve charge on centre & -ve on surface so terminal changes.
- The Current flow on External Circuit is from +ve to -ve terminal.

Ques 1 - A metal bar of mass  $m$  slides frictionlessly on two parallel conducting rails. A distance  $l$  apart a resistor  $R$  is connected across the rails & a uniform mag. field  $\vec{B}$  is pointing into the page.

- find dir<sup>n</sup> & magnitude of the current in the resistor.
- Magnetic force on the metal bar with dir<sup>n</sup>.
- If  $v_0$  is the speed at  $t=0$  time, find the speed at later time  $t$  of the conducting bar.

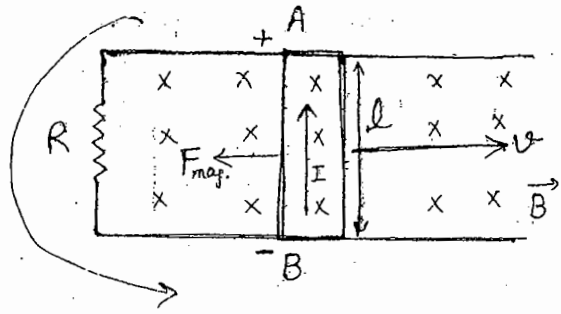


(A)

For +ve charges push upward  
-ve " " down

So A → +ve  
B → -ve

Current will flow towards  
resistance, as this is open  
circuit from one side.



$$\text{emf, } \mathcal{E} = \int \vec{F}_{\text{mag}} \cdot d\vec{l}$$

$$\mathcal{E} = vBl$$

$$\text{Current } I = \frac{\mathcal{E}}{R} \Rightarrow I = \frac{vBl}{R}$$

dir<sup>n</sup> → downwards

Inside the rod, current from B → A

Metal Bar does not have any resistance. So total resistance  
is R on whole circuit.

(B) If a wire of length l & current flowing in it is I  
then Magnetic force will be

$$\begin{aligned} \vec{F}_{\text{mag}} &= I \int d\vec{l} \times \vec{B} \\ &= \frac{vBl}{R} \cdot lB \end{aligned}$$

$$\vec{F}_{\text{mag}} = \frac{vB^2l^2}{R}$$

dir<sup>n</sup> → to the left

(C) Bar is moving in dir<sup>n</sup> →

&  $\vec{F}_{\text{mag}}$  is in dir<sup>n</sup> ←

Both will try to stop the bar.

If m be the mass of bar & v be the vel.  
then mechanical force

$$m \frac{dv}{dt} = - \frac{vB^2l^2}{R} \Rightarrow \frac{dv}{dt} = - \frac{vB^2l^2}{mR}$$

$$\frac{dv}{v} = - \frac{B^2l^2}{mR} dt$$

$$\ln v = -\frac{B^2 l^2}{Rm} t + C$$

At  $t=0$ ,  $v=v_0$

$$\ln\left(\frac{v}{v_0}\right) = -\frac{B^2 l^2}{Rm} t$$

$$v = v_0 e^{-\frac{B^2 l^2}{Rm} t}$$

velocity is exponentially ↓ with time,  
As  $B \uparrow$ , the decrease in  $v$  will be more.

Que:- A square loop of wire of side 'a' lies on a table at a distance  $s$  from a very long straight wire which carries a current  $I$ . If someone pulls the loop away from the wire at speed  $v$  what is the induced emf in the loop. Also find the dir<sup>n</sup> of induced current.

Square loop is pulled upward dir<sup>n</sup>.

Flux passes through the square loop

$$\phi_m = \int B \cdot ds$$

$B \rightarrow$  mag. field of wire  
 $ds \rightarrow$  area of loop

Mag. field of a wire is

$$B = \frac{\mu_0 I}{2\pi s} \hat{\phi}$$

dir<sup>n</sup> of Mag. field  $\rightarrow$  It is coming out.

Area,  $ds = dx dy$

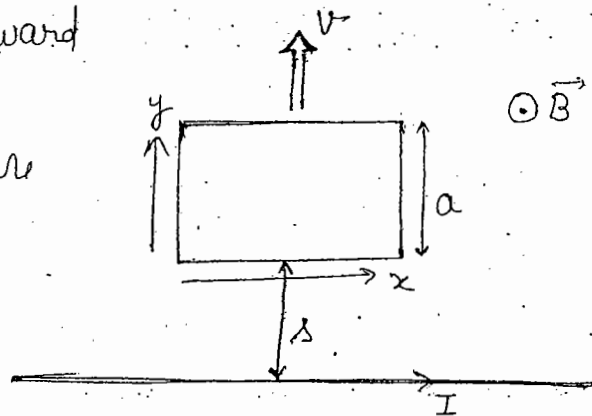
$$\phi_m = \int_0^a \int_s^{s+a} \frac{\mu_0 I}{2\pi y} dx dy$$

{ limits of  $y \rightarrow s$  to  $s+a$

Here variation of mag. field is along  $y$  dir<sup>n</sup>

$$\phi_m = \frac{\mu_0 I}{2\pi} a \ln\left(\frac{s+a}{s}\right)$$

If flux  $\rightarrow$  const then No emf.



$s$  is variable. If loop is away from wire then  $s \uparrow$  & then flux  $\downarrow$ . (area of loop & angle  $\rightarrow$  constant & mag. field changes)  
 So Here flux is not constant.  $\downarrow$  depending on  $s$

Now,  $\epsilon$  mf,  $\epsilon = -\frac{d\Phi_m}{dt}$

$$= -\frac{\mu_0 I a}{2\pi} \left(\frac{s}{s+a}\right) \left(\frac{-a}{s^2}\right) \frac{ds}{dt}$$

$\frac{ds}{dt} \rightarrow$  Rate of change of distance i.e. velocity  $v$ .

$$\epsilon = \frac{\mu_0 I a^2}{2\pi s(s+a)} v$$

This much emf will induce in the loop.

Dir<sup>n</sup> of the induce current: As loop is moving away from wire  $\rightarrow s \uparrow$ . Here flux is decreasing. So induce current will try to increase it, & flux is decreasing due to dec. in mag. field so induce current will try to inc. the mag. field. To do so, it will develop a mag. field opposite to original.

So Dir<sup>n</sup> of current - Anticlockwise

• If we are pulling the loop towards the wire,

then flux  $\uparrow$ ,  $\vec{B} \uparrow$ , so current try to dec. the  $\vec{B}$

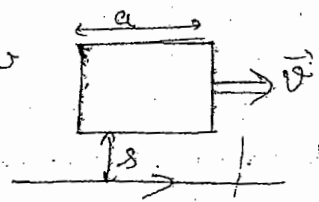
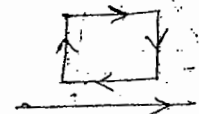
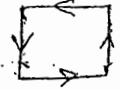
Dir<sup>n</sup> of current - Clockwise

• If we pull the loop parallel to wire then there will be No change in flux. Now flux will pass through the loop but change in flux = 0 so emf = 0

\* If wire is finite then on the ends of wire, mag. field will be complicated.

\* If loop pulling away from wire, dir<sup>n</sup> of  $I \rightarrow$  Anti  
 " " " towards " " "  $\rightarrow$  clockwise

\* Induced emf try to dec. the flux.



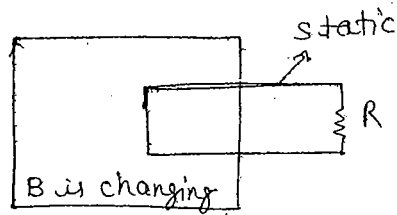
# Magnetic Flux with changing Magnetic field

(II case)

Loop is static but B is changing.

emf,

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi_m}{dt}$$



This is the integral form of Faraday's law.

$\vec{E} \rightarrow$  This is not constant electrostatic field.  
So  $\oint \vec{E} \cdot d\vec{l} \neq 0$  Here. (i.e. Not static)

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{S}$$

$$\Phi_m = \int \vec{B} \cdot d\vec{S}$$

Loop is static i.e. area is not changing

$$\text{So } \frac{\partial S}{\partial t} = 0$$

$$\oint \vec{E} \cdot d\vec{l} = -\int \frac{d\vec{B}}{dt} \cdot d\vec{S}$$

$$\Rightarrow \int_S (\nabla \times \vec{E}) \cdot d\vec{S} = -\int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S}$$

$$\Rightarrow \int_S (\nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t}) \cdot d\vec{S} = 0$$

$$\Rightarrow \boxed{\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}}$$

So we have induced electric field only if  $\vec{B}$  is changing with time.

&  $\vec{E}$  is not electrostatic here coz for electrostatic  $\vec{E}$ ,  $(\nabla \times \vec{E} = 0)$

So  $\vec{E}$  is not conservative as well,

$\vec{E} \rightarrow$  Non conservative & Non electrostatic

No scalar pot<sup>n</sup> is defined for that electric field.

This ele. field is induced electric field, & The properties of induced elec. field are same as prop of mag. field as it arises from mag. field.

E - field lines  $\rightarrow$  Open Curve

B - field lines  $\rightarrow$  Close Curve

Field lines of Induced Electric field - Closed Curve

$$\& \quad \boxed{\vec{\nabla} \cdot \vec{E} = 0}$$

bcz there is no charge correspond to it otherwise  $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

$\neq$  Induced Elec. field is  $\rightarrow$

$\rightarrow$  Non Conservative

$\rightarrow$  Non electrostatic

$\rightarrow$  Closed Curve

$\rightarrow$  Div  $\vec{E} = 0$

$$\text{emf, } \mathcal{E} = \oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi_m}{dt} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{S}$$

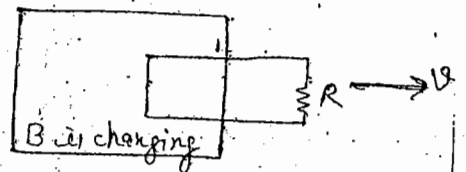
$$= -\int \frac{d\vec{B}}{dt} \cdot d\vec{S} \quad (\text{if } B \text{ is not changing with } t)$$

Case III:- If loop & ~~the~~ mag. field both are changing then

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{S}$$

$$= -\int \frac{d\vec{B}}{dt} \cdot d\vec{S} + \oint \vec{F}_{\text{mag}} \cdot d\vec{l}$$

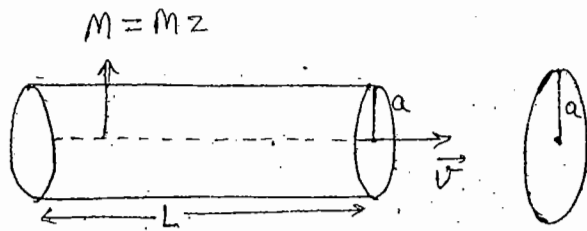
$$= -\int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} + \oint (\vec{v} \times \vec{B}) \cdot d\vec{l}$$



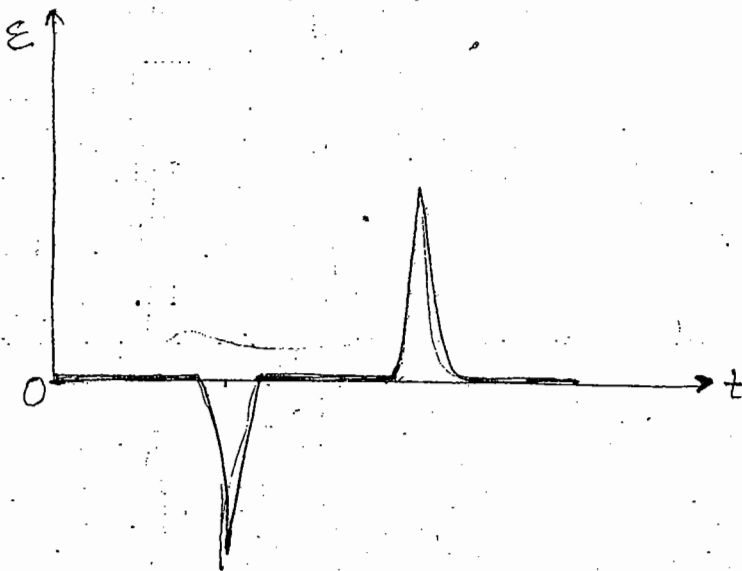
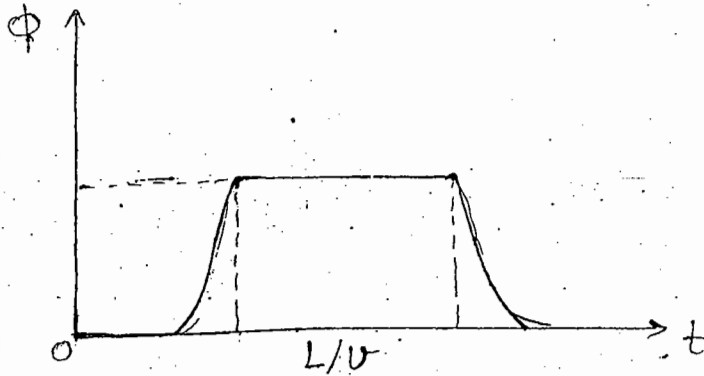
Que:- A long cylindrical magnet of length 'L' & radius 'a' carries a uniform magnetization  $\vec{M}$  parallel to its axis. It passes at a constant velocity  $v$  through a circular ring of slightly larger diameter. Graph the induced emf in the ring as a func<sup>n</sup> of time.

If Magnetization of ~~the~~ magnet is  $M$  then mag. field of a magnet is

$$\boxed{\vec{B} = \mu_0 M \hat{z}}$$



When magnet come close to ring then flux  $\uparrow$ . When it is in the ring then flux is constant through the passing of the magnet & then it will dec. coz it leave the ring. So emf occur when it enters & leaves the ring.



Ques :- A long solenoid of radius  $a$  is driven by an alternating current s.t. field inside the solenoid is

$$\vec{B}(t) = B_0 \cos \omega t \hat{z}$$

A circular loop of wire of radius  $a/2$  & resistance  $R$  is placed inside the solenoid & coaxial with it. Find the current induce in the loop as a fun of time.

$$\vec{B}(t) = B_0 \cos \omega t \hat{z}$$

B is not a func<sup>n</sup> of distance i.e.  
B uniform. So flux

$$\phi = B \cdot \pi \left(\frac{a}{2}\right)^2$$

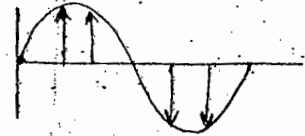
$$= B \frac{\pi a^2}{4}$$

$$\phi = \frac{B_0 \pi a^2}{4} \cos \omega t$$

$$\mathcal{E} = \frac{d\phi}{dt} = \frac{\omega B_0 \pi a^2}{4} \sin \omega t \Rightarrow \mathcal{E} = \frac{B_0 \pi a^2 \omega}{4} \sin \omega t$$

$$\text{Current } I = \frac{\mathcal{E}}{R} \Rightarrow I = \frac{B_0 \omega \pi a^2}{4R} \sin \omega t$$

Dir<sup>n</sup> of current  $\rightarrow$  changing accordingly  $\sin \omega t$ . For upper half circle  $\uparrow$  & lower half circle  $\downarrow$  will be different.



Ques 1 - A square loop of wire with side 'a' lies in the 1st quadrant of x-y plane with one corner at the origin. In this region there is non-uniform time dependent magnetic field  $\vec{B}(y,t) = Ky^3 t^2 \hat{z}$  is coming out of the page. Where k is some constant. Find the induced emf in the loop.

$$\vec{B}(y,t) = Ky^3 t^2 \hat{z}$$

Non uniform & time dependent.

$$\text{flux } \phi = \int B \cdot ds$$

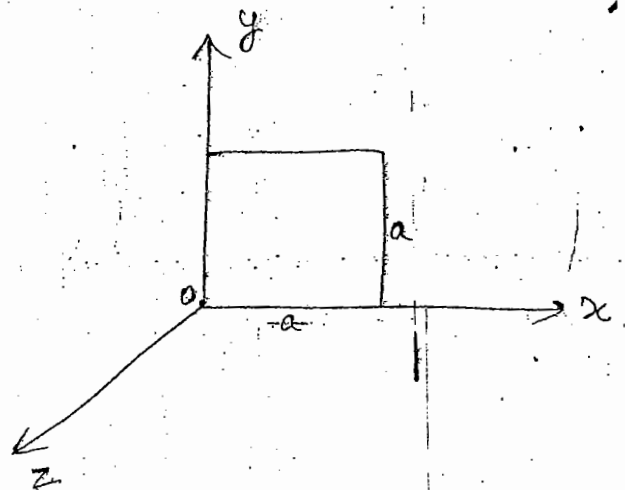
$$= \int_0^a \int_0^a Ky^3 t^2 dx dy$$

$$= Kt^2 [x]_0^a \left[ \frac{y^4}{4} \right]_0^a$$

$$= Kt^2 a \cdot \frac{a^4}{4}$$


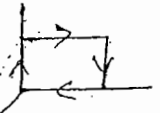
$$\phi = \frac{Kt^2 a^5}{4}$$

flux is changing with time.



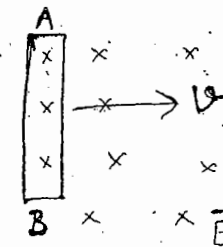
$$\text{emf } \epsilon = -\frac{d\phi}{dt} = -\frac{d}{dt} \left[ \frac{kt^2 a^5}{4} \right] = \frac{-ka^5}{4} \cdot 2t$$

$$\boxed{\epsilon = -\frac{kt a^5}{2}}$$

Current producing such mag. field will be Anticlockwise.   
 B is  $\uparrow$  with time, so induced current will try to  $\downarrow$  it.  
 So Dir<sup>n</sup> of induced current for induced ele. field mag. will be clockwise. 

Note: Induced current always less than the original current except the case of Superconductors ( $I_{in} = I$ ).

Q.1: A <sup>metallic</sup> rod AB moves with a uniform velocity  $v$  in a uniform mag. field  $B$  as shown in the figure.

- (a) The rod becomes electrically charged. 
- (b) The end A becomes +vely charged.
- (c) " B " " " " "
- (d) The rod becomes hot because of joule heating.

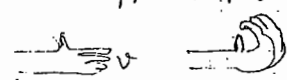
Q.2: A rod of length  $l$  rotates with a uniform angular velocity  $\omega$  about its  $\perp$  bisector. A uniform mag. field  $B$  exist parallel to the axis of rotation. The pot<sup>n</sup> difference b/w the centre of the rod & an end is

- (a) 0 (b)  $\frac{1}{8} \omega B l^2$  (c)  $\frac{1}{2} \omega B l^2$  (d)  $B \omega l^2$

Q.3: The pot<sup>n</sup> diff. b/w two ends of the rod is

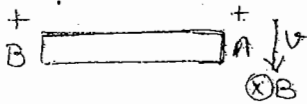
- (a) 0 (b)  $\frac{1}{2} B l \omega^2$  (c)  $B l \omega^2$  (d)  $2 B l \omega^2$

① (b) A  $\rightarrow$  +ve, B  $\rightarrow$  -ve

B  $\rightarrow$    
 so upward  $\rightarrow$  +ve



(2) Rod is rotating about mid point.



End A & B  $\rightarrow$  +ve  
 Centre O  $\rightarrow$  -ve

It will become a battery of length  $l$ .

$$\vec{v} = \vec{\omega} \times \vec{r}$$

$$= \omega r$$

The charges in the rod are different. The linear velocity is 0 at the centre & increased away from origin & max. at A.

$$\mathcal{E} = \int_0^{l/2} \omega r B dr = \frac{\omega B}{2} \left(\frac{l}{2}\right)^2 = \frac{1}{8} \omega B l^2$$

$$\boxed{\mathcal{E} = \frac{1}{8} \omega B l^2}$$

(3) A & B both have +ve charge do Pot<sup>n</sup> diff. b/w them.

i) 0

$$\mathcal{E} = \int_{-l/2}^{l/2} \omega r B dr = \frac{\omega B}{2} (l^2)_{-l/2}^{l/2} = \frac{\omega B}{2} \left[ \frac{l^2}{4} - \frac{l^2}{4} \right] = 0$$

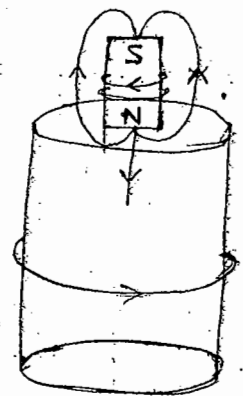
$$\boxed{\mathcal{E} = 0}$$

Q. :- A bar magnet is released from the rest along the axis of a very long vertical copper tube. After some time the magnet

- (i) will stop in the tube.
- (ii) will move with almost constant speed
- (iii) will move with an acceleration  $g$ .
- (iv) will oscillate.

[ (ii) is correct. ]

If it is in the copper tube then it will move with 0 acceleration & constant speed. (almost constant). It depends on how strong the magnet is.

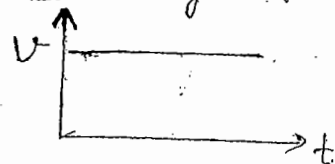


If copper ~~rod~~ <sup>magnet</sup> move downward inside the tube. As it pass through the rings <sup>again & again</sup> (cylinder is made by rings)  $\rightarrow$  change in the flux, & induces mag. field which oppose its motion.

As magnet enters in one ring then flux constant & again it enters in the next ring so flux will be change, & give rise to induce mag. field.

When magnet enters into the tube then current will be opposite to the actual current,

& When leaving the tube then dir<sup>n</sup> of current will be same as actual current.

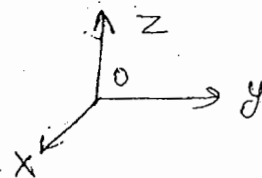
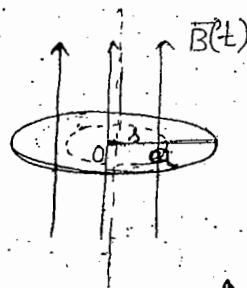


Ques:- A uniform mag. field  $B(t)$  pointing in the up dir<sup>n</sup> fills the circular region as shown in the figure. If  $B$  is changing with time. What is the induce electric field,

Induce electric field;

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\phi}{dt}$$

$$= -\int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} \quad \text{--- (1)}$$



Sketch a Ampirical loop of radius  $s$ .

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} = \mu_0 \int \vec{J} \cdot d\vec{S}$$

flux passing through the loop,

$$(1) \Rightarrow \phi_m = B \pi s^2$$

$$\text{Now, } \oint E \cdot dl = -\frac{d\phi}{dt} \Rightarrow E \cdot 2\pi s = -\pi s^2 \frac{\partial B(t)}{\partial t}$$

$$\boxed{E_{in} = -\frac{s}{2} \frac{\partial B(t)}{\partial t} \hat{\phi}}$$

If mag. field is in  $z$  dir<sup>n</sup> then  $E_{in}$  will be in  $\phi$  dir<sup>n</sup>.

• If  $\vec{B} = at^2 \hat{z}$

Here  $B$  is  $\uparrow$  with  $t$  so Flux  $\uparrow$ .

so induce current or induce ele. field will try to  $\downarrow$  the flux. [so its dir<sup>n</sup> will be opposite to the actual cur<sup>t</sup> (anti c.)]  
so dir<sup>n</sup> of  $E_{in}$  will be Clockwise by watching up from up.

• If  $B$  is  $\downarrow$  with  $t$  then dir<sup>n</sup> of  $E_{in}$  will be Anticlockwise

• If we switch off the mag. field, i.e.  $B=0$  then flux  $\downarrow$  & induce current will try to  $\uparrow$  the flux then dir<sup>n</sup> of  $E_{in}$  will be Anticlockwise.

Q. A line charge  $\lambda$  is uniformly distributed on the rim of a wheel of radius  $b$  which is then suspended horizontally as shown in the figure, & it is free to rotate. In the central region upto radius  $a$  there is a uniform mag. field  $B$  pointing in the up dir<sup>n</sup>. Now if someone turn off the magnetic field then calculate the angular momentum acquired by the wheel.

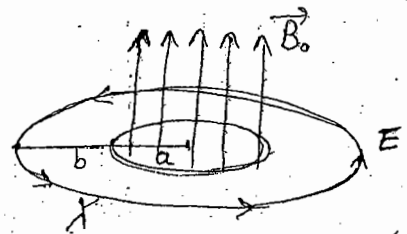
$B_0 \rightarrow$  const. Not depending on time

Right  $\&$  now flux pass

$$\Phi_m = B_0 \pi a^2$$

Now switch off  $B$  i.e.  $B = 0$

$$\Phi_m = 0$$



Flux changes then there is a induce electric field. dir<sup>n</sup> of induce electric field is s.t. it will try to restore the flux.

Each charge is fix in ring. On applying force, charges do motion & due to this whole rim will do motion so this rim have angular mom.

$$\oint E \cdot dl = - \frac{d\Phi_m}{dt}$$

$$= - \pi a^2 \frac{dB_0}{dt}$$

mag. field is lying in the region of radius  $a$ .

So Torque  $N = \vec{r} \times \vec{F}$

$\vec{F} \rightarrow$  force required to rotate the charge, electric field will do work for rotation of charges - Electric force

force/unit length =  $f = \lambda E$

$$\left\{ q = \int \lambda dl \right\}$$

So total force =  $\int \lambda E \cdot d\vec{l}$

$$\left\{ \begin{aligned} F &= qE \\ &= \int \lambda dl E \\ &= \int \lambda E dl \end{aligned} \right.$$

$\therefore N = b \lambda \int E \cdot d\vec{l}$

dir<sup>n</sup> of torque  $\rightarrow$  upward

$$\left\{ \begin{aligned} &= \int \vec{r} \times \vec{F} \\ &= \int \vec{r} \times \lambda E \cdot d\vec{l} \end{aligned} \right.$$

$$N = \frac{dL}{dt} = - \pi a^2 b \lambda \frac{dB_0}{dt}$$

$L \rightarrow$  angular Mom.

$$dL = -\pi a^2 b \lambda dB_0$$

When  $B = B_0$  ;  $L = 0$   
 $B = 0$  ;  $L = L$

$$\text{So } \int_0^L dL = -\pi a^2 b \lambda \int_{B_0}^0 dB_0$$

$$\Rightarrow \boxed{L = \pi a^2 \lambda b B_0}$$

This much angular mom. will be acquired by the rim.

We know  $L = m v r$  If mass of the rim is  $m$ ,

$$r = b, \quad L = m v b$$

$$L = m \omega b^2 \quad (v = \omega r = \omega b)$$

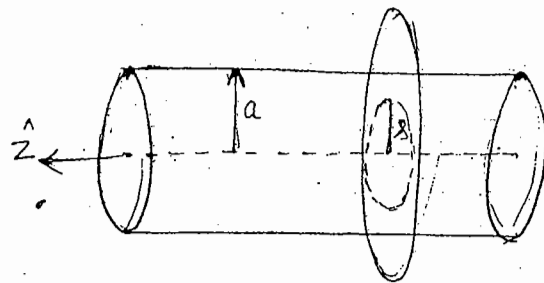
$$\text{So } m \omega b^2 = \pi a^2 b \lambda B_0$$

$$\boxed{\omega = \frac{\pi a^2 \lambda B_0}{m b}}$$

Q. 1 - A long solenoid with radius  $a$  &  $n$  turns per unit length carries a time dependent current  $I(t)$  in the  $\hat{z}$  dir<sup>n</sup>. Find the electric field both dir<sup>n</sup> & magnitude at a distance  $s$  from the axis both inside & outside the solenoid.

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi_m}{dt}$$

Mag. field inside the solenoid  $\Rightarrow B = \mu_0 n I(t)$



$$E \cdot 2\pi s = -\mu_0 n \cdot \pi s^2 \frac{dI}{dt}$$

$$\boxed{\vec{E}_{in} = -\frac{\mu_0 n s}{2} \frac{dI}{dt} \hat{\phi}}$$

If  $B$  is in  $\hat{z}$  dir<sup>n</sup> &  $\vec{E}_{in}$  (induced) will be in  $\hat{\phi}$  dir<sup>n</sup>

Outside :- Flux =  $\mu_0 n I \pi a^2$

$$E \cdot 2\pi s = -\mu_0 n \pi a^2 \frac{dI}{dt}$$

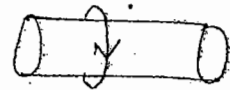
$$\vec{E}_{\text{out}} = -\frac{\mu_0 n a^2}{2s} \frac{dI}{dt} \hat{\phi}$$

Although mag. field outside the solenoid is 0 but induce electric field is not  $\vec{E}_{\text{out}} \neq 0$

$$(E_{\text{induc}})_{\text{inside}} \propto s$$

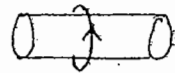
$$(E_{\text{induc}})_{\text{outside}} \propto \frac{1}{s}$$

If  $I$  (current) is  $\uparrow$  with time then



induce current oppose the flux

If  $I \downarrow$  with time



create the flux.

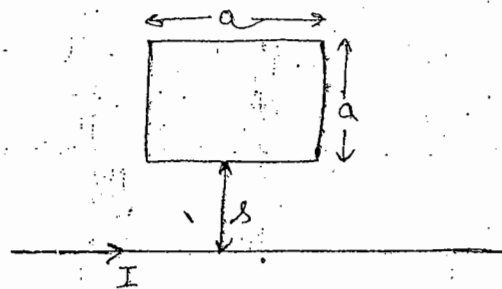
Q. A square loop of side  $a$  & resistance  $R$  lies at a distance  $s$  from an infinite straight wire that carries a current  $I$ . Now someone cut the wire s.t.  $I$  drops to zero. In what dir<sup>n</sup> induce current in loop will flow. And calculate the total charge passes a given point in the loop during this time of current flow.

emf

$$\mathcal{E} = -\frac{d\phi}{dt}$$

$$\mathcal{E} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{s}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi s} \text{ (out of page)}$$



$$ds = dx dy$$

$$\mathcal{E} = -\frac{d}{dt} \int_s^{s+a} \frac{\mu_0 I}{2\pi s} a ds$$

$$= -\frac{d}{dt} \left[ \frac{\mu_0 I a}{2\pi} (\ln s)^{s+a} \right] = -\frac{\mu_0 a}{2\pi} \ln\left(\frac{s+a}{s}\right) \frac{dI}{dt}$$

$$\text{emf} = I_{\text{loop}} \cdot R$$

$$I_{\text{loop}} \cdot R = -\frac{\mu_0 a}{2\pi} \ln\left(\frac{s+a}{s}\right) \frac{dI}{dt}$$

$$\Rightarrow \boxed{I_{\text{loop}} = -\frac{\mu_0 a}{2\pi R} \ln\left(\frac{s+a}{s}\right) \frac{dI}{dt}}$$

We know  $I = dQ/dt$

$$\frac{d\Phi_{\text{loop}}}{dt} = -\frac{\mu_0 a}{2\pi R} \ln\left(\frac{s+a}{s}\right) \frac{dI}{dt}$$

$$\int_0^{\Phi} d\Phi_{\text{loop}} = -\int_I^0 \frac{\mu_0 a}{2\pi R} \ln\left(\frac{s+a}{s}\right) dI$$

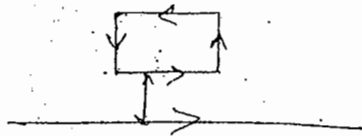
$$\Rightarrow \Phi_{\text{loop}} = \frac{\mu_0 I a}{2\pi R} \ln\left(\frac{s+a}{s}\right)$$

$$\Rightarrow \Phi_{\text{loop}} = \frac{1}{R} \left[ \frac{\mu_0 I a}{2\pi} \ln\left(\frac{s+a}{s}\right) \right]$$

$$\Rightarrow \boxed{\Phi_{\text{loop}} = \frac{\Phi}{R}} \checkmark$$

Dir<sup>n</sup> of Induce current  $\rightarrow$  Anticlockwise

$I \downarrow$ ,  $B \downarrow$ ,  $\phi \downarrow$   $\therefore$  induce current will try to  $\uparrow$  the flux.



Q. A square loop of edge 'a' having 'n' turns is rotated with a uniform angular velocity  $\omega$  about one of its diagonals which is kept fixed in horizontal position as shown in the figure. A uniform mag. field exist in the vertical dir<sup>n</sup>. Find the induce emf in the coil. Also plot the graph b/w induce current & phase wt.

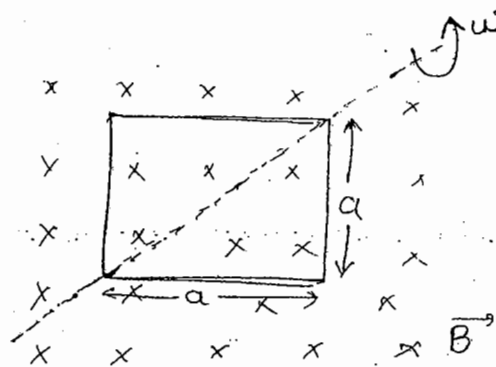
Area is fixed. B is fixed but angle is changing.

$\therefore$  flux changes due to angle change

$$\text{flux } \phi = B a^2 \cos \theta$$

If loop is rotating with ang. velocity  $\omega$  then in time  $t$ , loop rotate by angle  $\theta = \omega t$

$$\therefore \phi = B a^2 \cos \omega t$$

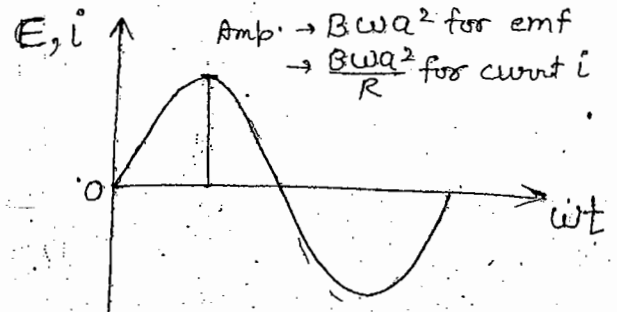
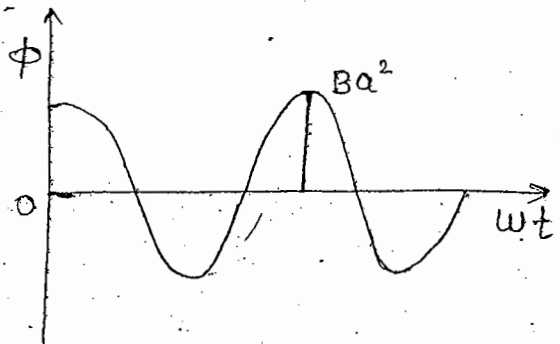


emf  $\mathcal{E} = -\frac{d\phi}{dt} = B\omega a^2 \sin \omega t$

If Resistance of the loop is  $R$  then current flow through the loop will be

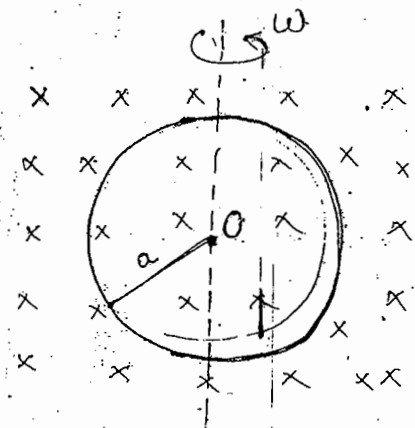
$$i = \frac{\mathcal{E}}{R} \Rightarrow \boxed{i = \frac{B\omega a^2 \sin \omega t}{R}}$$

Plot:-



Plot of emf & current will be same. Only difference is of amplitudes.

Q. A conducting circular loop of radius  $a$  is rotated about its diameter at  $\omega$  a constant angular velocity. In a mag. field  $B$ ,  $\perp$  to the axis of rotation, in what position of the loop, induced emf will be zero.



flux passes through the loop

$$\phi = B \pi a^2 \cos \theta$$

$$\theta = \omega t$$

$$\boxed{\phi = B \pi a^2 \cos \omega t}$$

emf  $\boxed{\mathcal{E} = -\frac{d\phi}{dt} = B \pi a^2 \omega \sin \omega t}$

When  $\theta = \omega t = \frac{\pi}{2}$  then emf will be maximum & flux = 0  
(phase diff. b/w emf & flux is of  $90^\circ$ )  
flux is leading in phase than emf.

$$\text{as } \sin(\omega t + \frac{\pi}{2}) = \cos \omega t$$

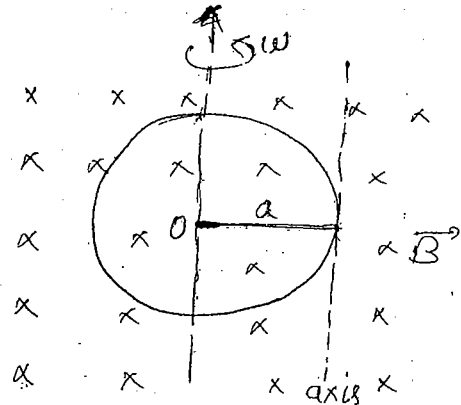
As compare to  $\cos$  &  $\sin$ , we get  $\sin$  is  $\pi/2$  ahead flux is ahead in phase

• In this case

$$\text{flux } \phi = B \pi a^2 \cos \omega t$$

$$\text{emf } \varepsilon = B \pi a^2 \omega \sin \omega t$$

Now the whole loop is rotating about the axis. There will be No difference in  $\phi$  &  $\varepsilon$ .

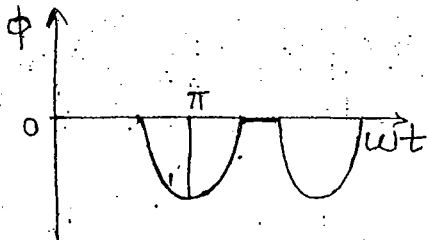


• But if there is no mag field on the R.H.S. of axis then:

flux will exist only from  $-\frac{\pi}{2}$  to  $+\frac{\pi}{2}$

$$\text{i.e. } -\frac{\pi}{2} < \omega t < \frac{\pi}{2} \quad (\theta = \omega t)$$

then wave of flux will be Half wave rectifier



If flux wave is half  $\cos$  wave then emf wave will be half sine wave.

$\varepsilon \rightarrow$  half wave sinusoidal.

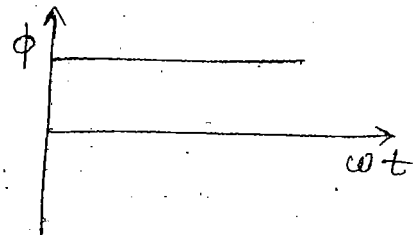
The wave can be on +ve or -ve axis depends upon the rotation.

The Axis of rotation is parallel to the axis of loop.

$$\text{flux pass through loop } \phi = B \pi a^2$$

$$\text{change in flux} = 0$$

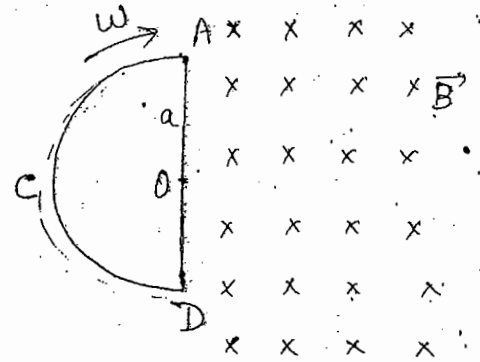
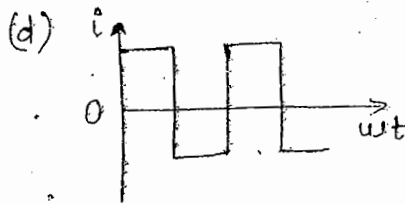
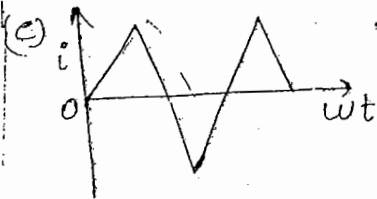
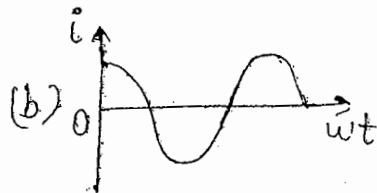
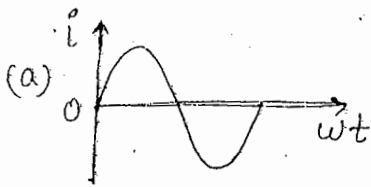
$$\therefore \text{Induced emf} = 0$$



Q. The mag. field  $B$  shown in the figure is directed into the plane of the paper; ACDA is a semicircular loop of radius 'a' with the centre at O. The loop is now made to rotate clockwise with a constant angular velocity  $\omega$  about axis passing through O &  $\perp$  to the plane of the paper. The resistance of the loop is  $R$ . Obtain an expression for the magnitude of the induced current.



of the loop. Plot a graph b/w induced current & time.

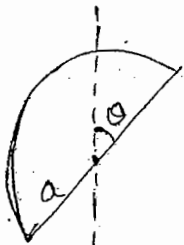


axis of rotation is O.

Axis of Rotation is O i.e. loop is rotating about O. So flux passing through the loop is variable.

$$\text{Maximum area limit} = \frac{\pi a^2}{2}$$

It is rotating so after some time position of loop will be



→ Angle b/w A (area vector) & B is Not changing

→ B is Not changing

→ Area is changing

If loop rotate by  $180^\circ$  then it comes in mag. field. i.e. area A is completely inside the B.

$$\theta = \omega t, \quad \{ \text{If } \theta = \pi \}$$

then area

$$A = \left( \frac{\pi a^2}{2} \right) \left( \frac{\theta}{\pi} \right) = \frac{a^2 \theta}{2}$$

If  $0 < \theta < \pi$  then flux  $\uparrow$  (area linearly  $\uparrow$  with  $\theta$ )

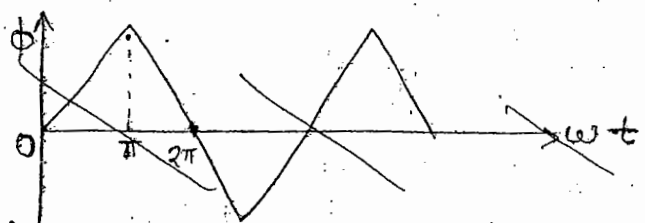
If  $\pi < \theta < 2\pi$  then flux  $\downarrow$

So flux ( $0 < \theta < \pi$ )

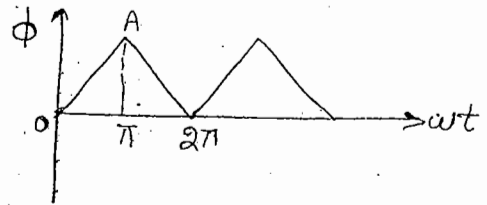
$$\phi = B \frac{a^2 \theta}{2} \Rightarrow \phi = \frac{Ba^2(\omega t)}{2}$$

Flux  $\uparrow$  linearly with  $\omega t$  up to  $0$  to  $\pi$ . Then from  $\pi$  to  $2\pi$  flux linearly  $\downarrow$  with  $\theta$  bcoz loop is out of B now. At

$\theta = 2\pi$ ,  $\phi$  again zero bcoz ( $2\pi$  same)



1 wave complete  $0 \rightarrow 2\pi$



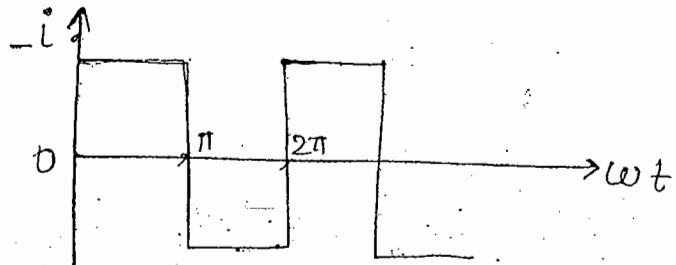
Now emf,  $\mathcal{E} = -\frac{d\phi}{dt}$

flux linear with  $t$  so on differentiating we get constant. So we get square wave.

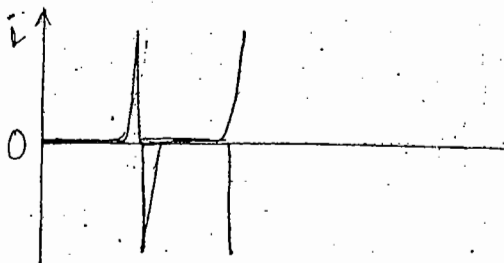
Slop of OA is +ve so current or emf will be -ve.

$\mathcal{E} = -\frac{d\phi}{dt}$  (here -ve sign present so take -i on axis)

\* Differentiation of linear wave is always a square wave.



If we apply differentiator of square wave - then we get 'Spikes'.



If sharp change; then spikes are narrow.

If broad change, then spikes are spread.

If we apply Integrator on spikes - then we get square wave again.

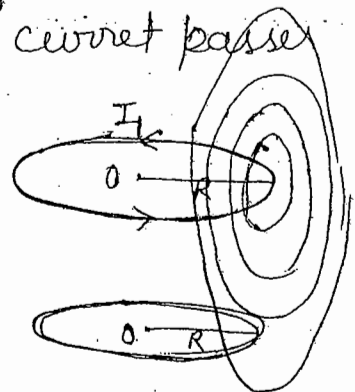
Wave of  $\phi \rightarrow$  triangular  
wave of  $i \rightarrow$  square wave

## Mutual Inductance :-

If we have 2 current carrying coils of radius  $R$ .  
Put these coils close to each other. If current passes through coil (1) is  $I_1$  & coil (2) is zero.

Due to current  $I_1$  of loop (1),

Magn. field lines of loop (1) will pass through the loop (2), so there will be a mag. flux through loop (2).



So there will be an induced emf.

If we change the current  $I_1$ , then mag. field  $B_1$  will change as  $B \propto I_1$ .

So flux changed which is linked to loop (2).

So there will be induced emf.

The dir<sup>n</sup> of

If flux  $\Phi \downarrow$ , dir<sup>n</sup> of current in loop (1) & (2) are same  
" " " " " " " " " " opposite  
" " " " " " " " " " " " " "

So flux pass through loop (2) is due to the mag. field of loop (1) & area of loop (2).

$$\Phi_2 \propto I_1 \quad \left\{ \begin{array}{l} \text{as } B \text{ flux } \Phi \propto B \text{ \& } B \propto I \text{ so} \\ \Phi \propto I \end{array} \right.$$

And constant of proportionality is called Mutual Inductance,  $(M)$ .

$$\text{i.e. } \Phi_2 = M_{21} I_1$$

$M_{21} \rightarrow$  Mutual Inductance b/w 2 & 1.

$\Rightarrow$  Now change the current, ( $I_1$  &  $I_2 \rightarrow$  same magnitude)

Now current is flowing through loop (2)

And mag. flux pass through loop (1)

will depend upon due to the mag. field  $B$  of loop (2).

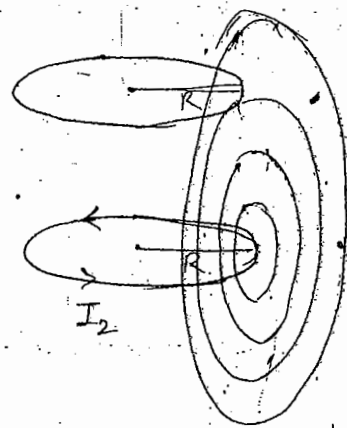
then  $\Phi_1 \propto I_2$

$I_1 = I_2 = I$  (same mag.)

So both flux  $\Phi_1$  &  $\Phi_2$  will be same.

$$\Phi_1 = M_{12} I_2$$

$$\Phi_1 = \Phi_2$$



flux  $\propto$  current

On interchanging current, flux will be interexchange irrespective of their areas.

Mutual Inductance is purely geometrical quantity. This depends

on size, shape & positions of the loop.

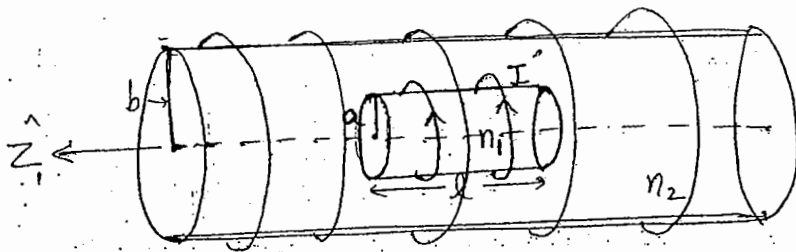
⇒ If Radius of both loops are different still flux is same.

$$\left. \begin{array}{l} \text{loop(1)} \rightarrow 2R \\ \text{loop(2)} \rightarrow R \end{array} \right\} \text{ then } \phi_1 = \phi_2$$

⇒ On changing size of loop,  $M$  will change.

⇒ To calculate flux of any loop, we have to fix the value of  $M$  (i.e. In the process, size, shape & distance b/w both loops can not be changed)

Q. :- A short solenoid of length  $L$  & radius  $a$  with  $n_1$  turns per unit length lies on the axis of a very long solenoid of radius  $b$  &  $n_2$  turns per unit length. Current  $I$  flows in the short solenoid. What is the flux through the long solenoid.



No current on large solenoid.

Mag. field of small solenoid passing through the large one but Mag. field of a short solenoid is complicated.

Inside  $\rightarrow B = \mu_0 n_1 I$  but outside, Not exactly zero at the ends of short loop.

Beoz Mag. field of short solenoid is complicated.

Hence interchange the current.

Now assume, current  $I$  is flowing in the long solenoid & we have to find the mag. flux through short solenoid

Mag. field of large solenoid

$$\vec{B} = \mu_0 n_2 I \hat{z}$$

By single ring of a ~~short~~ solenoid, flux pass out

$$\phi_{\text{single}} = \mu_0 n_2 I \cdot \pi a^2$$

And in short solenoid,  $n_1$  are the no. of turns &  $l$  is the length.

So  $n_1 l \rightarrow$  turns per unit length.  
then flux

$$\phi_{\text{Total}} = n_1 l \phi_{\text{single}}$$

$$\phi_{\text{Total}} = \mu_0 n_1 n_2 l \cdot \pi a^2 I$$

So same flux will pass through the short & long's.

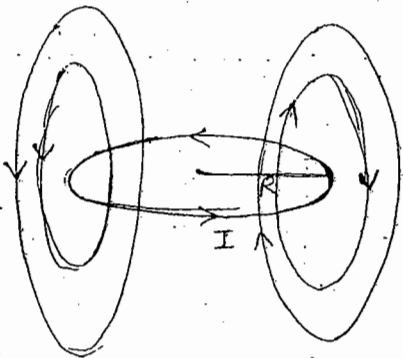
Now Mutual Inductance of this configuration

$$\phi = MI \Rightarrow M = \mu_0 n_1 n_2 l \cdot \pi a^2$$

$M$  depends on medium b/w both solenoids.

### Self Inductance (L) :-

Suppose we have a circular coil. Current flowing in this is  $I$  & its radius is  $R$ . Then there will be flux passing through the coil due to its own magnetic field.



$$\text{flux } \phi \propto B \text{ \& } B \propto I$$

So flux passing through the coil is proportional to the current  
 $\phi \propto I$

And Constant of proportionality is Self Inductance.

Self  $\rightarrow$  bcoz it is due to self current.

$$\boxed{\phi = LI}$$

If we are changing current with time then  $B$  is changing with time & hence  $\phi$  is changing with time. Area is const.  $L$  depends on size & shape of loop.

So there will be an induced emf

$$\text{emf } \varepsilon = -\frac{d\Phi}{dt} = -L \frac{dI}{dt}$$

If  $I \uparrow$  with  $t$  then  $\frac{dI}{dt} \rightarrow +ve$  but  $\varepsilon = -ve$

So induced current will oppose the change in current.

This is called Self Inductance.

☞

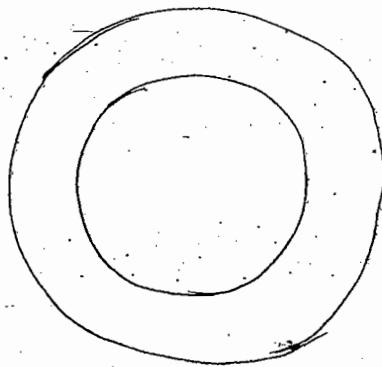
Q. Find the self inductance of a toroidal coil with rectangular cross-section inner radius  $a$  & outer radius  $b$  & height  $h$  which carries a total  $N$  turns.

Toroid  $\rightarrow$  Endless solenoid.

Mag. field of toroidal coil is

$$\vec{B} = \frac{\mu_0 N I}{2\pi s} \hat{\phi}$$

(Inside the toroidal coil) where  $a < s < b$  [Non-uniform]



There are  $N$  no. of turns.

Flux passing through a single turn,

$$\Phi_{\text{single}} = \frac{\mu_0 N I}{2\pi} \int_a^b \frac{1}{s} h ds$$

$$\Phi_{\text{single}} = \frac{\mu_0 N I h}{2\pi} \ln(b/a)$$

Total flux passing through  $N$  turns of toroid, will be

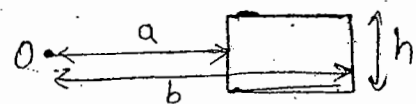
$$\Phi_{\text{Total}} = N \Phi_{\text{single}}$$

$$\Phi_{\text{Total}} = \frac{\mu_0 N^2 h}{2\pi} \ln(b/a) I$$

We know  $\Phi = LI$

So self inductance will be

$$L = \frac{\mu_0 N^2 h}{2\pi} \ln(b/a)$$



$$\text{area} = (b-a)h$$

$$\int_a^b \int_0^h dx dy$$

Mag. field varying with  $b$   
 $ds = dx dy$ . But  $B$  is not changing with  $y$   
 so  $dy = h$

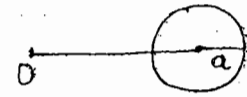
This is the self inductance of toroidal coil with rectangular cross-section.

If cross-section is circular instead of rectangular:-

$$\text{Area element} = s d\phi ds$$

$$= 2\pi s ds$$

(no variation with  $\phi$ , only with  $s$ )



$$\text{Now, } \phi_{\text{single}} = \frac{\mu_0 N I}{2\pi} \int_0^a \frac{1}{s} s ds 2\pi$$

$$\phi_{\text{single}} = \mu_0 N I a$$

$$\text{Total flux } \phi_{\text{Total}} = N \cdot \phi_{\text{single}}$$

$$\phi_{\text{Total}} = \mu_0 N^2 I a$$

$$\text{So Self Inductance } L = \mu_0 N^2 a$$

$$\int_0^{2\pi} \int_0^a s ds d\phi$$

$$\int_0^a s ds 2\pi$$

$$\Rightarrow \pi a^2$$

### Analogy b/w Mechanics & Electromagnetism:

In Mechanics, K.E. is  $K = \frac{1}{2} m v^2$

& P.E. is  $U = \frac{1}{2} k x^2$

If we have a coil & current is flowing in it is  $I$  & self inductance of that coil is  $L$  then magnetic energy stored by that coil is  $U_m = \frac{1}{2} L I^2$

Capacitor stores the electrical energy & Inductor stores magnetic energy.

↳ in the form of charge  $q$  or field in eff.

↳ in the form of current.

Inductor  $\rightarrow L \rightarrow I$

Capacitor  $\rightarrow C \rightarrow q$

current  $\rightarrow$  dynamic  
charge  $\rightarrow$  static

$$U_e = \frac{q^2}{2C} \quad \& \quad \text{Also } U_e = \frac{\epsilon_0}{2} \int E^2 d\tau$$

$$K = \frac{1}{2} m v^2 \longleftrightarrow U_m = \frac{1}{2} L I^2$$

$$U = \frac{1}{2} k x^2 \longleftrightarrow U_e = \frac{q^2}{2C}$$

Electromag. Waves carry energy but not carry charge.  
 With E.M. Wave, both energies are associated in <sup>or current</sup> electrical & magnetic. So magnetic energy resides in the magnetic field & electric energy resides in Ele. field. bcoz there is No charge (or current)

In Magnetostatics,  $U_m = \frac{1}{2\mu_0} \int_{\text{all space}} B^2 d\tau$

Mechanics		electromag.
<del>Magnetostatic</del>		
m	→	L
v	→	I
K	→	$\frac{1}{C}$
x	→	q

⇒ If we have 2 bodies of mass m & 2m then body of mass m will accelerate more.

Mass → less, More → acceleration

If M is more it will be difficult to ↑ the velocity.

⇒ If we have 2 coils of self inductance L & 2L then it is easy to ↑ the current of coil of S.I. L.

To ↑ current, have to fight against <sub>its</sub> back emf.

If L is more, it will be difficult to ↑ the current.

26/8/2012

Q. A long co-axial cable carries a current I, the current flows down the surface of inner cylinder of radius a & back along the cylinder of radius b. Find the magnetic energy stored in the section of length l.

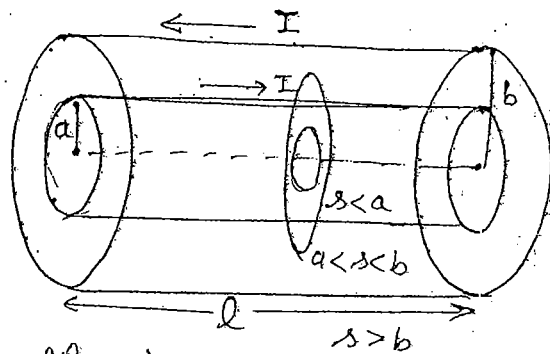
Magnetic energy stored

$$U_m = \frac{1}{2\mu_0} \int_{\text{all space}} B^2 d\tau$$

$$U_e = \frac{1}{2} \int_{\text{all space}} \vec{D} \cdot \vec{E} d\tau$$

Also  $U_m = \frac{1}{2} \int_{\text{all space}} \vec{H} \cdot \vec{B} d\tau$





current is flowing on the surface of both inner & outer cylinder

for  $s < a$ ,  $I_{enc} = 0$

$$\text{so } \boxed{B = 0}$$

for  $a < s < b$ ,  $I_{enc} = I$

$$\boxed{\vec{B} = \frac{\mu_0 I}{2\pi s} \hat{\phi}}$$

dir<sup>n</sup> of  $I_{enc}$  is  $\hat{z}$  Hence dir<sup>n</sup> of mag. field is  $\hat{\phi}$

for  $s > b$ ,  $I_{enc} = 0$

bcoz current on both cylinders are equal & opposite  
so cancel out  $I_{enc} = +I - I = 0$

$$\text{so } \boxed{B = 0}$$

$$\text{so } U_m = \frac{1}{2\mu_0} \int_{\text{all space}} B^2 d\tau$$

$$U = \frac{\mu_0^2 I^2}{2\mu_0 4\pi^2} \int_a^b \frac{1}{s^2} s ds d\phi dz$$

{ limits on  $s \rightarrow 0$  to  $\infty$  but from  $\int_0^a (B=0)$  &  $\int_b^\infty (B=0)$  }

$$U = \frac{\mu_0 I^2}{8\pi^2} 2\pi \cdot l \ln(b/a)$$

$$\boxed{U = \frac{\mu_0 l}{4\pi} \ln(b/a) I^2}$$

This much energy will be stored in this configuration.

Self Inductance of this confi.

$$U = \frac{1}{2} L I^2$$

$$\boxed{L = \frac{\mu_0 l}{2\pi} \ln(b/a)}$$

Q. Find the mag. energy stored in a toroidal coil of rectangular cross-section in a radius  $a$ , outer radius  $b$  & height  $h$ . Total No. of turns in the coil are  $N$  and current is  $I$ .

## Electrodynamics before Maxwell :-

(Gauss Law in electrostatics) (i)  $\vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0$  (ii)  $\vec{\nabla} \cdot \vec{B} = 0$  (Gauss law in magnetostatics)

(iii)  $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$  (Faraday's law)

(iv)  $\vec{\nabla} \times \vec{B} = +\mu_0 \vec{J}$  (Ampere's law)

These 4 eq<sup>n</sup> deriving the electrodynamics before Maxwell. Are these consistent in Electrodynamics :-

Physical significance of  $\vec{\nabla} \cdot \vec{B} = 0$  (Sometimes No name)

→ Non-existence of magnetic monopoles.

⇒ Taking <sup>div</sup> curl of eq<sup>n</sup> (iii),

L.H.S:  $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E}) = 0$  (div of curl is always zero)

R.H.S:  $-\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{B}) = 0$

$\vec{\nabla} \cdot \vec{B} = 0$  always, No restriction.

So Faraday's law i.e. this eq<sup>n</sup> is valid in electrodynamics.

⇒ Taking div. of eq<sup>n</sup> (iv),

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = 0$$

$$\vec{\nabla} \cdot \vec{J} = 0$$

but  $\vec{\nabla} \cdot \vec{J} = 0$  only in magnetostatics.

So this Ampere's law is valid only in Magnetostatics i.e. where there is No changing fields & current must be steady.

If accumulation of charge is present then this is not valid.

So this law must be modified -

## Modification of Ampere's law by Maxwell

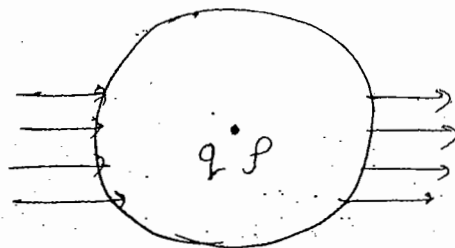
After modification, eq<sup>n</sup> (iv) becomes Modified Ampere's law. All 4 eq<sup>n</sup> together called Maxwell's eq<sup>n</sup>s.

In Magnetostatics  $\vec{\nabla} \cdot \vec{J} = 0$

But if charge is changing with time i.e.  $\rho$  " " " " then  $\vec{\nabla} \cdot \vec{J} \neq 0$

If we have a close surface & charge  $q$  is placed in this close surface & its charge density is  $\rho$ . This  $\rho$  is Not changing with time i.e. charge is conserved. i.e. No charge is flowing in or out.

OR 2nd possibility is that - charge coming in = charge coming out.



Flux of the current passing through the boundary of sphere = 0

then  $\vec{\nabla} \cdot \vec{J} = 0$

In 2nd case, still flux = 0

then  $\vec{\nabla} \cdot \vec{J} = 0$

i.e.  $\vec{\nabla} \cdot \vec{J} = 0$  if  $\rho$  is not depending on time.

But if  $\rho$  or  $q$  is a func<sup>n</sup> of time.

then flux pass through boundary = 0

→ If the flux is dec. with time then current will flow outward (in the dir<sup>n</sup> of flow of +ve charge)

→ If charge ↑ with time then current will flow into the sphere.

→ If charge is not change with time then current flow = 0

If Electrodynamics,

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

If  $\rho$  dec. with time then  $\rho = -ve$  then  $\vec{\nabla} \cdot \vec{J} = \frac{\partial \rho}{\partial t}$   
current flow outward.

If  $\rho$  ↑ with time  $\rho = +ve$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} \text{ then current flow into}$$

This eq<sup>n</sup> is called eq<sup>n</sup> of Continuity  
& its physical significance is local conservation of charge.

$$\boxed{\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}}$$

→ charge is conserved globally, neither be created nor be destroyed.

Here charge is conserved on a local body that's why it is called Local conservation of charge.

$$\text{eq<sup>n</sup> (1)} \Rightarrow \vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0$$

$$\Rightarrow \rho = \epsilon_0 (\vec{\nabla} \cdot \vec{E})$$

Put it into Continuity eq<sup>n</sup>,

$$\vec{\nabla} \cdot \vec{J} = -\epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E})$$

change the order then (because both operators are independent on each other)

$$\vec{\nabla} \cdot \vec{J} = -\epsilon_0 \vec{\nabla} \left( \frac{\partial \vec{E}}{\partial t} \right)$$

$$\Rightarrow \boxed{\vec{\nabla} \cdot \left[ \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right] = 0}$$

In electrodynamics, we need to replace  $\vec{J}$  by  $\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$ . then we get Modified Ampere's law.

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \Rightarrow \boxed{\vec{\nabla} \times \vec{B} = \mu_0 \left[ \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right]}$$

Now L.H.S. = 0 & R.H.S. = 0

(A)

So this eq<sup>n</sup> is consistent with electrodynamics.

This eq<sup>n</sup> is called Modified Ampere's law.

Also called 4th Maxwell eq<sup>n</sup>.

In Magnetostatic,  $B$  &  $E$  are independent of time

$$\frac{\partial E}{\partial t} = 0$$

$$\text{So } \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

In Eq<sup>n</sup> (A)  $\Rightarrow \epsilon_0 \frac{\partial \vec{E}}{\partial t} \rightarrow$  called displacement current density in vacuum.

Displacement Current - follow no other property of current. This is being called current only becoz it is producing mag. field. There are no charges corresponding to this displacement current. Corresponding to  $\vec{J}$  there are charges.

4 eq<sup>n</sup>s together  $\rightarrow$

3<sup>rd</sup> eq<sup>n</sup> say  $\rightarrow$  change in Mag. field producing Elec. field.

4<sup>th</sup> " " " " Elec. " " " " Mag. "

$$\vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Differential forms

$$\oint \vec{E} \cdot d\vec{s} = \frac{q_{enc}}{\epsilon_0}$$

$$\oint \vec{B} \cdot d\vec{s} = 0$$

$$\oint \vec{E} \cdot d\vec{l} = -\frac{\partial}{\partial t} \int_s \vec{B} \cdot d\vec{s}$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} + \mu_0 \epsilon_0 \frac{\partial}{\partial t} \int_s \vec{E} \cdot d$$

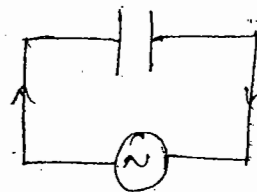
Integral forms

Practical Example of Displacement Current :- is found in air filled capacitor.

If we connect it with source then current flow.

In Air gap, No current.

$\rightarrow$  Current is flowing - displacement Current.

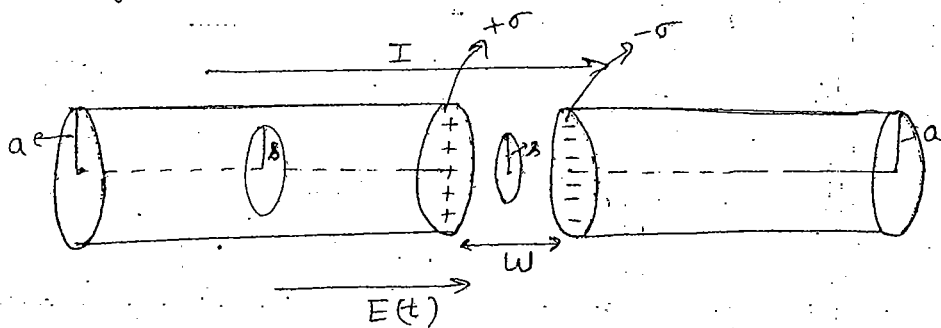


If source is time dependent  $\rightarrow$  charge accumulate on plate of capacitor  $\rightarrow$  E-field produce. Here  $\sigma = \sigma(t)$  bcoz charge is built up with time. So E-field will also be the fun of time. So a current produces due to the change in elec. field called Displacement Current.

Current produces due to motion of free electron called Conduction Current.

{ bound current  $\rightarrow$  due to motion of bound charge }

Q. A thick wire of radius  $a$  carries a constant current  $I$  uniformly distributed over its cross-section. A narrow gap in the wire of width  $w \ll a$  forms a parallel plate capacitor as shown in the figure. Find the mag. field in the gap at a distance  $s < a$  from the axis.



$$E(t) = \frac{\sigma(t)}{\epsilon_0}$$

$$\text{Current density } \vec{J}_a = \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \epsilon_0 \frac{1}{\epsilon_0} \frac{\partial \sigma}{\partial t} = \frac{\partial \sigma}{\partial t}$$

dir<sup>n</sup> of current is the dir<sup>n</sup> of elec. field

Current Enclose by the  $s$  loop,

$$I_{enc} = \int \vec{J}_d \cdot d\vec{s}$$

$$= \epsilon_0 \frac{\partial \sigma(t)}{\partial t} \cdot \frac{\pi s^2}{\epsilon_0}$$

$$= \frac{\partial \sigma(t)}{\partial t} \pi s^2 \times \frac{\pi a^2}{\pi a^2}$$

$$I_{enc} = \frac{1}{\pi a^2} \frac{\partial q(t)}{\partial t} \pi s^2 \quad \left\{ \begin{array}{l} \text{charge / unit time} \\ \text{- current} \end{array} \right\}$$

$\downarrow$   
 current

$$I_{enc} = \frac{I s^2}{a^2}$$

Ampere's law,  $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_c + \mu_0 \epsilon_0 \int \frac{\partial \vec{E}}{\partial t} \cdot d\vec{s}$

$\downarrow$   
 conduction current

$I_c = 0$  bcoz no free  $e^-$  in the gap  
 so total current will be due to Ind term.

$$B \cdot 2\pi s = \mu_0 \frac{I s^2}{a^2}$$

$$\vec{B} = \frac{\mu_0 I s}{2\pi a^2} \hat{\phi}$$

$$\left\{ \begin{array}{l} I_{enc} = \int J_d \cdot d\vec{s} \\ = \epsilon_0 \int \frac{\partial E}{\partial t} \cdot d\vec{s} \end{array} \right\}$$

Displacement current is necessary to make the current continuous across the capacitor.

This mag. field is same as  $\rightarrow$  in case of uniform mag. field inside the wire.

### Maxwell's Eq<sup>n</sup> in Matter:-

(i)  $\vec{\nabla} \cdot \vec{D} = \rho_f$

(ii)  $\vec{\nabla} \cdot \vec{B} = 0$  ( $\vec{\nabla} \cdot \vec{H} \neq 0$  as Magnetization is non-zero)  
 may or may not (depending on cond<sup>n</sup>)

$\left\{ \begin{array}{l} \text{If } M \text{ not depend on } t \text{ then } \vec{\nabla} \cdot \vec{H} = 0 \end{array} \right\}$

(iii)  $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

(iv)  $\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$

Before Maxwell  $\rightarrow$  4th eq<sup>n</sup>  $\rightarrow \vec{\nabla} \times \vec{H} = \vec{J}_f$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}_f + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

find in terms of  $H = ?$

In inside the matter, there will be polarisation & magnetisation.



$$\vec{J} = \vec{J}_b + \vec{J}_f$$

$$\vec{J} = \vec{J}_f + \underbrace{\nabla \times \vec{M}}_{\text{Magnetisation Current}}$$

$$\frac{1}{\mu_0} (\nabla \times \vec{B}) = \underbrace{\vec{J}_f}_{\downarrow} + \nabla \times \vec{M} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \underbrace{\frac{\partial \vec{P}}{\partial t}}_{\text{Polarisation current}}$$

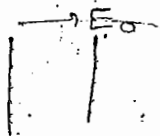
(i) Due to the motion of free charges

(ii) Due to the bound charges - bound or Magnetisation current.

(iii) Due to the change in Elec. field - Displacement current.

(iv) If  $E$  is changing with time then  $P$  also changing with time & current produce - Polarisation current.

In free space  $E$  field is  $E_0$



but if space is not free fill the matter in it then elec. field will be changed.

$$\epsilon E = \epsilon_0 E_0 + P$$

$$E = \frac{E_0}{\epsilon_r} + \frac{P}{\epsilon}$$



Due to  $E$  field, charges become polarised & began to oscillate so polarisation current produce.

$$\frac{1}{\mu_0} (\nabla \times \vec{B}) = \vec{J}_f + \nabla \times \vec{M} + \frac{\partial}{\partial t} (\epsilon_0 \vec{E} + \vec{P})$$

$$= \vec{J}_f + \nabla \times \vec{M} + \frac{\partial \vec{D}}{\partial t}$$

density displacement current in matter

$$\boxed{\nabla \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}}$$

→ called Maxwell's eq<sup>n</sup> in Matter.

## Maxwell's Eq<sup>n</sup>. in Free Space :-

In free space - there is no charge & no current.

$$(i) \nabla \cdot \vec{D} = 0 \Rightarrow \boxed{\nabla \cdot \vec{E} = 0} \quad (D = \epsilon E)$$

$$(ii) \nabla \cdot \vec{B} = 0$$

$$(iii) \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$(iv) \nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\left. \begin{aligned} \nabla \times \vec{H} &= \vec{J}_f + \frac{\partial \vec{D}}{\partial t} \\ &\parallel \\ &0 \\ &\text{(free space)} \end{aligned} \right\}$$

## Maxwell's Eq<sup>n</sup> for Static fields :-

$$(i) \nabla \cdot \vec{E} = \rho / \epsilon_0$$

$$(ii) \nabla \cdot \vec{B} = 0$$

$$(iii) \nabla \times \vec{E} = 0$$

$$(iv) \nabla \times \vec{B} = \mu_0 \vec{J}$$

{ static }

$$\left\{ \frac{\partial \vec{D}}{\partial t} = 0 \right\}$$

## Maxwell's Eq<sup>n</sup> for Isotropic Linear Dielectric :-

In dielectric  $\rightarrow$  free charges = 0

$$\rho_f = 0$$

for Linear dielectric,  $\vec{D} = \epsilon \vec{E}$

isotropic means  $\epsilon$  is not depend on space co-ordinate

i.e.  $\epsilon$  is not a fun<sup>n</sup> of position.

$$(i) \nabla \cdot \vec{D} = 0 \Rightarrow \boxed{\nabla \cdot \vec{E} = 0}$$

$$\left\{ \begin{aligned} \nabla \cdot (\epsilon E) &= 0 \\ \Rightarrow \epsilon (\nabla \cdot E) &= 0 \end{aligned} \right.$$

(for Anisotropic  $\nabla \cdot \vec{D} = 0$  but  $\nabla \cdot \vec{E} \neq 0$   
bcos  $\epsilon$  is a fun<sup>n</sup> of position)

$$(ii) \nabla \cdot \vec{B} = 0$$

$$(iii) \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$(iv) \nabla \times \frac{\vec{B}}{\mu} = \vec{J}_f + \frac{\partial \epsilon \vec{E}}{\partial t}$$

$$\Rightarrow \boxed{\nabla \times \vec{B} = \mu \epsilon \frac{\partial \vec{E}}{\partial t}}$$

$\vec{J}_f = 0$  (No free current)  
for linear  $\rightarrow \vec{B} = \mu \vec{H}$   
 $\nabla \times \vec{H} = \epsilon (\nabla \times \vec{B})$

Solution of Maxwell's eq<sup>n</sup> in free space :-

OR  
Electromagnetic Waves in Vacuum :-

Maxwell's eq<sup>n</sup> in free space,

$$\vec{\nabla} \cdot \vec{E} = 0 \quad \text{--- (1)}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \text{--- (2)}$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \text{--- (3)}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \quad \text{--- (4)}$$

Maxwell's eq<sup>n</sup> are four first order differential eq<sup>n</sup>.  
We need to convert these first " " " into 2<sup>nd</sup> order diff. eq<sup>n</sup>.

Take the curl of eq<sup>n</sup> (iii),

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B})$$

Put the value of  $\vec{\nabla} \times \vec{B}$  from eq<sup>n</sup> (4) into this eq<sup>n</sup>,

$$\vec{\nabla} (\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$\nabla \cdot \vec{E} = 0$  from eq<sup>n</sup> (1),

$$\nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\boxed{\nabla^2 \vec{E} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0} \quad \text{--- (5)}$$

Now, Take the curl of eq<sup>n</sup> (4),

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{B}) = \mu_0 \epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{E}) \quad \text{(from (3))}$$

$$\vec{\nabla} (\vec{\nabla} \cdot \vec{B}) - \nabla^2 \vec{B} = -\mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2} \quad (\nabla \cdot \vec{B}) = 0$$

$$\boxed{\nabla^2 \vec{B} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2} = 0} \quad \text{--- (6)}$$

eq<sup>n</sup> (5) & (6) are the 2<sup>nd</sup> order diff. eq<sup>n</sup> of electric & mag. field.

All the information of 4 Maxwell eq<sup>n</sup> contained in two eq<sup>s</sup> (5 & 6)  
 eq<sup>n</sup> (5) & (6) are the Wave eq<sup>s</sup> of electric & mag. field.  
 General Wave eq<sup>n</sup>,

$$\nabla^2 f - \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2} = 0 \quad (7)$$

Compare (5) & (6) with (7)  $\Rightarrow$  We get

$$v = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = c \quad (8)$$

$c \rightarrow$  speed of light.

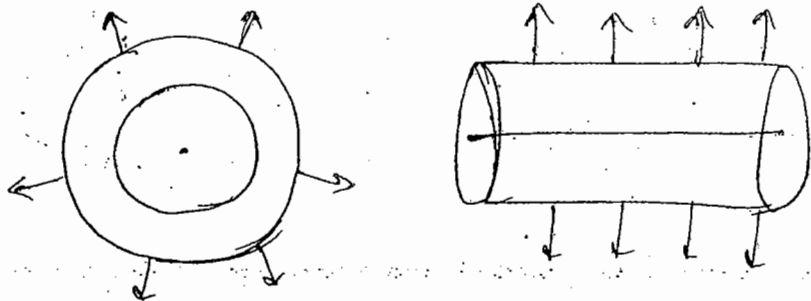
Hence, Light waves are Electromagnetic Waves.  
 They don't require any medium to propagate.

[This can't be proved if Maxwell didn't give Displacement current term]

- Solution of II<sup>nd</sup> order diff. eq<sup>n</sup> gives  $\rightarrow$  one give Ele. field & another give Mag. field. And both field depend on each other. They can not exist without each other.

Solution may be of many kind.

In Cartesian co-ordinate  $\rightarrow$  we get plane waves  
 4 spherical-polar  $\rightarrow$  spherical waves  
 4 cylindrical  $\rightarrow$  cylindrical waves



Small portion of spherical wave front & cylinder  
 is a plane. (large radius sphere)

We are interested in plane wave soln.

Plane wave sol<sup>n</sup> of  $\vec{E}$  &  $\vec{B}$

Suppose  $\vec{E}$  &  $\vec{B}$  are propagate in  $x, y, z$  dir<sup>n</sup>

$$\vec{E} = E_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\vec{B} = B_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

These sol<sup>n</sup>s must satisfy the Maxwell's eq<sup>n</sup> as they are the solution of Maxwell's eq<sup>n</sup>.

$$\vec{\nabla} \cdot \vec{E} = 0 \Rightarrow \boxed{\vec{k} \cdot \vec{E} = 0} \quad \text{--- (9)}$$

$\nabla$ -operator apply on plane wave. (it operates on space part)  
After operation it gives  $i\vec{k}$ .

& time operator gives  $-i\omega$ .

$$\boxed{\begin{array}{l} \nabla \rightarrow i\vec{k} \\ \frac{\partial}{\partial t} \rightarrow -i\omega \end{array}}$$

Vibration of  $\vec{E}$  &  $\vec{B}$  are the  $\perp^r$  to the wave propagation.  $\Rightarrow \boxed{\vec{k} \cdot \vec{B} = 0}$  --- (10) from (A) & (B)

Wave vector tells the dir<sup>n</sup> of propagation.

So  $\boxed{\vec{E} \text{ \& \ } \vec{B} \text{ are Transvers in Nature,}}$

Put the value of  $\vec{E}$  &  $\vec{B}$  in eq<sup>n</sup> (3) & (4),

$$\text{eq<sup>n</sup> (3)} \Rightarrow \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\begin{aligned} i(\vec{k} \times \vec{E}) &= -(-i\omega)\vec{B} \\ &= +i\omega\vec{B} \end{aligned}$$

$$\vec{k} \times \vec{E} = \omega\vec{B}$$

$$\Rightarrow \boxed{\vec{B} = \left( \frac{\vec{k} \times \vec{E}}{\omega} \right)} \quad \text{--- (11)}$$

As  $E \perp^r k$  &  $B \perp^r k$  so

$\vec{E}$ ,  $\vec{B}$  &  $\vec{k}$  are mutually perpendicular.

$$\text{dir<sup>n</sup> of } \vec{B} = \vec{k} \times \vec{E}$$

$$\begin{aligned} \text{Eqn (4)} \Rightarrow \nabla \times \vec{B} &= \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \\ i(\vec{k} \times \vec{B}) &= \mu_0 \epsilon_0 (i\omega) \vec{E} \\ \vec{k} \times \vec{B} &= -\mu_0 \epsilon_0 \omega \vec{E} \end{aligned}$$

$$\boxed{\vec{E} = \frac{-c^2 (\vec{k} \times \vec{B})}{\omega}} \quad \text{--- (12)}$$

When Wave vector  $\vec{k}$  & mag. field  $\vec{B}$  are given & find  $\vec{E}$  field  $\vec{E}$  then use above relation directly.

$$\text{dir}^n \text{ of } \vec{E} \rightarrow -(\vec{k} \times \vec{B})$$

from (12)  $\rightarrow \vec{E}, \vec{B}, \vec{k}$  are mutually  $\perp^r$ .

In free space, Electromag. waves are plane waves.

$$\text{Let } \begin{aligned} \vec{E} &= E \hat{x} \\ \vec{B} &= B \hat{y} \end{aligned}$$

$$\text{Hence } \vec{k} = k \hat{z}$$

$$\text{Now, } \begin{aligned} \vec{E} &= E_0 e^{i(kz - \omega t)} \hat{x} \\ \vec{B} &= B_0 e^{i(kz - \omega t)} \hat{y} \end{aligned}$$

$$(\vec{k} \cdot \vec{r} = kz)$$

$$\bullet E = E_0 e^{i(kz - \omega t)} \hat{x} \rightarrow \begin{array}{l} \text{dir}^n \text{ of } E \text{ field} \\ \text{freq. of vibration is } \omega \\ \text{of field} \end{array}$$

$\downarrow$  amplitude of wave.      $\downarrow$  dir. of propagation.  $\downarrow$   $\hat{x}$   $\downarrow$   $\hat{z}$

$$\bullet \text{ If } E = E_0 e^{i(\omega t - kz)} \hat{x}$$

still dir<sup>n</sup> of field is  $\hat{x}$  +  $\hat{z}$  propagation

• either  $(\omega t - kz)$  or  $(kz - \omega t)$  then dir<sup>n</sup> of prop. is  $\hat{x}$  +  $\hat{z}$   
i.e. b/w  $\omega t$  &  $kz$ , one plus, one minus then  $\hat{x}$  +  $\hat{z}$ .

$$\bullet \text{ If sign of } \omega t \text{ & } kz \text{ is same then dir}^n \text{ of propagation } -\hat{z}$$

i.e.  $\vec{E} = E_0 e^{i(-\omega t - kz)} \hat{x} \rightarrow -\hat{z}$   
 $= E_0 e^{i(\omega t + kz)} \hat{x} \rightarrow -\hat{z}$

\* Among wt & ka  
 same sign  $\rightarrow -\hat{z}$   
 opposite sign  $\rightarrow +\hat{z}$

Energy Density  $u$  Energy per unit volume

Electric field vector gives the Electric energy density  
 & magnetic " " " " magnetic " "  $u_m$

$$u_e = \frac{\epsilon_0}{2} \int_{\text{all space}} E^2 d\tau$$

$E \rightarrow$  Total elec. field

$$u_e = \frac{\epsilon_0}{2} E^2$$

$$\& u_m = \frac{1}{2\mu_0} \int_{\text{all space}} B^2 d\tau$$

$$u_m = \frac{B^2}{2\mu_0}$$

We have,  $\vec{B} = \frac{\vec{K} \times \vec{E}}{\omega}$

$$\begin{aligned} \vec{K} &\rightarrow K \hat{z} \\ \vec{E} &\rightarrow E \hat{x} \end{aligned}$$

$$\{\hat{z} \times \hat{x} = \hat{y}\}$$

$$\vec{B} = \frac{KE}{\omega} \hat{y}$$

$$v = \frac{\omega}{K} = \text{wave velocity (in free space)}$$

$$\text{so } \vec{B} = \frac{E}{c} \hat{y}$$

$$\therefore u_m = \frac{B^2}{2\mu_0} = \frac{E^2}{2c^2\mu_0} = \frac{E^2 \mu_0 \epsilon_0}{2\mu_0} = \frac{\epsilon_0 E^2}{2}$$

$$u_m = u_e$$

Mag. field energy = Electric field energy.

In free space, Mag. field & Ele. field carry equal energy. This energy remain in field, i.e. mag. energy remain in mag. field & e. energy remain in Ele. field.

Total Energy density  $u = u_e + u_m = \epsilon_0 E^2$

## Energy Flux or Poynting Vector ( $\vec{S}$ ) :-

Poynting Vector is defined as Energy per unit area per unit time carried by the electromagnetic wave.

OR Power per unit area is called Poynting Vector.

Unit :-  $J/m^2\text{-sec}$  or  $W/m^2$  (watt/m<sup>2</sup>)

$$\vec{S} = \vec{E} \times \vec{H}$$

$$= \frac{\vec{E} \times \vec{B}}{\mu_0}$$

$$\vec{S} = \frac{EB}{\mu_0} \hat{z}$$

dir<sup>n</sup> of  $E \rightarrow \hat{x}$   
 $B \rightarrow \hat{y}$   
( $\hat{x} \times \hat{y} \rightarrow \hat{z}$ )

$$B = \frac{E}{c} \Rightarrow \vec{S} = \frac{E^2}{\mu_0 c} \hat{z}$$

$$\vec{S} = \frac{E^2}{\mu_0 c} \times \frac{c}{c} \hat{z} = \frac{E^2 c}{\mu_0 c^2} = \frac{E^2 \mu_0 \epsilon_0 c}{\mu_0}$$

$$\vec{S} = c \epsilon_0 E^2 \hat{z}$$

$$\boxed{\vec{S} = cu \hat{z}} \quad (u = \epsilon_0 E^2)$$

This is Relation b/w Poynting vector + energy density.

$\vec{S} \rightarrow$  tells the dir<sup>n</sup> of Energy propagation.

$\vec{k} \rightarrow$  " " " " " wave " "

Generally, dir<sup>n</sup> of  $\vec{S}$  &  $\vec{k}$  matches but not every time.

In present case, dir<sup>n</sup> of  $\vec{k} = \hat{z}$   
dir<sup>n</sup> of  $\vec{S} = \hat{z}$

In free space, dir<sup>n</sup> of wave propagation is same as dir<sup>n</sup> of energy flow.

Electromag. wave not only carry the energy but also carry the momentum.



## Momentum Density of EM Waves :-

Total mom. per unit volume called Mom. density denoted by  $\vec{p}$

In free space,

$$\vec{p} = \mu_0 \epsilon_0 \vec{S}$$

$$\vec{p} = \frac{\vec{S}}{c^2} = \frac{u}{c} \hat{z}$$

 $(\vec{S} = cu)$

This is called Electromag. mom. density.

## Average Value of these quantities :-

We have, Energy density  $u = \epsilon_0 E^2$

Poynting vector  $\vec{S} = c \epsilon_0 E^2 \hat{z}$

Momentum density  $\vec{p} = \frac{\epsilon_0 E^2}{c} \hat{z}$

Now, we calculate average energy density, Average poynting vector & average mom. density over a cycle.

We know, the solutions are

$$\vec{E} = E_0 e^{i(Kz - \omega t)} \hat{x}$$

$$\vec{B} = B_0 e^{i(Kz - \omega t)} \hat{y}$$

We can write,

$$\vec{E} = E_0 \left[ \underbrace{\cos(Kz - \omega t)}_{\text{real Part}} + i \underbrace{\sin(Kz - \omega t)}_{\text{imaginary Part}} \right] \hat{x}$$

Only Real part carries the energy.

$$E^2 = \vec{E} \cdot \vec{E} = E_0^2 \cos^2(Kz - \omega t)$$

Average Value of energy density

$$\langle u \rangle = \epsilon_0 E_0^2 \langle \cos^2(Kz - \omega t) \rangle$$

Average value of  $\cos^2$  over a cycle of  $2\pi$  gives  $\frac{1}{2}$ .

so  $\langle u \rangle = \frac{1}{2} \epsilon_0 E_0^2$   $\rightarrow$  we can also write it in terms of mag. field ( $B_0$ )  $\rightarrow$  amp. of mag. field

$E_0 \rightarrow$  amplitude

This is the combination of electric & magnetic energy density

So separately,

$$\langle U_e \rangle = \frac{1}{4} \epsilon_0 E_0^2$$

$$\langle U_m \rangle = \frac{1}{4} \epsilon_0 E_0^2$$

Relation b/w elec. & mag. fields,  $B_0 = \frac{E_0}{c}$   
amplitude of

$$\Rightarrow E_0 = B_0 c$$

$$\Rightarrow E_0^2 = B_0^2 c^2$$

$$\Rightarrow E_0^2 = \frac{B_0^2}{\mu_0 \epsilon_0}$$

So  $\langle U \rangle = \frac{1}{4} \epsilon_0 E_0^2 = \frac{B_0^2}{4 \mu_0}$

Average value of Poynting vector also called Intensity  
it is the average energy per unit area per unit time associated with the EM wave.

$$\langle \vec{S} \rangle = I$$

eg. An EM wave of given intensity, incident on  $1 \text{ m}^2$  area for 10 sec then calculate energy transferred to the surface.

$$\rightarrow I = 2 \text{ J/m}^2 \text{ sec}$$

energy/unit area/unit time

$$\text{So Energy} = 2 \times 10 = 20 \text{ Joule}$$

Now,

$$\langle \vec{S} \rangle \equiv I \text{ (intensity)} \\ = c \langle U \rangle \hat{z}$$

$$\langle \vec{S} \rangle = \frac{1}{2} \epsilon_0 c E_0^2 \hat{z}$$

→ This much intensity is transfer to the surface.

This can be in another form (in terms of mag. field)

Average value of Mom. density

Mom. density → mom./unit volume,

If Mom. density of EM wave is given per unit volume & calculate mom. transfer to the given volume then

$$\langle \vec{p} \rangle = \frac{1}{2} \frac{1}{c} \epsilon_0 \langle E_0^2 \rangle$$

$$\langle \vec{p} \rangle = \frac{\epsilon_0 E_0^2}{2c}$$

This much avg. mom./unit volume will transfer to the volume.

### Radiation pressure (P)

Pressure  $\rightarrow$  force per unit area

$$P = \frac{F}{A}$$

If a surface is made of atoms contain charges & e<sup>-</sup> revolve in the orbits. If EM wave incident on the surface of atom. Then the force applied per unit area is called the radiation pressure.

force  $\rightarrow$  Rate of change of momentum  
i.e. mom. per unit time

We know the mom. density which is mom./unit volume.

i.e. if Mom. density  $\times$  volume = ~~force~~ mom.  
& ~~force~~ <sup>mom.</sup> per unit ~~area~~ <sup>time</sup> gives pressure.

$$\langle \vec{p} \rangle = \frac{1}{2} \frac{\epsilon_0 E_0^2}{c}$$

force & force/unit gives pressure.

Let Mom. transferred in time  $\Delta t$  is  $\Delta p$

$$\Delta p = \langle \vec{p} \rangle A c \Delta t$$

{ If EM wave travels with speed of light then in time  $\Delta t$  it will travel distance  $c \Delta t$ . }

Now force

$$F = \frac{\Delta p}{\Delta t} = \frac{1}{2} \frac{\epsilon_0 E_0^2}{c} \times c A$$

$$\begin{aligned} \text{time} &= \frac{\text{distance}}{\text{speed}} \\ &= \frac{c \Delta t}{c} \end{aligned}$$

$$\text{Pressure } P = \frac{F}{A} \Rightarrow \boxed{P = \frac{c}{2c} \epsilon_0 E_0^2 = \frac{I}{c}}$$

This much pressure will be on the surface due to electromag. wave.

So Radiation pressure is intensity divided by speed of light EM wave.

→ This is the radiation pressure if the ~~max~~ medium is perfectly Absorbing ( $P = \frac{I}{c}$ )

→ If surface is perfectly reflecting then pressure will be doubled.

$$P = \frac{2I}{c}$$

Note

• Metal reflects EM Waves (Mirrors are reflectors) bcoz metal contains large no. of free  $e^-$ s. so free  $e^-$ s are responsible for this reflection.

→ If we incident EM wave on a mirror then free  $e^-$  starts to vibrate with the freq. of EM wave then it will oscillate & emit radiation. (i.e.  $e^-$  Re-radiate the EM wave) in this phenomenon No time lag.

→ When EM wave incident on surface then (one) pressure <sup>produce</sup> & when it re-radiate then again there will be pressure so pressure will be doubled.

→ If for perfectly Absorbing medium, when wave re-radiate then there will be no pressure. so in this case there is single pressure.

Microwaves & EM wave they can travel with insulators.

Wave Impedance of free space :-

It is denoted by  $Z_0$ . & defined as

$$Z_0 = \left| \frac{E_0}{H_0} \right|$$

$E_0$  → Amp. of E-field

$H_0$  → Amp. of mag. field intensity.

$$B_0 = \mu H_0 \Rightarrow H_0 = \frac{B_0}{\mu}$$

$$\text{So } Z_0 = \left| \frac{E_0}{H_0} \right| = \frac{\mu_0 E_0}{B_0} = \mu_0 c = \mu_0 \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}} = 120 \cdot \pi \quad \text{This is the impedance of free space.}$$

$$Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}} = 120\pi = 377 \Omega$$

In free space,  $Z_0$  is a real quantity.

Hence  $\vec{E}$  &  $\vec{B}$  vibrates in same phase. (in free space)

$$\vec{E} = E_0 \cos(kz - \omega t) \hat{x}$$

$$\vec{B} = B_0 \cos(kz - \omega t) \hat{y}$$

There is No phase diff.

Important points of free space :-

→ EM waves are transverse in free space.

i.e.  $E \perp k$  &  $B \perp k$

$E \perp B \perp k$

They are moving with speed of light  $c$ .

→  $\vec{E}$  &  $\vec{B}$  are vibrating in same phase

→ Same energy lies in  $\vec{E}$  &  $\vec{B}$  field.

Electromagnetic waves in isotropic linear Dielectric

Medium :- for linear isotropic (dielectric medium),  $\vec{D} = \epsilon \vec{E}$

Maxwell's eq<sup>n</sup>

$$\vec{D} = \epsilon \vec{E}$$

$$\vec{B} = \mu \vec{H}$$

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$

for dielectric medium, No free charge, No free charge density.

$$\rho_f = 0$$

$$\vec{J}_f = 0$$

⇒

$$\vec{\nabla} \cdot (\epsilon \vec{E}) = 0 \Rightarrow$$

$$\vec{\nabla} \cdot \vec{E} = 0 \quad (1)$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad (2)$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad (3)$$

$$\vec{\nabla} \times \vec{B} = \mu \epsilon \frac{\partial \vec{E}}{\partial t} \quad (4)$$

Take curl of eq<sup>n</sup> (3),

$$\vec{\nabla} \times \vec{\nabla} \times \vec{E} = -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B})$$

$$\Rightarrow \nabla^2 \vec{E} - \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} = 0 \quad \text{--- (5)}$$

Take curl of eq<sup>n</sup> (4),

$$\nabla^2 \vec{B} - \mu \epsilon \frac{\partial^2 \vec{B}}{\partial t^2} = 0 \quad \text{--- (6)}$$

If we compare these (2) 2<sup>nd</sup> order eq<sup>n</sup> with original wave eq<sup>n</sup>, we get

$$\nabla^2 f - \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2} = 0 \quad \text{--- (7)}$$

We get  $v = \frac{1}{\sqrt{\mu \epsilon}} \quad \text{--- (8)}$

$$v = \frac{1}{\sqrt{\mu_0 \mu_r \epsilon_0 \epsilon_r}} = \frac{c}{\sqrt{\mu_r \epsilon_r}}$$

$$v < c$$

So in linear isotropic dielectric, speed of EM wave in that medium is less than speed of light in free space for Any transparent medium,

$$v = \frac{c}{n} \quad \text{--- (9)}$$

$n \rightarrow$  refractive index of medium,

$v \rightarrow$  wave speed

Comparing (8) & (9), we get

$$\boxed{n = \sqrt{\mu_r \epsilon_r}}$$

So refractive index of the medium can be calculated by Relative permittivity & Relative permeability.

If medium is Non magnetic  $\rightarrow \mu_r = 1$

then

$$\boxed{n = \sqrt{\epsilon_r}}$$

Now, Maxwell's eq<sup>n</sup> implies the solutions,

$$\left. \begin{aligned} \vec{k} \cdot \vec{E} &= 0 \\ \vec{k} \cdot \vec{B} &= 0 \end{aligned} \right\} \text{These eq<sup>n</sup>s implies that } \rightarrow$$

→ Inside isotropic dielectric, EM waves are transverse wave.

If  $E$  &  $k$  is given & we have to find  $B$  then

$$\boxed{\vec{B} = \frac{\vec{k} \times \vec{E}}{\omega}}$$

$$\Rightarrow \nabla \times (\vec{k} \times \vec{B}) = -\nabla \times \omega \mu \epsilon \vec{E}$$

$$\vec{E} = -\frac{1}{\mu \epsilon \omega} (\vec{k} \times \vec{B})$$

$$\boxed{\vec{E} = -\frac{v^2}{\omega} (\vec{k} \times \vec{B})}$$

$$\left\{ v = \frac{1}{\sqrt{\mu \epsilon}} \right.$$

Now, Magnitudes of  $\vec{B}$ ,

$$\boxed{|\vec{B}| = \frac{|\vec{E}|}{v}}$$

where  $\frac{\omega}{k} = v$

If wave is travelling in isotropic dielectric medium then  $\left[ \frac{\omega}{k} = v \right]$

Conclusion :-  $\vec{E} \perp \vec{B} \perp \vec{k}$  i.e. mutually  $\perp$  to each other.

→ Energy density :-

electric energy density  $u_e = \frac{\epsilon}{2} E^2$

Magnetic " " "  $u_m = \frac{B^2}{2\mu} = \frac{E^2 \mu \epsilon}{2\mu} = \frac{E^2 \epsilon}{2}$

$$u_m = \frac{1}{2} \epsilon E^2$$

$$\Rightarrow \boxed{u_e = u_m}$$

Total Energy density  $u = u_e + u_m$

$$\boxed{u = \epsilon E^2}$$

→ Poynting Vector :-  $\vec{k} \cdot \vec{E} = 0$ ,  $\vec{k} \cdot \vec{B} = 0$

$$\vec{E} = E_0 e^{i(kz - \omega t)} \hat{x}$$

$$\vec{B} = B_0 e^{i(kz - \omega t)} \hat{y}$$

$$\vec{S} = \vec{E} \times \vec{H}$$

$$= \frac{\vec{E} \times \vec{B}}{\mu} = \frac{1}{\mu v} E^2 = \frac{v}{\mu v^2} E^2$$

$$(B = E \sqrt{\mu \epsilon} = E/v)$$

$$\boxed{\vec{S} = \epsilon v E^2 \hat{z} = v u \hat{z}}$$

$$v^2 = \frac{1}{\mu \epsilon}$$

So Energy flow is in the dir<sup>n</sup> of Wave propagation.  
(dir<sup>n</sup> of wave propagation is  $\hat{z}$ )

On Comparing With free space, We get if we replace

$$\begin{aligned} \mu_0 &\rightarrow \mu \\ \epsilon_0 &\rightarrow \epsilon \\ c &\rightarrow v \end{aligned}$$

then we get, expressions for isotropic dielectric

Momentum density  $\vec{p} = \mu \epsilon \vec{S} = \frac{\mu}{v} \hat{z}$

Wave Impedence  $Z = \left| \frac{E}{H} \right| = \sqrt{\frac{\mu}{\epsilon}}$

$$Z = \sqrt{\frac{\mu_0 \mu_r}{\epsilon_0 \epsilon_r}} = 120 \pi \sqrt{\frac{\mu_r}{\epsilon_r}}$$

$$\left. \begin{aligned} \mu_r &\geq 1 \\ \epsilon_r &\geq 1 \end{aligned} \right\} Z = 120 \pi \sqrt{\frac{\mu_r}{\epsilon_r}} = \text{Real Value}$$

If  $Z$  is Real that means  $\vec{E}$  &  $\vec{B}$  are vibrating in same phase.

Conclusion :-

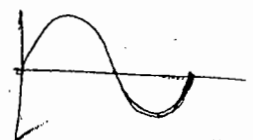
→ speed of medium  $v$  is less than  $c$ . &  $\rightarrow n = \sqrt{\mu_r \epsilon_r}$

→ for a linear isotropic dielectric medium

$$\mu_r \geq 1 \quad \& \quad \epsilon_r \geq 1$$

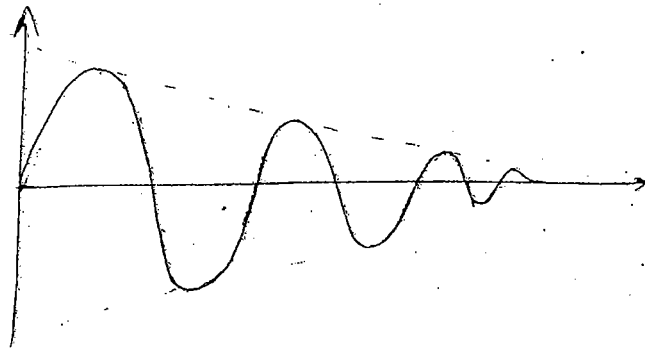
(i) If  $\epsilon_r = 1$ ,  $\mu_r = 1$  that means free space is also a dielectric medium of dielectric constant one.

(ii) If  $\epsilon_r > 1$ ,  $\mu_r > 1$  then  $n$  is real then sol<sup>n</sup> of EM will be oscillatory





(iii) If  $\epsilon_r < 0$  (-ve),  $\mu_r \geq 1 \Rightarrow n \rightarrow \text{imaginary}$   
 If  $n$  is imaginary or complex, then solution of EM wave will be damped.



If  $\epsilon_r \geq 0$ ,  $\mu_r < 0$ , Again sol<sup>n</sup>  $\rightarrow$  damped  
 (inside the conducting medium)

- In all these cases, dir<sup>n</sup> of  $\vec{S}$  &  $\vec{K}$  will be same.  
Energy flow      wave prop.

Here if  $\epsilon_r$  &  $\mu_r$  are not the func<sup>n</sup> of position then medium will be isotropic.

Note :- If  $\epsilon_r$  &  $\mu_r$  are func<sup>n</sup> of position then dir<sup>n</sup> of  $\vec{S}$  &  $\vec{K}$  are different.

Case (iv) :- If  $\epsilon_r$  &  $\mu_r$  are simultaneously negative.  
 then  $\vec{S}$  &  $\vec{K}$  are antiparallel.

$$\begin{cases} \mu = \mu_0 \mu_r \\ \epsilon = \epsilon_0 \epsilon_r \end{cases}$$

No medium exist in nature, in which both  $\epsilon_r$  &  $\mu_r$  are simultaneously -ve.

For Left Handed Material,  $\vec{S}$  &  $\vec{K}$  are antiparallel.  
 i.e. This type of medium is called L.H. material.

ES

# Electromagnetic Waves inside an Anisotropic Linear Dielectric Medium :-

Generally, for dielectrics, permeability  $\mu = \mu_0$

This medium is Anisotropic w.r to permittivity  $\epsilon$  only.  
Maxwell's eq<sup>n</sup>, Linear  $\rightarrow \vec{D} = \epsilon \vec{E}$

$\vec{\nabla} \cdot \vec{D} = \rho_f \Rightarrow \boxed{\vec{\nabla} \cdot \vec{D} = 0}$  (1) Dielectric  $\rightarrow \rho_f = 0$

$\Rightarrow \nabla \cdot (\epsilon \vec{E}) = 0$  Here  $\epsilon$  is not const.

but  $\nabla \cdot \vec{E} \neq 0$

$\boxed{\vec{\nabla} \cdot \vec{B} = 0}$  (2)

$\boxed{\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}}$  (3)

$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$

for dielectric  $\vec{J}_f = 0$

$\Rightarrow \boxed{\vec{\nabla} \times \vec{H} = \frac{\partial \vec{D}}{\partial t}}$  (4)

$\vec{\nabla} \cdot \vec{D} = 0 \Rightarrow \vec{k} \cdot \vec{D} = 0$

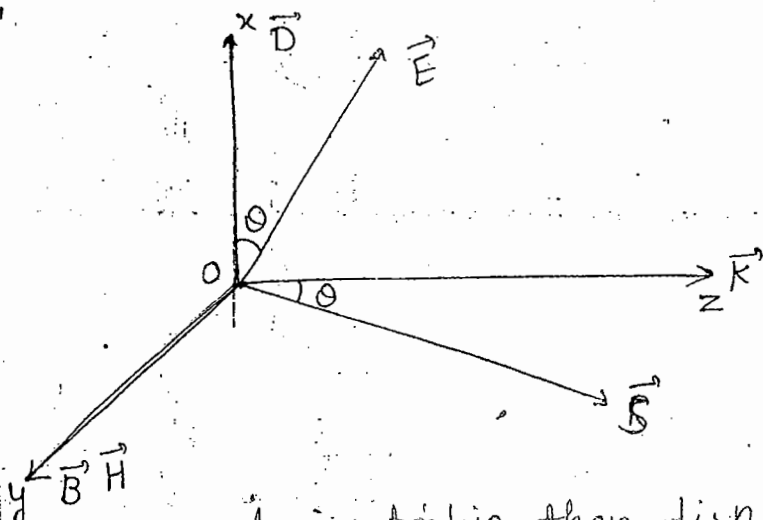
$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \vec{k} \cdot \vec{B} = 0$

i.e.  $\vec{B}$  &  $\vec{D}$  are  $\perp$  to wave propagation i.e.

$\vec{B} \perp \vec{D} \perp \vec{k}$

$\vec{S} = \vec{E} \times \vec{H}$

&  $\vec{B} = \mu_0 \vec{H}$

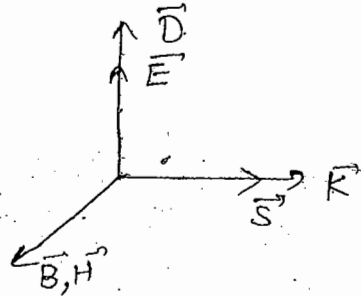


i.e. If medium is Anisotropic then dir<sup>n</sup> of energy flow is not same as wave prop.

## Main Points :-

- EM waves in Anisotropic medium are transverse w.r. to  $\vec{B}$  &  $\vec{H}$ . Not w.r. to  $\vec{E}$  &  $\vec{D}$ .
- Dir<sup>n</sup> of Energy flow is not same as the dir<sup>n</sup> of wave propagation.
- The Electric field is making angle  $\theta$  with  $\vec{D}$ . Hence  $\vec{S}$  is also making angle  $\theta$  with wave propagation  $\vec{k}$ .

for Isotropic :-



→ Doubly reflecting Systems ( $n_x \neq n_y$ ) [ref. index is not same in all dir<sup>n</sup>.] are the examples of Anisotropic medium.

## Electromag. Waves in Conducting Medium :-

Maxwell's Eq<sup>n</sup>,

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$

for a conducting medium,  $\vec{D} = \epsilon \vec{E}$  &  $\vec{B} = \mu \vec{H}$

volume free charge  $\rho_f = 0$  &  $\boxed{\vec{J}_f = \sigma \vec{E}}$

If we put any free charge in conducting medium then free charge will be on surface. No free charge can reside inside the conducting medium.

$$\vec{\nabla} \cdot \vec{D} = 0 \Rightarrow \boxed{\vec{\nabla} \cdot \vec{E} = 0} \quad \text{--- (1)}$$

$$\boxed{\vec{\nabla} \cdot \vec{B} = 0} \quad \text{--- (2)}$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad (3)$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{E} + \mu_0 \epsilon \frac{\partial \vec{E}}{\partial t} \quad (4)$$

Take curl of eq<sup>n</sup> (3),

$$\vec{\nabla} \times \vec{\nabla} \times \vec{E} = -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B})$$

$$\vec{\nabla}(\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\frac{\partial}{\partial t} [\mu_0 \vec{E} + \mu_0 \epsilon \frac{\partial \vec{E}}{\partial t}]$$

$$\nabla^2 \vec{E} = \mu_0 \frac{\partial \vec{E}}{\partial t} + \mu_0 \epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\Rightarrow \boxed{\nabla^2 \vec{E} - \mu_0 \frac{\partial \vec{E}}{\partial t} - \mu_0 \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} = 0} \quad (5)$$

Take curl of eq<sup>n</sup> (4),

$$\vec{\nabla} \times \vec{\nabla} \times \vec{B} = \mu_0 (\vec{\nabla} \times \vec{E}) + \mu_0 \epsilon \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{E})$$

$$\vec{\nabla}(\vec{\nabla} \cdot \vec{B}) - \nabla^2 \vec{B} = \mu_0 \left(-\frac{\partial \vec{B}}{\partial t}\right) + \mu_0 \epsilon \left(-\frac{\partial^2 \vec{B}}{\partial t^2}\right)$$

$$\boxed{\nabla^2 \vec{B} - \mu_0 \frac{\partial \vec{B}}{\partial t} - \mu_0 \epsilon \frac{\partial^2 \vec{B}}{\partial t^2} = 0} \quad (6)$$

eq<sup>n</sup> (5) & (6) are II<sup>nd</sup> order differential eq<sup>n</sup>s.

II<sup>nd</sup> term, of eq<sup>n</sup> (5) & (6) are damping terms, comes from damped harmonic oscillator.

$$\frac{d^2x}{dt^2} - \omega^2 x = \frac{dx}{dt}$$

Bcoz of this term, amplitude of damped harmonic oscillator is decaying.

Now, we take wave vector  $k$  is a complex quantity in the solutions of wave eq<sup>n</sup>.

$$\vec{E} = E_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\vec{B} = B_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

These solutions must satisfy the given diff. eq<sup>n</sup>.

$$(5) \Rightarrow (i\vec{k}^*)^2 \vec{E} - (-i\omega) \mu_0 \vec{E} - (-i\omega)^2 \mu_0 \epsilon \vec{E} = 0$$

$$-(k^*)^2 \vec{E} + i\omega \mu_0 \vec{E} + \mu_0 \epsilon \omega^2 \vec{E} = 0$$

(from (6) → We get same eq<sup>n</sup>)

$$(k^*)^2 = \mu \epsilon \omega^2 + i \omega \mu \sigma$$

$$k^* = [\mu \epsilon \omega^2 + i \omega \mu \sigma]^{1/2} \quad (7)$$

Wave vector is Complex.

Let  $k^* = \alpha + i\beta$

$\alpha \rightarrow$  real part  
 $\beta \rightarrow$  imaginary part

$$(k^*)^2 = \alpha^2 - \beta^2 + 2i\alpha\beta \quad (8)$$

Compare (7) & (8)  $\Rightarrow$

$$\alpha^2 - \beta^2 = \mu \epsilon \omega^2 \quad (9)$$

$$2\alpha\beta = \omega \mu \sigma \quad (10)$$

We have 2 unknowns  $\alpha$  &  $\beta$ .

$$(10) \Rightarrow \beta = \frac{\omega \mu \sigma}{2\alpha}$$

$$(9) \Rightarrow \alpha^2 - \frac{\omega^2 \mu^2 \sigma^2}{4\alpha^2} = \mu \epsilon \omega^2$$

$$4\alpha^4 - \omega^2 \mu^2 \sigma^2 = 4\mu \epsilon \omega^2 \alpha^2$$

$$4\alpha^4 - 4\mu \epsilon \omega^2 \alpha^2 - \frac{1}{4}\omega^2 \mu^2 \sigma^2 = 0$$

$$\alpha^2 = \frac{\mu \epsilon \omega^2 \pm \sqrt{(\mu \epsilon \omega^2)^2 + \omega^2 \mu^2 \sigma^2}}{2}$$

$$\alpha^2 = \frac{\mu \epsilon \omega^2 \pm \mu \epsilon \omega^2 \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2}}{2}$$

$$\alpha^2 = \frac{\mu \epsilon \omega^2}{2} \left[ 1 + \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} \right]$$

$$\Rightarrow \alpha = \omega \sqrt{\frac{\epsilon \mu}{2}} \left[ \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} + 1 \right]^{1/2} \quad (11)$$

Similarly for  $\beta$ ,  $\alpha = \frac{\omega \mu \sigma}{2\beta}$ , we get

$$4\beta^4 - \frac{\omega^2 \mu^2 \sigma^2}{4} + \mu \epsilon \omega^2 \beta^2 = 0$$

$$\Rightarrow \beta = \omega \sqrt{\frac{\epsilon \mu}{2}} \left[ \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} - 1 \right]^{1/2} \quad (12)$$

$$\vec{k}^* = k^* \hat{n}$$

$$= (\alpha + i\beta) \hat{n}$$

$$\vec{E} = E_0 e^{i[(\alpha + i\beta)(\hat{n} \cdot \vec{r}) - \omega t]}$$

$$\vec{E} = E_0 e^{-\beta(\hat{n} \cdot \vec{r})} e^{i[\alpha(\hat{n} \cdot \vec{r}) - \omega t]} \quad (13)$$

$$\vec{B} = B_0 e^{-\beta(\hat{n} \cdot \vec{r})} e^{i[\alpha(\hat{n} \cdot \vec{r}) - \omega t]} \quad (14)$$

Now Amplitude is exponentially  $\downarrow$  with space (Not with time).

Decay will be fast or slow, it will depend upon  $\beta$ .

→  $\beta$  is called Attenuation const. or coefficient.

→  $\alpha$  is propagation coefficient.

→  $\beta$  depends upon certain properties of medium,  
depends upon  $\rightarrow \epsilon, \mu, \sigma$

If medium is dielectric  $\rightarrow \sigma = 0 \rightarrow \beta \rightarrow 0$

then no attenuation in wave.

→ Attenuation in wave is due to  $\sigma$  & conductivity  $\sigma$  is due to free  $e^-$ s. { for dielectric  $\rightarrow$  No free  $e^-$  so  $\sigma = 0$  }

→ Here  $\alpha$  is like  $k$  (wave vector)

Wave Velocity  $v = \frac{\omega}{\alpha}$

$$v = \sqrt{\frac{2}{\epsilon\mu}} \left[ \sqrt{1 + \left(\frac{\sigma}{\omega\epsilon}\right)^2} + 1 \right]^{-1/2}$$

This is the wave velocity inside the conducting medium

If we put  $\sigma = 0$  then we get expression for dielectric.

$$v = \sqrt{\frac{2}{\epsilon\mu}} \frac{1}{\sqrt{2}}$$

$$v = \frac{1}{\sqrt{\mu\epsilon}}$$

Wave velocity is decreased as compared to dielectric.

## Distinction b/w Good Conductors & Bad Conductors :-

Conductor is good or bad - It depends upon its

→ Conductivity ( $\sigma$ )

→ Relaxation time ( $\tau$ )

If we put a free <sup>static</sup> charge inside the conductor then how quickly that charge come out to the surface - that time will be the Relaxation time.

If conductor is bad, Its relaxation time will be more, it take more time to come out to the surface.

Relaxation time is given by permittivity to conductivity ratio.

$$\tau = \frac{\epsilon}{\sigma}$$

Now If we fall an EM wave over a conductor, we know  $\vec{E}$  inside the conductor is 0. So amplitude of EM wave inside the conductor must be zero. This  $\vec{E}$  field is not electrostatic, it is dynamic (changing with time) here  $\omega$  is the freq. of oscillation of Elec. & mag. field.

$\tau$  will

So Conductor is good or bad → it is Not only depend of  $\sigma$  &  $\tau$  but also depend on freq.  $\omega$ .

→ If a conductor is good for a particular freq.  $\omega$ , It may be bad for some another freq.

$$\text{If } \tau \ll \frac{1}{\omega}$$

⇒ Good Conductor

$$\text{If } \tau \gg \frac{1}{\omega} \Rightarrow \text{Bad Conductor}$$

$$(i) \Rightarrow \frac{\epsilon}{\sigma} \ll \frac{1}{\omega} \Rightarrow \frac{\sigma}{\epsilon\omega} \gg 1 \Rightarrow \text{good conductor}$$

$$(ii) \Rightarrow \frac{\sigma}{\epsilon\omega} \ll 1 \Rightarrow \text{bad conductor}$$

Inside the conductor, free volume charge density.

$$\rho_f = 0$$

At  $t=0$ , we put  $\rho_f$  inside conductor & after some time  $\rho_f$  becomes 0. We have to find that time in which  $\rho_f$  becomes 0 from  $\rho_f$ .

Use Continuity eqn,

$$\nabla \cdot \vec{J}_f = -\frac{\partial \rho_f}{\partial t}$$

We have,  $J_f = \sigma E$

$$\text{So } \sigma (\nabla \cdot \vec{E}) = -\frac{\partial \rho_f}{\partial t}$$

$$\Rightarrow \frac{\sigma}{\epsilon} \rho_f = -\frac{\partial \rho_f}{\partial t}$$

$$\Rightarrow \frac{\partial \rho_f}{\rho_f} = -\frac{\sigma}{\epsilon} dt$$

$$\Rightarrow \ln \rho_f(t) = -\frac{\sigma}{\epsilon} t + C$$

At time  $t=0$ ,  $C = \ln \rho_f(0)$

$$\Rightarrow \ln \rho_f(t) = -\frac{\sigma}{\epsilon} t + \ln \rho_f(0)$$

$$\Rightarrow \ln \frac{\rho_f(t)}{\rho_f(0)} = -\frac{\sigma}{\epsilon} t$$

$$\Rightarrow \rho_f(t) / \rho_f(0) = e^{-\frac{\sigma}{\epsilon} t}$$

$$\Rightarrow \boxed{\rho_f(t) = \rho_f(0) e^{-\frac{\sigma}{\epsilon} t}}$$

with time exponential

It defines - How the free charge decays inside the conductor.

If we have a Perfect Conductor,

$$\sigma = \infty$$

So free charge inside = 0

Relaxation time  $\tau = \frac{\epsilon}{\sigma}$  (if  $\sigma = \infty$ )

$$\boxed{\tau = 0}$$

i.e. No time lag in putting the charge & come out to the surface.



for Insulator  $\sigma = 0$

$$\tau = \frac{\epsilon}{\sigma} = \infty$$

i.e. charge take  $\infty$  time to come out to the surface.

i.e. It can never come out to the surface.

Note :-  $\nabla \cdot \vec{D} = \rho_f$  is valid for every medium.

$\nabla \cdot (\epsilon \vec{E}) = \rho_f$  " " only for isotropic medium.

for semiconductor

Conductivity is small but finite.

$\sigma =$  very small

so  $\tau =$  large

i.e. It will take more time to come out.

•  $\nabla \cdot \vec{E} = 0$  is valid only for perfect conductor.

Wave velocity inside good & bad conductor :-

$$V_{\text{good}} = \frac{\omega}{\alpha}$$

$$\alpha = \omega \sqrt{\frac{\epsilon \mu}{2}} \left[ \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} + 1 \right]^{1/2}$$

for good,  $\frac{\epsilon}{\sigma} \ll \frac{1}{\omega} \Rightarrow \frac{\sigma}{\epsilon \omega} \gg 1$  so neglect 1 as compare to  $\frac{\sigma}{\epsilon \omega}$

$$\beta = \omega \sqrt{\frac{\epsilon \mu}{2}} \left[ \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} - 1 \right]^{1/2}$$

$$\alpha_{\text{good}} = \beta_{\text{good}} = \omega \sqrt{\frac{\epsilon \mu}{2}} \left(\frac{\sigma}{\omega \epsilon}\right)^{1/2}$$

$$= \sqrt{\omega} \sqrt{\frac{\epsilon \mu}{2}} \left(\frac{\sigma}{\epsilon \omega}\right)^{1/2} = \sqrt{\frac{\sigma \omega \mu}{2}}$$

$$V_{\text{good}} = \frac{\omega}{\alpha} = \sqrt{\frac{2\omega}{\sigma \mu}}$$

for bad cond.  $\frac{\sigma}{\epsilon \omega} \ll 1$

$$V_{\text{bad}} = \frac{\omega}{\alpha}$$

$$\alpha_{\text{bad}} = \omega \sqrt{\epsilon \mu}$$

$$v_{\text{bad}} = \frac{\omega}{\omega \sqrt{\epsilon \mu}}$$

$$v_{\text{bad}} = \frac{1}{\sqrt{\epsilon \mu}}$$

This is similar to velocity inside the dielectric medium.

## Skin Depth ( $\delta$ ) :-

If we incident EM wave on conductor. Inside the conductor, near the surface E-field is not zero but

It will travel some distance & then E-field become zero.

Skin depth is the distance at which amplitude of EM wave become  $1/e$  value of the value at the surface.

If E-field at surface is  $E_0$  then after travelling some distance i.e. skin depth, it become  $\frac{E_0}{e}$ .

More is  $\beta$ , less is the skin-depth.

$$\delta = \frac{1}{\beta}$$

Skin-depth of free space :- is  $\infty$ .

In free-space there is no decay in amp. of wave.

For Good Conductor,

$$\delta_{\text{good}} = \frac{1}{\beta} = \sqrt{\frac{2}{\sigma \omega \mu}}$$

for Bad Conductor,

(means it is Insulator)

$$\delta_{\text{bad}} = \infty \quad \text{for perfect insulator } \left( \begin{array}{l} \sigma = 0 \\ \beta = 0 \end{array} \right)$$

for perfect dielectric (it is a " " )

If conductivity is finite but very small then there will be some skin depth. There will be decay

so  $\delta$  will be finite.

$$\beta = \omega \sqrt{\frac{\epsilon \mu}{2}} \left[ \sqrt{1 + \left(\frac{\sigma}{\epsilon \omega}\right)^2} - 1 \right]^{1/2}$$

$$= \omega \sqrt{\frac{\epsilon \mu}{2}} \frac{1}{\sqrt{2}} \left(\frac{\sigma}{\epsilon \omega}\right) = \frac{\sigma}{2} \sqrt{\frac{\mu}{\epsilon}}$$

$$\delta_{\text{bad}} = \frac{1}{\beta_{\text{bad}}} = \frac{2}{\sigma} \sqrt{\frac{\epsilon}{\mu}}$$

{ for perfect insulator,  $\sigma = 0$  so  $\delta = \infty$  }

Phase :- If wave impedance is complex, it defines the phase difference b/w  $\vec{E}$  &  $\vec{B}$ .

$$Z = \left| \frac{E}{H} \right| = \frac{\mu E}{B} = \frac{\mu \omega}{k^*} \quad \left\{ \frac{E}{B} = v = \frac{\omega}{k^*} \right.$$

$$= \frac{\mu \omega}{(\alpha + i\beta)} = \text{Complex quantity}$$

Inside the conducting medium  $\vec{E}$  &  $\vec{B}$  are out of phase.

We know  $k^* = \alpha + i\beta = k e^{i\phi}$

where  $k \rightarrow \text{Amp.} \Rightarrow k = (\alpha^2 + \beta^2)^{1/2}$

$\phi \rightarrow$  phase difference  $\Rightarrow \tan \phi = \frac{\beta}{\alpha}$

We know that

$$\alpha = \omega \sqrt{\frac{\epsilon \mu}{2}} \left[ \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} + 1 \right]^{1/2}$$

$$\beta = \omega \sqrt{\frac{\epsilon \mu}{2}} \left[ \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} - 1 \right]^{1/2}$$

so  $k = (\alpha^2 + \beta^2)^{1/2} = \left[ \omega \sqrt{\frac{\epsilon \mu}{2}} \left( \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} + 1 \right)^{1/2} + \omega \sqrt{\frac{\epsilon \mu}{2}} \left( \sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} - 1 \right)^{1/2} \right]^2$

$$k = \omega \sqrt{\mu \epsilon} \left[ 1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2 \right]^{1/4}$$

and  $\tan \phi = \frac{\beta}{\alpha}$

$$\phi = \tan^{-1} \left( \frac{\sigma}{\omega \epsilon} \right)$$

This is the phase diff. b/w  $\vec{E}$  &  $\vec{B}$ . If  $\sigma = 0$  then  $\phi = 0$  i.e. No phase diff.

We have  $\vec{B} = \frac{\vec{k} \times \vec{E}}{\omega}$

$$\left\{ \begin{array}{l} \vec{k} = k \hat{z} \\ \vec{E} = E \hat{x} \\ \text{so } \vec{B} \text{ will be in } \hat{y} \end{array} \right.$$

$$\vec{B} = \frac{k^* E}{\omega} \hat{y} e^{-p(\hat{n} \cdot \vec{r})}$$

$$\vec{B} = \frac{k e^{i\phi}}{\omega} E_0 e^{i(kz - \omega t)} \hat{y}$$

$$\left\{ \begin{array}{l} k^* = k e^{i\phi} \\ E = E_0 e^{i(kz - \omega t)} \end{array} \right.$$

On putting the values of  $k$ , we get

$$\vec{B} = \sqrt{\mu \epsilon} \left[ 1 + \left( \frac{\sigma}{\omega \epsilon} \right)^2 \right]^{1/4} E_0 e^{i[kz - (\omega t - \phi)]} \hat{y}$$

Phase of  $\vec{E} = (kz - \omega t)$

$$\vec{B} = [kz - (\omega t - \phi)]$$

→  $\vec{B}$  is lagging behind  $\vec{E}$  by phase diff.  $\phi$  i.e.  $\vec{E}$  is leading by  $\phi$ .

→ The amplitude of  $\vec{B}$  is greater than  $\vec{E}$  (as  $\frac{\sigma}{\omega \epsilon} \gg 1$ )  
 becoz, Amp of  $\vec{B}$  contains amp. of  $\vec{E}$  & also a quantity multiplied by amp. of  $E$  (which the quantity is greater than 1)

→  $E$  decays faster that's why its amp. is small.

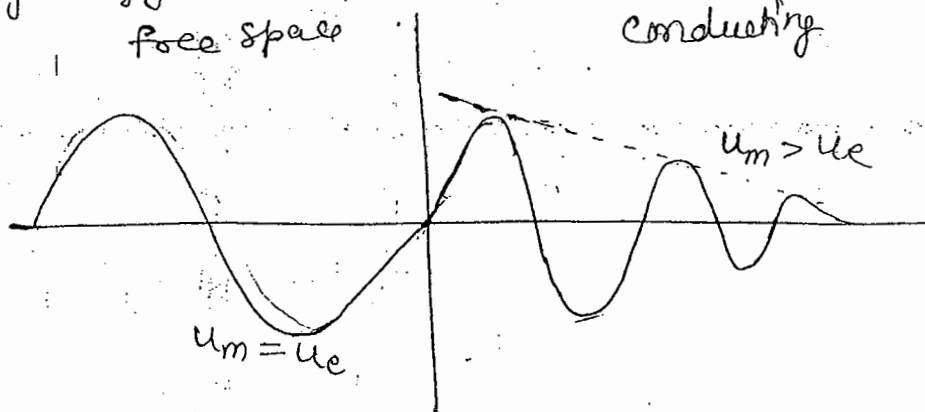
→ Energy density -

$$u_m > u_e$$

At any particular distance

$$u_m \propto B^2 \text{ \& } u_e \propto E^2$$

i.e. mag. energy density is greater than electric energy density.



→ Poynting Vector

$$\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu} \hat{z}$$

$$\begin{array}{l} \because \vec{E} \rightarrow \hat{x} \\ \therefore \vec{B} \rightarrow \hat{y} \\ \therefore \vec{S} \rightarrow \hat{z} \end{array}$$

ie. dir<sup>n</sup> of energy flow is same as dir<sup>n</sup> of wave propagation.

We have  $\vec{B} = \frac{\vec{k}}{\omega} \vec{E}$ .

$$\frac{\vec{B}}{E} = \sqrt{\mu\epsilon} \left[ 1 + \left( \frac{\sigma}{\omega\epsilon} \right)^2 \right]^{1/4}$$

so  $\vec{S} = \sqrt{\frac{\epsilon}{\mu}} \left[ 1 + \left( \frac{\sigma}{\omega\epsilon} \right)^2 \right]^{1/4} E^2 \hat{z}$

$$\vec{S} = \sqrt{\frac{\epsilon}{\mu}} \left[ 1 + \left( \frac{\sigma}{\omega\epsilon} \right)^2 \right]^{1/4} E_0^2 e^{-2\beta z} \left[ e^{2i(kz - \omega t)} \right] \hat{z}$$

### Conclusions in conducting medium

① → Ele. & mag. field amplitude decays exponentially.

$$E_0 e^{-\beta z} = \boxed{E_0 e^{-\frac{z}{\delta}}}$$

$$\left( \delta = \frac{1}{\beta} \right)$$

$$\vec{k} = k \hat{n}$$

$\hat{n}$  = dir<sup>n</sup> of prop.

$$(\hat{\sigma} \cdot \hat{n} = \hat{z})$$

e.g. - given that the skin depth for a certain material  $\delta = 10 \text{ nm}$ . Calculate the amp. of  $\vec{E}$  after 100nm distance into the conductor.

$E_0$  - field at surface.

$z$  → distance travelled into the medium.

$$E_0 e^{-\frac{z}{\delta}} = E_0 e^{-\frac{100 \text{ nm}}{10 \text{ nm}}} = E_0 e^{-10}$$

$e^{-10}$  → very very small (negligible)

\* If skin depth is given & find the amp. after a distance the use above formula.

② →  $E \perp k, B \perp k$

i.e.  $\boxed{E \perp B \perp k}$

EM waves are transverse.

③ → There is a phase diff. b/w  $\vec{E}$  &  $\vec{B}$  fields.

$\vec{E}$  leading in phase by angle  $\phi = \frac{1}{2} \tan^{-1} \left( \frac{\sigma}{\omega\epsilon} \right)$

④ →  $u_m \neq u_e$  but  $u_m > u_e$

do most of the energy lies in the mag. field

& decay of  $u$  is  $\boxed{u \propto e^{-\frac{2z}{\delta}}}$

⑤  $\vec{S} = \vec{K}$

i.e. dir<sup>n</sup> of Energy flow is along the dir<sup>n</sup> of wave propagation

i.e.  $\vec{S} \propto e^{-2z/\delta}$

Relation b/w Conduction Current density & Displacement

Current Density :- for a medium having conductivity  $\sigma$  & per-

mittivity  $\epsilon$  then  $\vec{J}_c = \sigma \vec{E}$   
 $\vec{J}_d = \epsilon \frac{\partial \vec{E}}{\partial t}$

If we incident a electromag. wave over such a medium

$\vec{E} = E_0 e^{i(kz - \omega t)} \hat{x}$

then

$\vec{J}_c = \sigma \vec{E}$

$\vec{J}_d = \epsilon(-i\omega) \vec{E}$

Then

$\frac{J_c}{J_d} = \frac{\sigma}{\epsilon(-i\omega)}$

$\left| \frac{J_c}{J_d} \right| = \left| \frac{\sigma}{\omega \epsilon} \right|$

for good conductor,  $\frac{\sigma}{\omega \epsilon} \gg 1$

so  $J_c \gg J_d$

for poor conductor,  $\sigma$  is less  $\frac{\sigma}{\omega \epsilon} \ll 1$

so  $J_c \ll J_d$

{ e.g. for a metal,  $J_c = 10^6 \text{ A/m}^2$  &  $J_d = 10 \text{ A/m}^2$  then }  
 it is good conductor.

If  $\sigma \uparrow$  then  $J_c \uparrow$  (more)

If  $\epsilon \uparrow$  or  $\omega \uparrow$  then  $J_d \uparrow$

i.e.  $J_c \rightarrow$  depend on conductivity

$J_d \rightarrow$  " " " " permittivity & freq.

## Propogation of EM Wave in Plasma

Plasma is the collection of charge particle, neutral particles & ions. It can consist of +ve & -ve ions.

Its cond<sup>n</sup> is that one of the charge type must be mobil

Plasma contains equal concentration of +ve & -ve ions.  
So Plasma as a whole is Neutral.

(One of charge type must be mobile but if both type mobile  $\rightarrow$  then no problem)

Plasma is found - in upper side of atmosphere

Ionosphere contains plasma.

Plasma can be made in laboratory.

Use - Plasma is used in Communication. It can reflect only few freq. EM waves.

It can be if we incident some EM wave on ionosphere, it will be reflected back if  $\omega < \omega_p$   
i.e. freq. of EM-wave is less than a particular freq. called plasma freq. ( $\omega_p$ )

$\omega_p \rightarrow$  depends on free charge carrier concentration.

So ionosphere can reflect radio waves but can not reflect visible waves. ( $\omega > \omega_p$ )

## Conductivity of Plasma Medium - Conditions of 2 types -

1) Static Conductivity

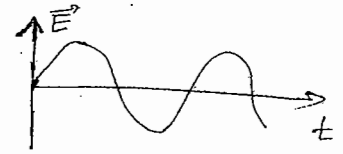
2) Dynamical

Static Conductivity :- static means if we apply a const. elec. field on a conductor then its conductivity will be

$$\sigma_s = \frac{n e^2 \tau}{m}$$

$n \rightarrow$  no. of free  $e^-$  per unit volume,  $e \rightarrow e^-$  charge  
 $\tau \rightarrow$  relaxation time,  $m \rightarrow e^-$  mass

Dynamical Cond. :- When we apply a variable E. field (i.e. varying with time) then on a conductor then its conductivity will be variable with freq. (Not const.). This is called Dynamical conductivity.



$$\sigma_d = \frac{ine^2}{m\omega}$$

$\omega \rightarrow$  freq.

Total Conductivity,

$$\begin{aligned}\sigma_{\text{Total}} &= \sigma_s + \sigma_d \\ &= \frac{ne^2\tau}{m} + \frac{ine^2}{m\omega} \\ &= \frac{ne^2}{m} \left( \tau + \frac{i}{\omega} \right)\end{aligned}$$

$$\sigma_{\text{Total}} = \frac{ne^2}{m(\gamma - i\omega)} = \frac{ne^2}{m\left(\frac{1}{\tau} - i\omega\right)}$$

$\gamma \rightarrow$  damping factor.

$$\sigma_{\text{Total}} = \frac{ne^2\tau}{m(1 - i\omega\tau)}$$

This is the total cond<sup>n</sup> of any conducting material.

For Static Conductivity,  $\omega = 0$ , cond<sup>n</sup> reduces to then  $\sigma_s = \frac{ne^2\tau}{m}$

Metal is also like plasma - In metal, there are +ve & -ve ions. One of charge type must be mobile. But in actual plasma, charge types ( $e^-$ ) move ( $e^+$ ) freely. & in metal, charge move freely but during moving they scattered with each other. & due to this relaxation time comes.

Ionosphere contains dilute plasma so  $e^-$  are completely free. so there is No relaxation time i.e. No damping.

$\Rightarrow$  So Conductivity of a ionosphere or plasma is

$$\sigma_d = \frac{ine^2}{m\omega}$$



For ionosphere or plasma medium, we have to put the value of  $\sigma$  (this is the diff. from conducting medium)

Maxwell's eq<sup>n</sup>,

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$

Inside the plasma  $\rightarrow$  no free charge so  $\rho_f = 0$   
 i.e. if we put some external free charge then it will go on surface of plasma.

For Dilute plasma i.e. for Ionosphere,

$$\epsilon \simeq \epsilon_0$$

$$\mu \simeq \mu_0$$

$$\Rightarrow \vec{\nabla} \cdot \vec{E} = 0 \quad \text{--- (1)}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \text{--- (2)}$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \text{--- (3)}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \sigma \vec{E} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \quad \text{--- (4)}$$

$$\vec{J}_f = \sigma \vec{E}$$

$$\vec{D} = \epsilon_0 \vec{E}$$

Taking curl of eq<sup>n</sup> (3) & put the value of  $\vec{\nabla} \times \vec{B}$  from (4)  
 We get

$$\nabla \times \nabla \times \vec{E} = -\frac{\partial (\nabla \times \vec{B})}{\partial t}$$

$$\nabla (\nabla \cdot \vec{E}) - \nabla^2 \vec{E} = -\frac{\partial}{\partial t} \left[ \mu_0 \sigma \vec{E} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right]$$

$$\nabla^2 \vec{E} - \mu_0 \sigma \frac{\partial \vec{E}}{\partial t} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0 \quad \text{--- (5)}$$

Now take curl of (4), We get

$$\nabla^2 \vec{B} - \mu_0 \sigma \frac{\partial \vec{B}}{\partial t} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2} = 0 \quad \text{--- (6)}$$

The sol<sup>n</sup> is  $\vec{E} = E_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$  Put in (5),

$$\nabla \rightarrow iK, \quad \frac{\partial}{\partial t} \rightarrow -i\omega$$

$$\epsilon^n(\vec{r}) \Rightarrow -k^2 \vec{E} + i\mu_0 \sigma \omega \vec{E} + \mu_0 \epsilon_0 \omega^2 \vec{E} = 0$$

$$\Rightarrow k^2 = i\mu_0 \sigma \omega + \mu_0 \epsilon_0 \omega^2$$

Put  $\sigma = \frac{ine^2 n}{m\omega}$

$$k^2 = -\frac{ne^2 \mu_0}{m} + \mu_0 \epsilon_0 \omega^2$$

$$= \mu_0 \epsilon_0 \omega^2 \left[ 1 - \frac{ne^2}{m \epsilon_0 \omega^2} \right]$$

where  $\omega_p = \left( \frac{ne^2}{\epsilon_0 m} \right)^{1/2}$  is called Plasma freq. (7)

$$k^2 = \frac{\omega^2}{c^2} \left[ 1 - \frac{\omega_p^2}{\omega^2} \right]$$

$$k = \frac{\omega}{c} \left[ 1 - \frac{\omega_p^2}{\omega^2} \right]^{1/2} \quad \text{--- (8)}$$

$k \rightarrow$  propagation coeff. or Amp. of wave vector

$\omega \rightarrow$  freq. of EM wave

(i)  $\omega_p \rightarrow$  plasma freq., it is the property of medium it depend on  $e^-$  concentration (power  $1/2$ )

$$\omega_p \propto n^{1/2}$$

(i) If any EM wave have freq  $\omega$  & ( $\omega < \omega_p$ ) then

$\omega < \omega_p$ ,  $k \rightarrow$  imaginary  $\rightarrow$  No propagation

if  $k$  is imaginary then ref. index will be imaginary.

& if ref. index is imaginary then wave propagation through that medium is Not possible & wave will be damped.

Wave can not propagate so it will reflect and go back into original medium.

All the EM wave having freq.  $\omega < \omega_p$  can not travel through Plasma

(ii) If  $\omega > \omega_p$ ,  $k \rightarrow$  Real,  $n \rightarrow$  real

So wave will propagate.  $\rightarrow$  propagation

## Refractive Index of plasma medium -

$$n = \frac{c}{v}$$

$$\text{and } v = \frac{\omega}{k} = c \left[ 1 - \frac{\omega_p^2}{\omega^2} \right]^{-1/2} \quad (\text{from 8})$$

$$\text{So } n = \frac{c}{c} \left[ 1 - \frac{\omega_p^2}{\omega^2} \right]^{1/2}$$

$$n = \left[ 1 - \frac{\omega_p^2}{\omega^2} \right]^{1/2}$$

(for  $\omega < \omega_p$  then  $n \rightarrow$  imaginary) (Real) [if  $\omega > \omega_p$  then  $n \rightarrow$  real]

## Expression for Cut off frequency in Plasma medium -

Plasma freq. is behaving like Cut off freq.

If  $\omega < \omega_p \rightarrow$  wave can not propagate

$\omega > \omega_p \rightarrow$  wave can propagate

∴ Plasma medium is High Pass filter.

$$\omega_p = \left( \frac{ne^2}{\epsilon_0 m} \right)^{1/2}$$

$$\text{Linear Plasma freq. } f_p = \frac{\omega_p}{2\pi} = \frac{1}{2\pi} \left( \frac{ne^2}{\epsilon_0 m} \right)^{1/2}$$

$n, e, \epsilon_0, m \rightarrow$  all const. ∴  $f_p \rightarrow$  const.

$f_c \rightarrow$  cut off freq.  $f_p = f_c = \frac{1}{\sqrt{\mu}}$

$n \rightarrow$  no. of  $e^-$  per meter<sup>3</sup> [ $m^{-3}$ ] (in M.K.S.)

## Maximum Penetration (skin) depth for plasma -

$$S_{\text{max}} = \frac{c}{\omega_p}$$

{ Wood - skin depth is mostly used for metals }

Q Find the skin depth for a typical metal  $\sigma = 10^7 \Omega^{-1} m^{-1}$  in visible range  $\omega = 10^{15} / \text{sec}$ . Assuming  $\epsilon \approx \epsilon_0$  &  $\mu \approx \mu_0$  & define why metals are opaque. Also find the phase diff. b/w Electric & magnetic field in this metal.

$$\sigma = 10^7 \Omega^{-1} m^{-1}$$

$$\omega = 10^{15} / \text{sec}$$

It is a good conductor, & for good conductor, skin depth

$$\delta_{\text{good}} = \sqrt{\frac{2}{\sigma \omega \mu}} = \sqrt{\frac{2}{10^7 \times 10^{15} \times 4\pi \times 10^{-7}}}$$

$$= \sqrt{\frac{10^{-16} \times 10}{2\pi}} = \sqrt{\frac{5}{\pi}} \times 10^{-8} \text{ m}$$

$$= 1.3 \times 10^{-8} \text{ m}$$

$$\delta_{\text{good}} = 13 \text{ nm}$$

Now why metal is opaque  $\Rightarrow$

at energy 13 nm, amp. decay by  $1/e$ . Hence amplitude decay very fast. So electromag. wave can not pass through the metal. Hence metals are opaque. But it has some limit.

$\omega > \omega_p$  then medium is transparent.

$\omega < \omega_p$ , medium is opaque.

- Reflectivity of any metal remain constant upto UV region but beyond UV region it will fall drops.

Hence transmittance is also const. upto UV region.

$$R + T = 1$$

Reflectivity drops means transmittance increases.

- Hence, for X-rays &  $\gamma$ -rays, we can not make the mirrors. Because No metal exist which can reflect X-rays &  $\gamma$ -rays.

Visible  $\rightarrow$  UV  $\rightarrow$  X-ray  $\rightarrow$   $\gamma$ -ray.

- X-rays can be reflected from an atomic plane but not by metal surface.  $R \approx 1$ ,  $T \approx 0$

$$\phi = \frac{1}{2} \tan^{-1} \left( \frac{\sigma}{\omega \epsilon} \right)$$

$$= \frac{1}{2} \tan^{-1} \left[ \frac{10^7 \Omega^{-1} m^{-1}}{10^{15} / \text{sec} \times 8.85 \times 10^{-12}} \right]$$

$$= \frac{1}{2} \tan^{-1} (10^3) = \frac{1}{2} \times (89)$$

{89 ≈ 90}

$$\approx \frac{1}{2} \frac{\pi}{2} \approx \frac{\pi}{4}$$

$$\boxed{\phi \approx 45^\circ}$$

Phase diff. b/w  $\vec{E}$  &  $\vec{B}$  inside a good conductor is approximately 45°.

ie.  $\vec{E}$  leads  $\vec{B}$  by 45°.

Q. In free space an electromagnetic wave is given by

$$\vec{E} = 20 \cos(\omega t - 50x) \hat{y} \text{ V/m}$$

Calculate

(i)  $\vec{B}$  (ii)  $\vec{J}_d$  (iii)  $\omega$

$$\vec{E} = 20 \cos(\omega t - 50x) \hat{y}$$

$$\vec{B} = \frac{\vec{k} \times \vec{E}}{\omega} \Rightarrow \frac{\omega}{k} = c \text{ then } \vec{B} = \frac{E}{c}$$

$$\vec{k} = 50 \hat{x}$$

$$\frac{\omega}{|k|} = c = 3 \times 10^8 \text{ m/sec}$$

$$\omega = 3 \times 10^8 \times 50 = \underline{1.5 \times 10^{10} / \text{sec}} \text{ Hz}$$

$$\vec{B} = \frac{20 \cos(\omega t - 50x) \hat{z}}{3 \times 10^8}$$

$$\vec{B} = \frac{2}{3} \times 10^{-7} \cos(\omega t - 50x) \hat{z} \text{ Wb/m}^2$$

$$\vec{J}_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t} = -\epsilon_0 20 \sin(\omega t - 50x) \cdot \omega$$

$$\vec{J}_d = -20 ($$

$$\vec{J}_d =$$

$$\text{A/m}^2$$

Q. An EM wave in free space is given by

$$\vec{E} = (10\hat{y} + 5\hat{z}) \cos(\omega t + 2y - 4z) \text{ V/m}$$

Calculate (i)  $\vec{B}$  (ii)  $\vec{k}$  (iii)  $\omega$  (iv)  $\vec{J}_d$

$$\begin{aligned} \vec{E} &= (10\hat{y} + 5\hat{z}) \cos(\omega t + 2y - 4z) \\ &= (10\hat{y} + 5\hat{z}) \cos[\omega t - \{(2\hat{y} + 4\hat{z}) \cdot (x\hat{x} + y\hat{y} + z\hat{z})\}] \end{aligned}$$

$$\therefore \vec{k} = -2\hat{y} + 4\hat{z} \quad \left\{ \cos(\omega t - \vec{k} \cdot \vec{r}) \text{ \& } \vec{r} = x\hat{x} + y\hat{y} + z\hat{z} \right\}$$

This is lying in y-z plane.

$$(ii) |\vec{k}| = \sqrt{4+16} = \sqrt{20} = 2\sqrt{5}$$

In free space, the wave velocity is

$$v = \frac{\omega}{k} = c$$

$$(iii) \Rightarrow \frac{\omega}{|\vec{k}|} = c \Rightarrow \omega = 3 \times 10^8 \times 2\sqrt{5}$$

$$\omega = 6\sqrt{5} \times 10^8 \text{ rad/sec.}$$

Now (i)  $\vec{B} = \frac{\vec{k} \times \vec{E}}{\omega}$

$$\therefore \vec{k} \times \vec{E} = (-10\hat{x} - 40\hat{x}) \cdot \cos(6\sqrt{5} \times 10^8 t + 2y - 4z)$$

$$\vec{B} = \frac{-50\hat{x}}{6\sqrt{5} \times 10^8} \cos(6\sqrt{5} \times 10^8 t + 2y - 4z)$$

$$\boxed{\vec{B} = \frac{5\sqrt{5}}{3 \times 10^8} \cos(6\sqrt{5} \times 10^8 t + 2y - 4z) (-\hat{x}) \text{ Wb/m}^2}$$

$$(ii) \vec{J}_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

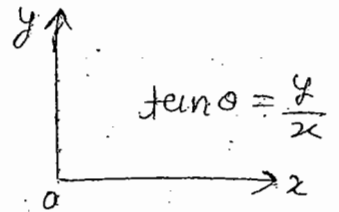
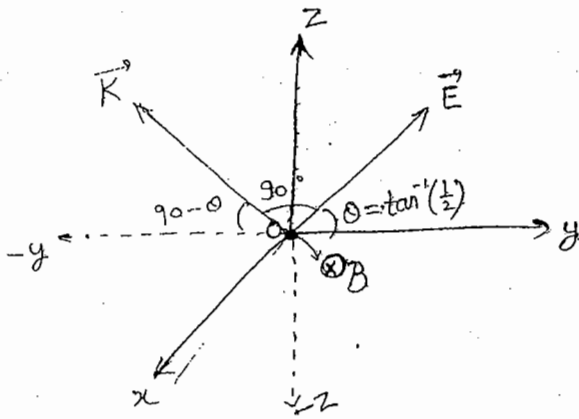
$$= \epsilon_0 (10\hat{y} + 5\hat{z}) [-\sin(\omega t + 2y - 4z)] \times \omega$$

$$\boxed{\vec{J}_d = -\epsilon_0 (10\hat{y} + 5\hat{z}) [6\sqrt{5} \times 10^8] \sin(\omega t + 2y - 4z)}$$

Poynting vector  $\rightarrow$

$$\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0}$$

dir<sup>n</sup> of  $\vec{S}$  is same as dir<sup>n</sup> of  $\vec{k}$ .



$$\vec{E} = 10\hat{y} + 5\hat{z}$$

$$\tan \theta = \frac{10}{5} = \frac{2}{1}$$

$$\theta = \tan^{-1}(2)$$

Mag. field is into the page. { Angle b/w  $\vec{E}$  &  $\vec{K}$  =  $90^\circ$  (in free space)

Q. Mag. field of an EM wave is given by  $\vec{B}(x, y, z, t) = B_0 \sin\left[\frac{(x+y)k}{\sqrt{2}} + \omega t\right] \hat{k}$  is given in free space. Find  $\vec{E}$  and  $\vec{S}$ . Graphical rep<sup>n</sup> = ?

$$\vec{B}(x, y, z, t) = B_0 \sin\left[\frac{(x+y)k}{\sqrt{2}} + \omega t\right] \hat{k}$$

$$= B_0 \sin\left[-\frac{(-x-y)k}{\sqrt{2}} + \omega t\right] \hat{k}$$

Standard form  $\vec{B} = B_0 \sin(\omega t - \vec{k} \cdot \vec{r})$

$$= B_0 \sin\left[\omega t - \left\{\frac{(-\hat{x} - \hat{y})k}{\sqrt{2}} \cdot (x\hat{x} + y\hat{y} + z\hat{z})\right\}\right]$$

We get  $\vec{k} = \frac{k}{\sqrt{2}}(-\hat{x} - \hat{y})$

We have

$$\vec{E} = -\frac{c^2}{\omega} (\vec{k} \times \vec{B})$$

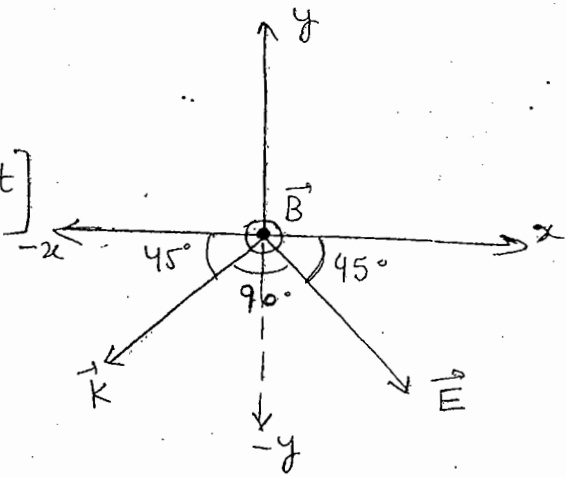
$$= -\frac{c^2}{\omega} \left[ \frac{k}{\sqrt{2}}(-\hat{x} - \hat{y}) \times B_0 \sin\left[\frac{(x+y)k}{\sqrt{2}} + \omega t\right] \hat{z} \right]$$

$$= -\frac{c^2}{\omega} \frac{k}{\sqrt{2}} [-\hat{y} + \hat{x}] B_0 \sin\left[\frac{(x+y)k}{\sqrt{2}} + \omega t\right]$$

$$\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0}$$

$$= \frac{1}{\mu_0} \left[ -\frac{c^2}{\omega} \frac{k}{\sqrt{2}} [-\hat{y} + \hat{x}] B_0 \sin\left[\frac{(x+y)k}{\sqrt{2}} + \omega t\right] \times B_0 \sin\left[\frac{(x+y)k}{\sqrt{2}} + \omega t\right] \hat{z} \right]$$

$$\vec{S} = \frac{c^2}{\mu_0 \omega} \frac{k}{\sqrt{2}} B_0^2 [-\hat{x} - \hat{y}] \sin^2 \left[ \frac{(x+y)k + \omega t}{\sqrt{2}} \right]$$



Q. Plane EM wave is propagating in lossless dielectric. Electric field of this wave is given by

$$\vec{E}(x, y, z, t) = E_0(\hat{x} + A\hat{z}) e^{i k_0 [-(x + \sqrt{3}z) - ct]}$$

Find (i) dielectric constant of the medium  $\epsilon_r$

(ii) value of A

(iii) Poynting Vector  $S$

$$\vec{E}(x, y, z, t) = E_0(\hat{x} + A\hat{z}) e^{i k_0 [(x + \sqrt{3}z) - ct]}$$

On comparing with  $\vec{E} = E_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$

We get  $\vec{k} = k_0(\hat{x} + \sqrt{3}\hat{z})$  so  $|\vec{k}| = 2k_0$

$$\omega = k_0 c$$

Wave velocity  $v = \frac{\omega}{|\vec{k}|} = \frac{k_0 c}{2k_0}$

$$v = \frac{c}{2}$$

also  $v = \frac{c}{n}$

On comparing  $\Rightarrow n = 2$

$\& n = \sqrt{\epsilon_r} \Rightarrow \epsilon_r = n^2 \Rightarrow \epsilon_r = 4$



for linear isotropic dielectric (lossless)

$$\vec{k} \cdot \vec{E} = 0$$

$$k_0 (\hat{x} + \sqrt{3} \hat{z}) \cdot E_0 (\hat{x} + A \hat{z}) e^{i k_0 (-ct + (x + \sqrt{3}z))} = 0$$

$$k_0 E_0 [1 + \sqrt{3} A] e^{i k_0 [-ct + (x + \sqrt{3}z)]} = 0$$

$$\Rightarrow 1 + \sqrt{3} A = 0$$

$$\Rightarrow \boxed{A = -\frac{1}{\sqrt{3}}}$$

$$\vec{B} = \frac{\vec{k} \times \vec{E}}{\omega}, \quad \omega = k_0 c$$

Now  $\vec{E} = E_0 \left[ \hat{x} - \frac{1}{\sqrt{3}} \hat{z} \right] e^{i k_0 [-ct + (x + \sqrt{3}z)]}$  &  $\vec{k} = k_0 (\hat{x} + \sqrt{3} \hat{z})$

$$\vec{k} \times \vec{E} = k_0 E_0 \left[ \frac{y}{\sqrt{3}} + \sqrt{3} \hat{y} \right] e^{i k_0 [-ct + (x + \sqrt{3}z)]}$$

$$\vec{B} = \frac{k_0 E_0}{k_0 c} \left[ \frac{y}{\sqrt{3}} \right] e^{i k_0 [-ct + (x + \sqrt{3}z)]}$$

$$\boxed{\vec{B} = \frac{4 E_0}{\sqrt{3} c} e^{i k_0 [-ct + (x + \sqrt{3}z)]} \hat{y}}$$

$$\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0}$$

dir<sup>n</sup> of  $\vec{S} \rightarrow$  dir<sup>n</sup> of  $\vec{k}$

$$\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0} = \frac{1}{\mu_0} \frac{4 E_0^2}{\sqrt{3} c} \left[ \hat{z} + \frac{1}{\sqrt{3}} \hat{x} \right] e^{2 i k_0 [-ct + (x + \sqrt{3}z)]}$$

2) A Plane wave  $\vec{E}$  is given by

$$\vec{E} = \left( \frac{1}{\sqrt{2}} \hat{i} + \frac{\sqrt{3}}{2} \hat{j} \right) \cos(10^8 t - \sqrt{3}x + y)$$

In Isotropic linear Non-magnetic medium. Find

- i) Wave vector  $\vec{k}$
- ii) Refractive index  $n$
- iii) Dielectric constant  $\epsilon_r$
- iv) Magnetic field  $\vec{B}$
- v) Wavelength of the wave  $\lambda$
- vi) Poynting vector  $\vec{S}$
- vii) Angle  $\theta$ , wave vector  $\vec{k}$  making from  $+x$  axis.

$$\vec{E} = \left( \frac{1}{\sqrt{2}} \hat{i} + \frac{\sqrt{3}}{2} \hat{j} \right) \cos(10^8 t - \sqrt{3}x + y)$$

$$\vec{E} = \left( \frac{1}{\sqrt{2}} \hat{x} + \frac{\sqrt{3}}{2} \hat{y} \right) \cos[10^8 t - (\sqrt{3}x - y)]$$

On comparing with  $\vec{E} = E_0 \cos(\omega t - \vec{k} \cdot \vec{r})$ , we get

$$\vec{k} = \sqrt{3} \hat{x} - \hat{y} \quad \& \quad \omega = +10^8$$

$$|\vec{k}| = \sqrt{3-1} = \sqrt{2} \Rightarrow \boxed{k = \sqrt{2}}$$

$$\text{Wave velocity } v = \frac{\omega}{|\vec{k}|} = \frac{+10^8}{\sqrt{2}}$$

$$n = \frac{c}{v} = \frac{3 \times 10^8}{v} \Rightarrow v = \frac{3 \times 10^8}{n}$$

$$\frac{3}{n} = \frac{1}{\sqrt{2}}$$

$$\text{On comparing, } n = +\sqrt{2} \times 3 \Rightarrow \boxed{n = +3\sqrt{2}}$$

$$n = \sqrt{\epsilon_r} \Rightarrow \epsilon_r = n^2 = 9 \times 2$$

$$\boxed{\epsilon_r = 18}$$

$$\vec{B} = \frac{\vec{k} \times \vec{E}}{\omega}$$

$$\vec{k} \times \vec{E} = \vec{k} = \sqrt{3} \hat{x} - \hat{y} \quad \& \quad \vec{E} = \left( \frac{1}{\sqrt{2}} \hat{x} + \frac{\sqrt{3}}{2} \hat{y} \right) \cos(10^8 t - \sqrt{3}x + y)$$

$$\vec{k} \times \vec{E} = \left( \frac{3}{2} \hat{z} + \frac{1}{\sqrt{2}} \hat{z} \right) \cos(10^8 t - \sqrt{3}x + y)$$

$$\omega = +10^8$$

$$\text{So } \boxed{\vec{B} = \frac{(3 + \sqrt{2}) \hat{z}}{10^8} \cos(10^8 t - \sqrt{3}x + y)}$$

Wave length  $\lambda = ?$

$$k = \frac{2\pi}{\lambda} \Rightarrow \lambda = \frac{2\pi}{k} \Rightarrow \lambda = \frac{2\pi}{\sqrt{2}}$$

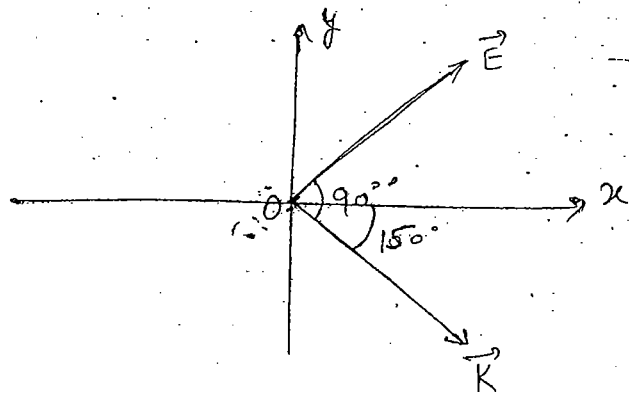
$$\boxed{\lambda = \sqrt{2} \pi} \text{ or } \lambda = 1.414 \times 3.14 \Rightarrow \boxed{\lambda = 4.44062}$$

Poynting Vector  $\vec{S} = ?$

$$\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0}$$

$$\vec{S} = \frac{1}{\mu_0} \left[ \frac{3}{\sqrt{2} \times 10^8} \hat{y} - \frac{\sqrt{3} \cdot \sqrt{2}}{2 \times 10^8} \hat{x} \right] \cos^2(10^8 t - \sqrt{3}x + y)$$

$$\vec{S} = \frac{1}{\mu_0} \left[ \frac{3}{\sqrt{2}} \hat{y} - \frac{\sqrt{3}}{2} \hat{x} \right] \frac{1}{10^8} \cos^2(10^8 t - \sqrt{3}x + y)$$



$$\vec{K} = \sqrt{3} \hat{x} - \hat{y}$$

$$\tan \theta = \frac{-1}{\sqrt{3}}$$

$$\theta = \tan^{-1}\left(\frac{-1}{\sqrt{3}}\right)$$

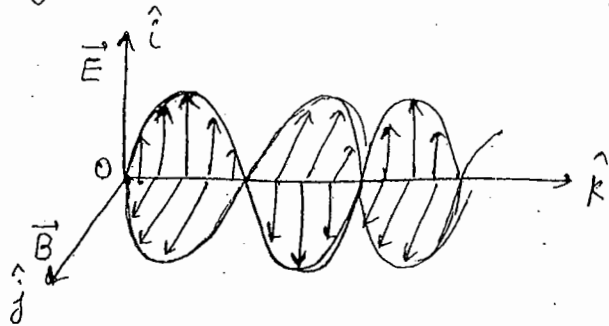
$$\theta = 150^\circ$$

# Polarisation in E.M. Waves :-

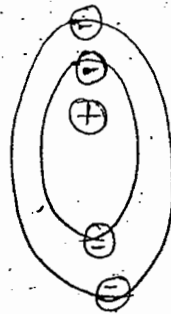
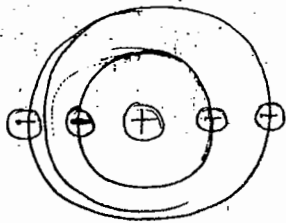
dir<sup>n</sup> of polarisation vector is the dir<sup>n</sup> of electric field  $\vec{E}$ .  
 suppose  $\vec{E}$  is vibrating along  $\hat{x}$ -dir<sup>n</sup> & wave is along  $\hat{z}$ .

so dir<sup>n</sup> of polarisation is  $\hat{x}$ .

dir<sup>n</sup> of mag. field  $\vec{B}$  is  $\perp^r$  to dir<sup>n</sup> of  $\vec{E}$ . Hence  $\perp^r$  to dir<sup>n</sup> of polarisation.



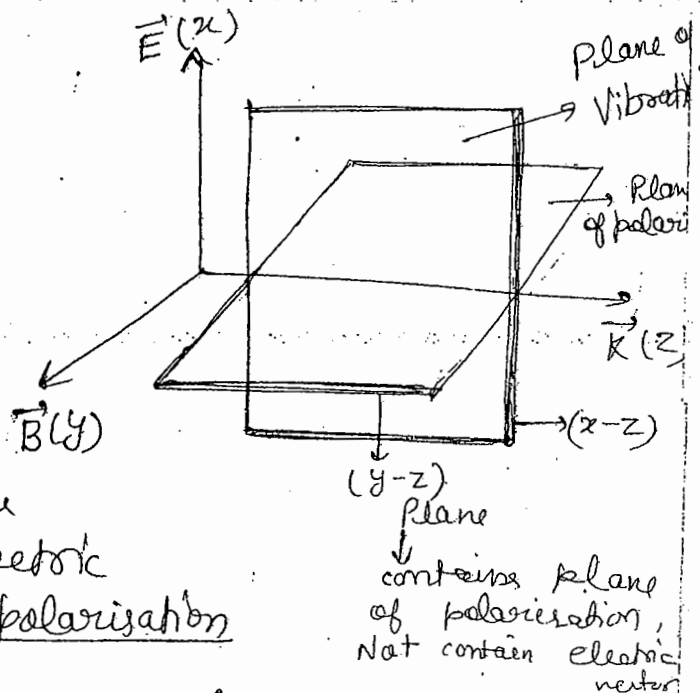
If we fall EM waves on any material (metal) which contains atom, then electric field will polarise the atom. for I half cycle,  $\vec{E}$  is upward so dir<sup>n</sup> of  $e^-$  is downward & dir<sup>n</sup> of nucleus is upward so atom will oscillate.



for lower half cycle  
 force of  $e^- \rightarrow$  up.  
 nuclei  $\rightarrow$  down  
 so atom will oscillate  
 & shape will change.

## Plane of Vibration :-

The plane that contains the dir<sup>n</sup> of propagation & the dir<sup>n</sup> of electric field, is called plane of vibration



## Plane of Polarisation :-

The plane that contains the dir<sup>n</sup> of propagation & No electric vibration, is called plane of polarisation

Plane of Vibration is  $\perp^r$  to plane of polarisation.

## Unpolarised Light :-

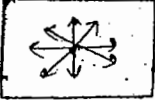
Light Waves  $\rightarrow$  EM wave in visible region.

The concept of polarisation is valid only in Transverse wave. It is not found in longitudinal wave.

Sound wave can not be polarised but light waves can (L.W.)

Polarisation is found in all electromag. wave (light sound ---). When light coming then  $\vec{E}$  &  $\vec{B}$  will confine in  $\perp^r$  to the dir<sup>n</sup> of propagation.

$\rightarrow$  If a light wave is coming & electric field vector is not confine, i.e.  $\vec{E}$  vibrate randomly in a plane & dir<sup>n</sup> of vibration is  $\perp^r$  to  $\vec{E}$ .

U.P.   $\vec{E}$  so it is called Unpolarised light.

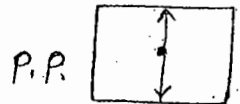
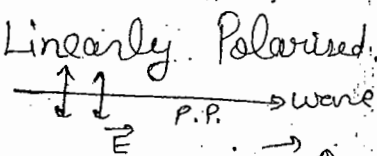
Polarisation may be of 3 types -

Plane polarised, circularly pol., elliptically pol.

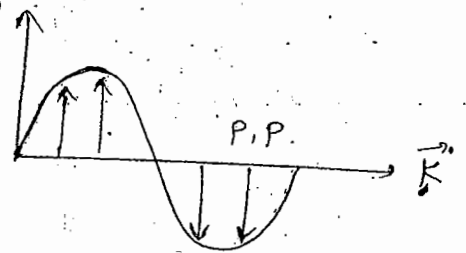
for plane polarisation,  $\vec{E}$  is confine along (i.e. vibrate along) a fix dir<sup>n</sup>.

It is also called Linearly Polarised.

e.g.  $E = E_0 e^{i(kz - \omega t)}$



This is Plane polarised wave.



If we superimpose, a another wave on it then

Dir<sup>n</sup> of polarisation is depend upon the dir<sup>n</sup> of polarisation of that other wave, their phase diff. & amplitude of both waves.

Note:- EM wave emit due to deexcitation of atoms. They will not produce only by single atom. When large no. of atoms deexcite from higher to lower level then EM wave will produce & there will be No phase correlation b/w the electric vector.

Sun gives unpolarised light bcoz light is not coming from single nuclei, it is coming from different nuclei so their electric vector will vibrate in diff. dir<sup>n</sup>  
 If beam & wave  $\rightarrow$  const. phase then  $\rightarrow$  Coherent wave.

Plane Polarised  $\rightarrow$  Electric vector always propagate along a fixed dir<sup>n</sup>.

### Elliptical & Circular Polarisation

If wave is coming towards us & electric vector rotate & traces a circle then it is circularly polarised.

If it traces an ellipse then it is elliptically polarised. & dir<sup>n</sup> of propagation is  $\perp$  to the field.

$$\vec{E}_1 = E_0 e^{i(kz - \omega t)} \hat{x}$$

$$\vec{E}_2 = E_0 e^{i(kz - \omega t)} \hat{y}$$

$$\vec{E}_3 = E_0 e^{i(kz - \omega t)} \hat{z}$$

If we superimpose  $\vec{E}_2$  on  $\vec{E}_1$  then wave will be plane polarised as these waves have same amp., same phase (i.e. no phase diff. b/w them) & dir<sup>n</sup> of polarisation is same.

Amplitude of Sum Superimposed wave  $\rightarrow 2E_0$

Q. Superimposition of which wave produce interference.

(i)  $E_1$  &  $E_2$

(ii)  $E_2$  &  $E_3$

(iii)  $E_1$  &  $E_3$

Cond<sup>n</sup> of Interference  $\rightarrow$  The phase diff. b/w 2 waves should remain const. with time i.e. Coherent.

Here all 3 waves are coherent (i.e. have const. phase)

$\rightarrow$  The superimposing waves must have same state of polarisation.

so  $E_1$  &  $E_2$  will produce interference as they have same state of polarisation.

$$\vec{E}_1 = E_0 e^{i(ky - \omega t)} \hat{x}$$

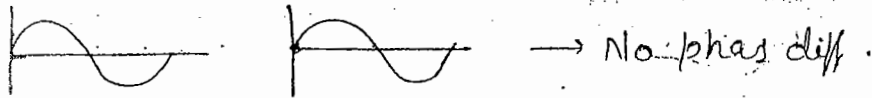
$$\vec{E}_2 = E_0 e^{i(kz - \omega t)} \hat{x}$$

Now these waves can not produce interference  
- sense bcoz they can not superimpose  
bcoz both are propagating in different state  
of polarisation dir<sup>n</sup>.

### Cond<sup>n</sup> of Interference

- i) propagation in same dir<sup>n</sup>
- ii) same freq.
- iii) phase diff. constant (coherent)
- iv) same state of polarisation.

If phase diff. b/w 2 waves is 0 then  $\rightarrow$  Constructive Inter.



If phase diff. b/w 2 waves is  $\pi/2$  then  $\rightarrow$  destructive Inter.



P.D.  $\rightarrow$   $0, 2\pi, 4\pi, \dots$  Constructive  
 $\pi, 3\pi, 5\pi, \dots$  Destructive

$\rightarrow$  By the superposition of  $E_1$  &  $E_2$  waves then their resultant wave will be plane wave & amplitude of resultant wave will be

$$E = \sqrt{E_1^2 + E_2^2 + 2E_1E_2 \cos \phi}$$

$\phi \rightarrow$  phase diff. b/w 2 waves.

It is valid only when both waves have same state of polarisation.

Here  $E_1$  &  $E_2 = E_0$  &  $\phi =$  phase diff.  $= 0$

$$\therefore E = \sqrt{E_0^2 + E_0^2 + 2E_0^2} = \sqrt{4E_0^2}$$

$$E = 2E_0$$

## Superimposition of 2 wave which are different state of polarisation

We can never achieve circular or elliptical polarisation by the superposition of waves which are in same state of polarisation (only we get plane P.)

But ~~we can~~ By the superposition of waves which are in different state then we can achieve circular or elliptically polarised wave under certain conditions & also can get plane P. wave.

First check the state of polarisation of 2 waves if same then  $\rightarrow$  Plane wave.

Now if  $\vec{E}_1$  &  $\vec{E}_2$  superimpose then

$$\vec{E}_1 = E_0 e^{i(kz - \omega t)} \hat{x} \quad , \text{P.P. in } \hat{x} \text{ dir}$$

$$\vec{E}_2 = E_0 e^{i(kz - \omega t)} \hat{y} \quad , \text{P.P. in } \hat{y} \text{ dir}$$

Resultant Wave  $\vec{E} = \vec{E}_1 + \vec{E}_2$

$$\boxed{\vec{E} = E_0 (\hat{x} + \hat{y}) e^{i(kz - \omega t)}} \quad \text{--- (A)}$$

(i) State of polarisation

If  $\perp$  then plane polarised.

But if  $\parallel$  then check.

(ii) phase difference  $\phi$

(a) If  $\phi = 0, \pi, 2\pi, 3\pi$  then wave will be plane polarised

(b) If  $\phi = \frac{\pi}{2}, \frac{3\pi}{2}, \dots$  then check amp. of both wave  $\rightarrow$  amplitude

1. if amp. same  $\rightarrow \boxed{E_1 = E_2} \rightarrow$  Circularly Polarised

2. if amp. is not same  $E_1 \neq E_2 \rightarrow$  Elliptically "

(c) If phase diff  $\phi \neq 0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}$  then surely it will Elliptically polarised.

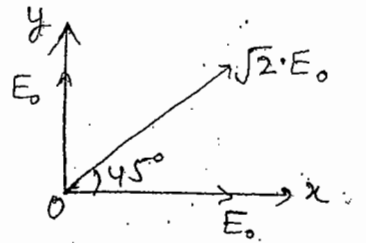


Now for (A)  $\Rightarrow$

$$\vec{E} = E_0 (\hat{x} + \hat{y}) e^{i(kz - \omega t)} \quad \left. \vphantom{\vec{E}} \right\} \begin{array}{l} \text{state of polarisation} \rightarrow \text{is same} \\ \text{both plane wave} \end{array}$$

This is plane polarised (No phase diff.)

Superimposed wave is making angle  $45^\circ$  with x-axis & its magnitude is  $\sqrt{2} E_0$ .



• If we have

$$\vec{E} = \vec{E}_1 + \vec{E}_2 = E_0 (\hat{x} + e^{i\phi} \hat{y}) e^{i(kz - \omega t)}$$

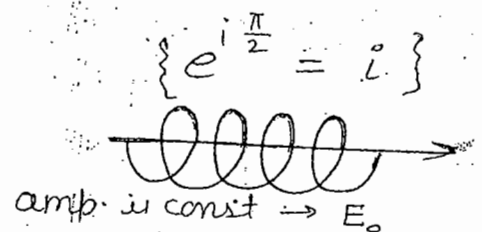
(i)  $\phi = 0$  then Plane polarised making angle  $45^\circ$  with x-axis.

(ii)  $\phi = \frac{\pi}{2}$  then

$$\vec{E} = E_0 (\hat{x} + i \hat{y}) e^{i(kz - \omega t)}$$

$i \rightarrow$  phase diff. of  $\pi/2$

This is circularly polarised wave.



(iii)  $\phi = \pi/4$

$$e^{i\pi/4} = \cos \frac{\pi}{4} + i \sin \frac{\pi}{4} = \frac{1}{\sqrt{2}} + i \frac{1}{\sqrt{2}} = \frac{1}{\sqrt{2}} (1 + i)$$

$$\vec{E} = E_0 \left[ \hat{x} + \frac{(1+i)}{\sqrt{2}} \hat{y} \right] e^{i(kz - \omega t)}$$

This is elliptically polarised



In ellipse - distance from centre is not same but in circle - " " is same so amplitude remain constant

\* Most General type of Polarisation is Elliptical polarisation. Plane polarised & Circularly polarised waves are the special case of elliptically polarised wave.

e.g.  $\vec{E} = E_0 (2\hat{x} + i\hat{y}) e^{i(kz - \omega t)}$

phase diff  $\rightarrow \pi/2$  & amp. is different

so elliptically polarised wave.

Circularly Polarised


- Right Circular Polarised RCP
- Left " " LCP

Elliptically Polarised

- Right Elliptical Polarised <sup>RCP</sup>
- Left " " <sup>LCP</sup>

- There are 2 type of sep<sup>n</sup>
  - one along → angular mom. (30% Probability)
  - 2nd along → optics (70% Probability)

If electric vector is moving towards us doing clockwise motion i.e. wave is coming towards us & electric vector is rotating clockwise then  
 acc. to optics sep<sup>n</sup> it is RCP (if amp. constant)  
 R.E.P (if amp. Not constant)

acc. to Angular Mom. sep<sup>n</sup>, it is 

If electric vector is rotating anticlockwise then  
 acc. to optics sep<sup>n</sup> it is LCP (const. amp.)  
 LEP (Not " " )

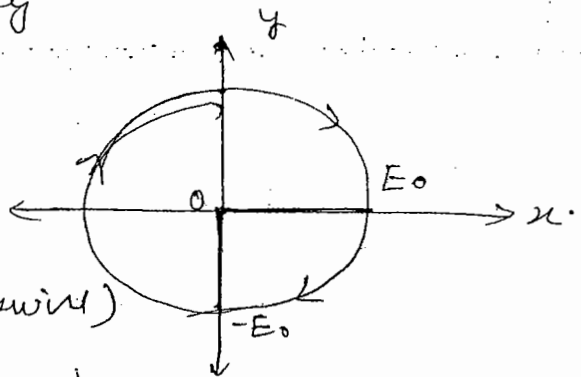
e.g.  $\vec{E} = E_0 \cos(Kz - \omega t) \hat{x} + E_0 \sin(Kz - \omega t) \hat{y}$   
 amp. same } → Circularly Polarised  
 Phase →  $\pi/2$

Take origin of wave  $z=0$  & dir of prop  $+\hat{z}$

$\vec{E} = E_0 \cos \omega t \hat{x} - E_0 \sin \omega t \hat{y}$

$\omega t \rightarrow$  phase

At  $\omega t = 0$ ,  $\vec{E}$  along  $\hat{x}$   
 $\omega t = \pi/2$ , "  $-\hat{y}$



Acc. to ang. mom. LCP (clockwise)  
 do acc. to optics → RCP

RCP

$$\underline{Q.} \quad \vec{E} = E_0 (\hat{x} + e^{i\frac{\pi}{2}} \hat{y}) e^{i(\omega t - kz)}$$

Wave propagation along +z dir<sup>n</sup>  
elec. vector is vibrating in x-y plane.

$$z=0,$$

$$\vec{E} = E_0 (\hat{x} + i\hat{y}) e^{i\omega t}$$

$$\text{for } \omega t = 0, \quad \vec{E} = E_0 (\hat{x} + i\hat{y})$$

We need to take real amplitude only so

$$\vec{E} = E_0 \hat{x}$$

$$\text{for } \omega t = \frac{\pi}{2}, \quad \vec{E} = E_0 (\hat{x} + i\hat{y}) e^{i\frac{\pi}{2}} = E_0 (\hat{x} + i\hat{y}) i$$

$$= iE_0 \hat{x} - E_0 \hat{y}$$

$$\vec{E} = -E_0 \hat{y} \quad (\text{real})$$

Rotation is clockwise  $\rightarrow$  so LCP acc. to ang. mom. exp.  
so RCP acc. to optics.

so RCP

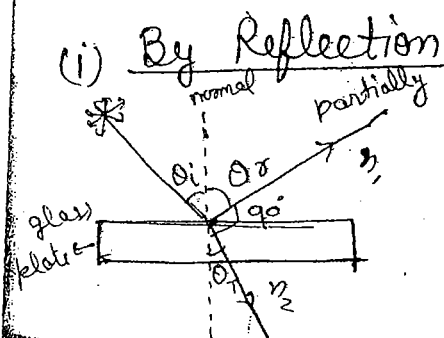
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## Production of Plane Polarised Light:-

Plane polarised light can be produced by no. of methods.

- i) Reflection method
- ii) Refraction " (Transmission)
- iii) By scattering
- iv) By phase retardation (doubly refracting crystals)
- v) Beam splitter

(i) By Reflection



$\therefore$  If we have a transparent glass plate. If an unpolarised light is incident onto a crystal at an angle  $\theta_i$ . Reflected light is partially polarised. Or is the reflection angle. And for a certain angle of incident, ~~refl~~  $\theta_i$  reflected

light is completely plane polarised with vibrations  $\perp$  to plane of incidence, & that particular angle of incidence is called Brewster's angle  $\theta_B$ .  $\theta_i = \theta_B$

This will happen When reflected light wave & transmitted light wave are  $\perp$  to each other.

$$\theta_r + \theta_T = \frac{\pi}{2}$$

$\theta_i = \theta_r$  (angle of incident = angle of reflection)

$$\therefore \theta_i + \theta_T = \frac{\pi}{2}$$

By Snell's law,  $\frac{\sin \theta_i}{\sin \theta_T} = \frac{n_2}{n_1}$

$n_1 \rightarrow$  refractive index of medium 1.  
 $n_2 \rightarrow$  " " " " " 2

$$\left\{ \begin{aligned} \sin \theta_T &= \sin(\frac{\pi}{2} - \theta_r) \\ &= \sin(\frac{\pi}{2} - \theta_B) \\ &= \cos \theta_B \end{aligned} \right.$$

$$\Rightarrow \frac{\sin \theta_B}{\sin \theta_T} = \frac{n_2}{n_1} \Rightarrow \tan \theta_B = \frac{n_2}{n_1}$$

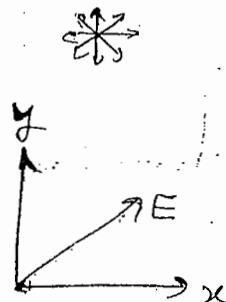
$$\Rightarrow \theta_B = \theta_p = \tan^{-1}\left(\frac{n_2}{n_1}\right)$$

This is Brewster angle & also called polarisation angle i.e. angle at which unpolarised light is completely plane polarised.

Note :- for air-glass interface and glass-air interface, this angle  $\theta_B$  or  $\theta_p$  is different as their ref. index has been inverted.

(iii) Refraction method :-

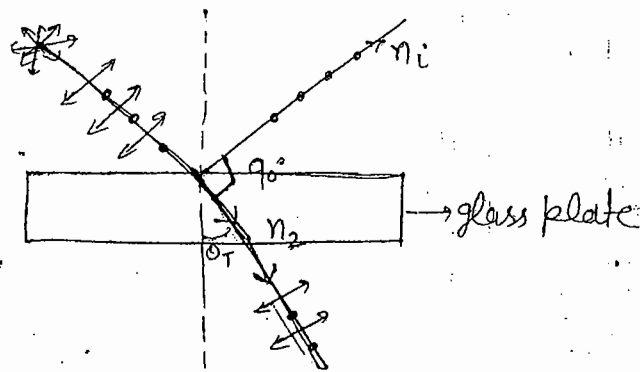
We can break any vector of unpolarised light into 2 components - horizontal  $\leftarrow$  vertical.



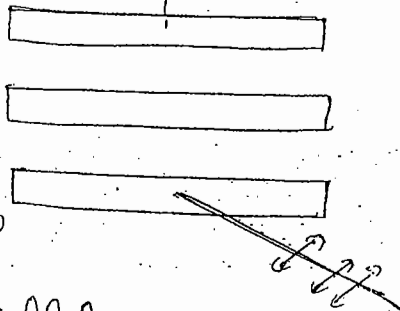
$\uparrow \rightarrow$  parallel to the plane of incidence

$\rightarrow \perp$  " " " "

Interface plane  $\rightarrow$  plane which separates 2 medium



If we place a larger no. of plates then there will be polarisation by refraction. & this will be parallel to the plane of incidence.



$\Rightarrow$  After passing through large no. of plates,  $\perp$  wave will filter & only parallel wave will remain.

- This law is valid for both rare to denser & denser to rare

air  $\rightarrow$  glass (rare to denser)  $n_{\text{glass}} > n_{\text{air}}$   
 glass  $\rightarrow$  air

Polarisation by Scattering :- When a EM wave is incident on atom or molecule then reflected light will be partially plane polarised.

{ sky is blue due to the scattering of blue colour - Rayleigh scattering - (it is  $\propto \frac{1}{\lambda^4}$ )  
 Red colour sca. least as its wavelength is large. }

When unpolarised light is scattered by small particles, the scattered light is partially polarised. The blue light received from the sky is accordingly partially polarised light.

(iv) By phase retardation :- In nature there are certain types of crystals which split the electromagnetic waves into 2 parts.

(i) E-ray (extraordinary ray)

(ii) O-ray (Ordinary ray)

→ E-ray does not follow, the laws of refraction while O-ray follows the laws of refraction.

→ E-ray travels with different speeds in different directions while O-ray travels with same speed in different dir<sup>n</sup>.

→ Along a particular dir<sup>n</sup> in a crystal E-ray & O-ray travels with same speed, this dir<sup>n</sup> is called Optic axis of the crystal.

If a medium is s.t. in which a ray split into E-ray & O-ray after entering in it. then there must be some angle at which E-ray & O-ray travel with same speed. The crystals in which this phenomenon occur are known as Doubly Refracting Crystals. These are Anisotropic medium as they have diff. properties in diff. dir<sup>n</sup>.

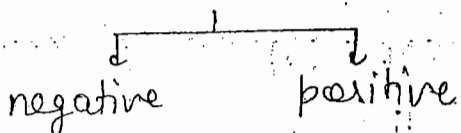
as Refractive index is different in different dir<sup>n</sup>.

• Doubly refracting Crystals are of 2 types -

(i) Uniaxial → one optic axis

(ii) Biaxial → two optic axis

uniaxial



Negative uniaxial crystal - In -ve crystal,

$$\boxed{n_o > n_e}$$

Hence

$$\boxed{v_e > v_o}$$

example → Calcite

$n_o$  → Ref. index of ordinary ray  
 $n_e$  → " " extra " "  
 $v_e$  → speed of extraordinary ray  
 $v_o$  → " " ordinary ray

## Positive Uniaxial crystal

$$n_e > n_o$$

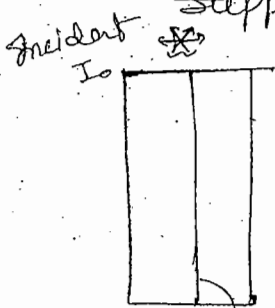
$$\text{Hence } \boxed{v_o > v_e}$$

example - Quartz.

Polarisers - These produce plane polarised light.  
Nicol prism is a device which convert unpolarised light into plane polarised light.

Nicol prism is made up of doubly reflecting crystal

Suppose we have a polariser,



if we incident some unpolarised light on polariser then we get vibrations  $\parallel$  to the polarisation axis of polariser.

if intensity of unpolarised light is  $I_0$  then transmitted intensity of polarised light is always half of  $I_0$ . ( $\frac{I_0}{2}$ )

Transmitted intensity is always found by the law of Malus.

Transmitted intensity is given by

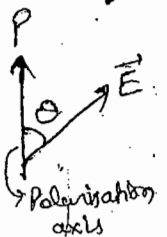
$$\boxed{I_t = I_0 \cos^2 \theta}$$

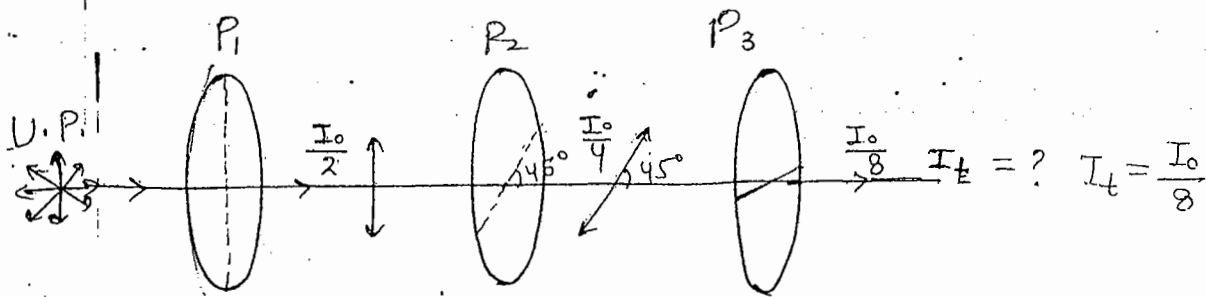
where,  $\theta$  is the angle b/w dir<sup>n</sup> of electric field & polarisation angle axis.

for unpolarised light we need to take average value of  $\cos^2 \theta$ . (i.e.  $\frac{1}{2}$ ) so

$$\boxed{I_t = \frac{I_0}{2}}$$

Polarisation axis is also called Transmission Axis.





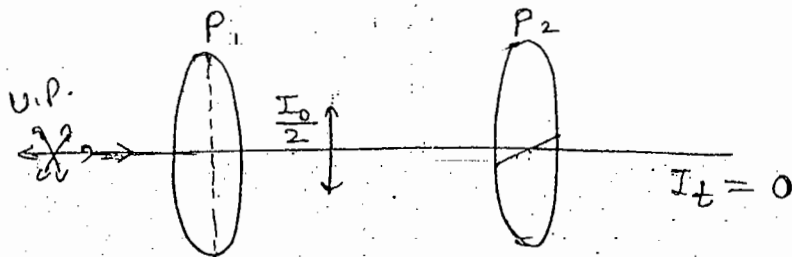
$$I_t = \frac{I_0}{2}$$

$$I_t = \frac{I_0}{2} \cos^2 45^\circ$$

$$I_t = \frac{I_0}{4} \cos^2 45^\circ$$

$$I_t = \frac{I_0}{4}$$

$$I_t = \frac{I_0}{8}$$



$$I_t = \frac{I_0}{2} \cos^2 90^\circ$$

$$I_t = 0$$

## How to produce Circularly & Elliptically polarised light

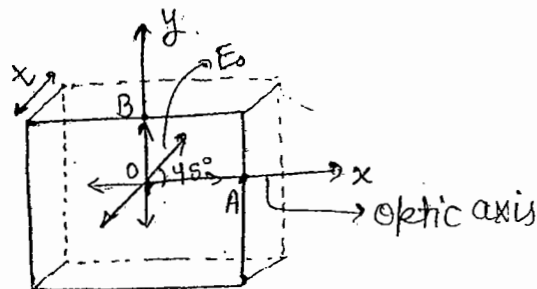
We use Quarter wave plate & quarter wave plates is made up of doubly reflecting wave crystals. s.t. it produce a path difference of  $\lambda/4$  i.e. phase diff. of  $\pi/2$  b/w E-ray & O-ray. That's why it is called  $\frac{\lambda}{4}$ -plate (Quarter wave plate)

$$\Delta\phi = \frac{2\pi}{\lambda} \times \frac{\lambda}{4}$$

$$\Delta\phi = \frac{\pi}{2}$$

Vibrations of E-ray & O-rays are  $\perp$  to each other. Suppose we have a plate of doubly reflecting crystal of thickness  $t$  is placed in  $x-y$  plane.

If we incident an EM wave on it which is in  $-z$  dir<sup>n</sup> & Elec. field.



$$\vec{E} = E_0 e^{i(Kz + \omega t)} \left( \frac{\hat{x} + \hat{y}}{\sqrt{2}} \right)$$



As elec. field enter in crystal EM wave split into 2 parts - one is along x,  $E_0 \cos 45^\circ$  & one is along y -  $E_0 \sin 45^\circ$ .

Vibrations of Electric field parallel to optic axis is E-Ray. & Vibration " " perpendicular " " " "

$$OA = E_0 \cos 45^\circ \quad (\text{E-ray})$$

$$OB = E_0 \sin 45^\circ \quad (\text{O-ray})$$

As E-rays travel with diff. speed so when these rays come out of the crystal then there must be some path difference in these rays. The path travelled by the wave is called optical path,

Optical path = ref. index of that medium  $\times$  distance travelled

$$\text{Optical path} = n t$$

for E-ray,  $n_e t$

for O-ray,  $n_o t$

$$\text{So path diff.} = (n_e t - n_o t) \quad (+ve)$$

for circularly polarised light

Phase diff  $\rightarrow \pi/2$

Path  $\rightarrow \lambda/4$

$$t = \frac{\lambda}{4(n_o - n_e)}$$

for plane polarised light

Phase diff  $\rightarrow \pi$

Path  $\rightarrow \lambda/2$

$$t = \frac{\lambda}{2(n_o - n_e)}$$

Now this is known as half wave plate or  $\frac{\lambda}{2}$ -plate. It depends upon thickness t, that how much path difference is produced by wave.

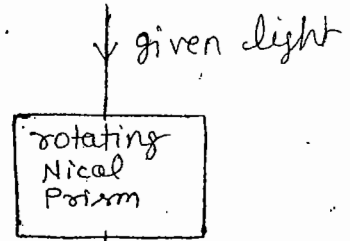
If t is in b/w these two values then phase diff is not  $\pi$  &  $\pi/2$

i.e. phase diff.  $\Delta\phi \neq 0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}, \dots$

Then Elliptically Polarised. & thickness  $t$  lies b/w these 2.

Detection of Light Wave :-

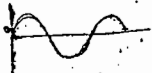
If a given light is passing through a rotating Nicol prism then, there are 3 possibilities,



There may be 3 possibilities

Variation in intensity with 0 minima then light wave is surely plane polarised.

$I \propto E^2$

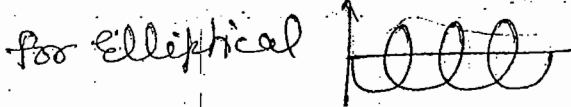


When Elec. field = 0, then Intensity = 0 (I can't be -ve as it is square of amp.  $E_0$ )

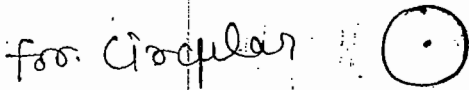
Variation in intensity with Non-zero minima then 2 possibilities

- Elliptical
- Partially plane P. i.e. mixture of unpolarised & plane polarised.

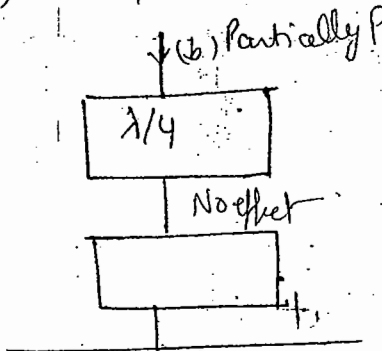
No variation in intensity. then  
→ Circularly P.  
→ Unpolarised



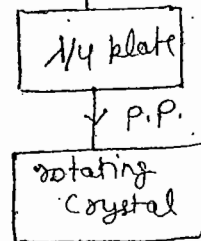
in ellipse radius can't be zero.



In (b) case, there is some doubt, so ~~we can~~ use a  $\lambda/4$  plate <sup>elliptically</sup> (b) light



variation int. with non-zero minima



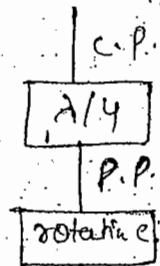
variation int. with 0 minima

If elliptically polarised light passes through  $\lambda/4$  plate then it will produce a phase diff of  $\pi/2$  b/w E-ray & O-ray. It'll become Plane polarised &  $\rightarrow$

If partially plane polarised light passes through  $\lambda/4$  plate then it will remain partially plane polarised (no effect) & after appearing through nical crystal there will be variation intensity with non-zero minima. It'll become Partially Plane polarised.

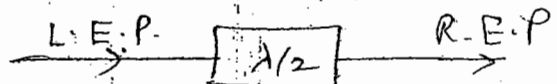
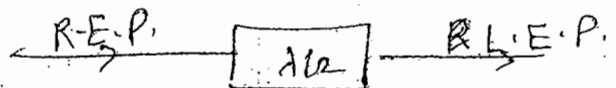
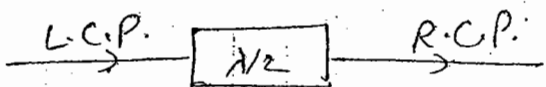
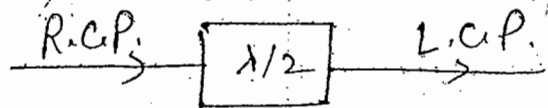
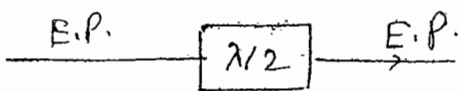
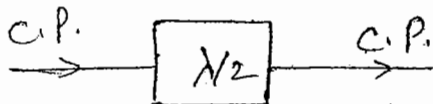
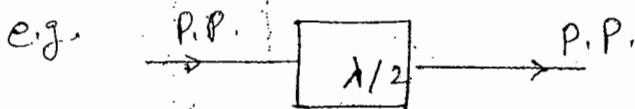
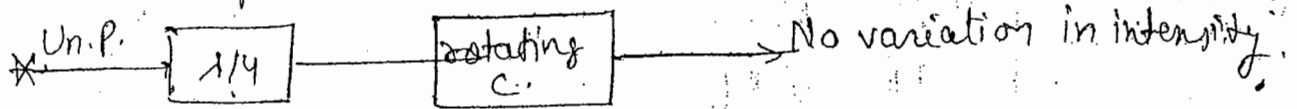
( $\rightarrow$  & after passing through rotating crystal, there will be variation in int. with 0 minima i.e. it was elliptical)

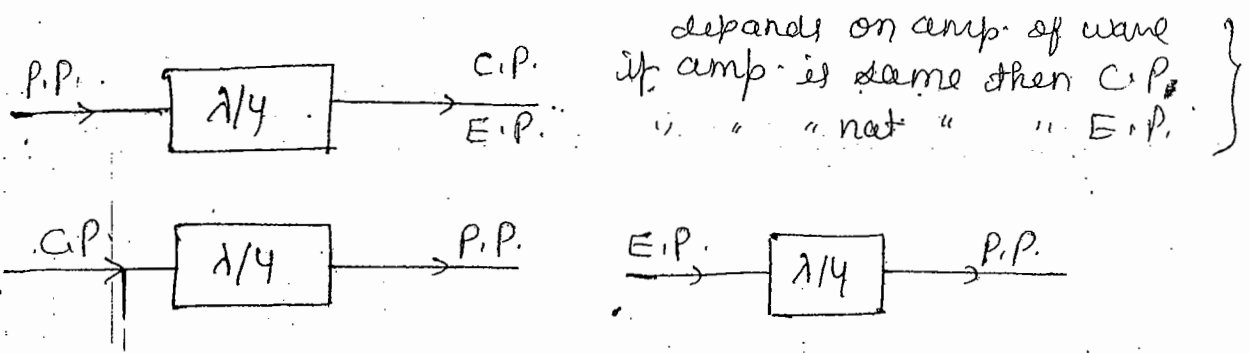
If C.P. light passes through  $\lambda/4$  plate then it'll become circular plane polarised. If we get variation in intensity with zero minima. This confirms it was circularly P. light.



variation int. with 0 min

If unpolarised light passes through  $\lambda/4$  plate. It remains unpolarised. If unpolarised light passes through rotating crystal then No. variation in intensity. This confirms it was Unpolarised.

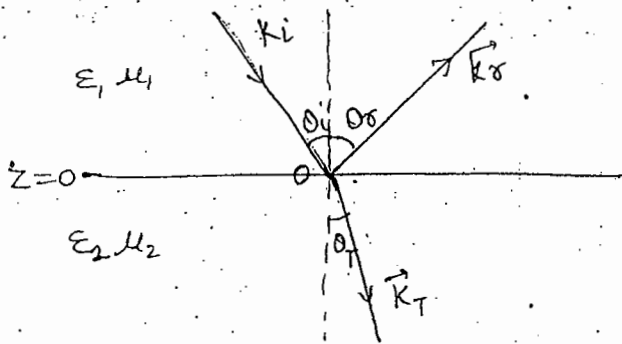




- Plane polarised light or linearly polarised light is the combination of L.C.P & R.C.P.

## Reflection & Refraction of EM Waves at the Dielectric Interface :-

If we have a (dielectric) interface having different dielectric above & below the interface.



(interface is in  $x-y$  plane &  $z$  dir<sup>n</sup> is normal to the surface.)

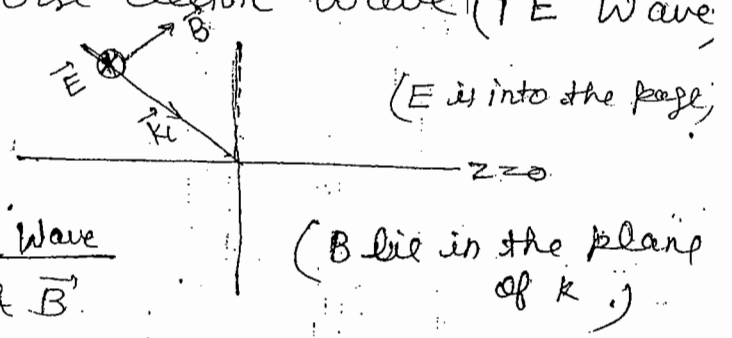
EM waves carries energy & when EM waves fall on an interface then there will be redistribution of energy & some part will reflect & some part will transmit.

Interface Plane :- The plane dividing the 2 mediums.  
In present case  $\rightarrow x-y$  plane

Plane of Incidence :- The plane that contains propagation vector & normal to the plane.  
In present case  $\rightarrow y-z$  plane of incidence

(i)  $\vec{E}$  (polarisation vector) is  $\perp$  to plane of incident.  
 This is also called Transverse electric wave (TE Wave)

- $\vec{B}$  &  $\vec{k}_i$  both lie in x-y plane
- $\vec{E}$  is lying in -z plane.
- $\vec{E}$  is  $\perp$  to both  $\vec{k}$  &  $\vec{B}$ .



So  $\vec{E}$  is transverse electric wave  
 i.e.  $\vec{E}$  is transverse to  $\vec{k}$  &  $\vec{B}$ .

& Normal waves are Transverse electromagnetic wave  
 i.e. transverse electric & transverse magnetic wave both

(ii)  $\vec{E}$  is parallel to plane of incident

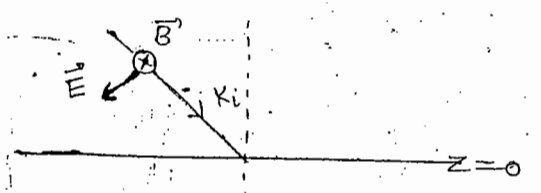
Here  $\vec{E}$  is not transverse.

&  $\vec{B}$  is into the page.

$\vec{E}$  vector is in y-z plane i.e.  $\parallel$  to the plane of incidence.

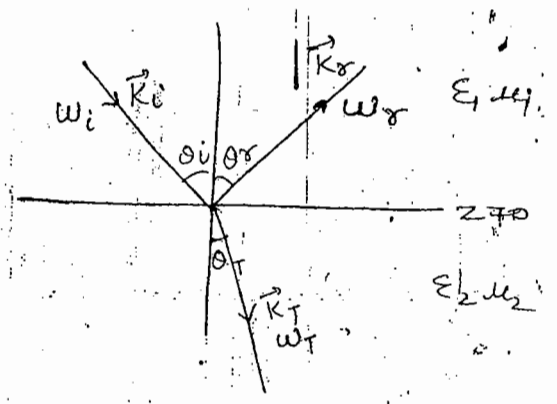
It is called Transverse Magnetic wave

$\vec{B}$  is  $\perp$  to the plane of  $\vec{E}$  &  $\vec{k}$



Static properties :- Same for TE & TM waves.

- (i)  $\omega_i = \omega_r = \omega_t$
- (ii) Wavelengths & wave velocity changes s.t. freq. remains same.
- (iii)  $\theta_i = \theta_r$
- (iii)  $\frac{\sin \theta_i}{\sin \theta_t} = \frac{n_2}{n_1} = \frac{v_1}{v_2} = \frac{\sqrt{\epsilon_2 \mu_2}}{\sqrt{\epsilon_1 \mu_1}}$



Dynamical properties :-

Boundary Cond<sup>n</sup> :- (i)  $E_1^{\parallel} = E_2^{\parallel}$

(ii)  $\epsilon_1 E_1^{\perp} = \epsilon_2 E_2^{\perp}$

(iii)  $B_1^{\perp} = B_2^{\perp}$  ; (iv)  $\frac{B_1^{\parallel}}{\mu_1} = \frac{B_2^{\parallel}}{\mu_2}$

(on interface, no free charge so  $E_1^{\perp} = E_2^{\perp}$ )

On the basis of these 4 B.C., we can derive the Dynamical properties.

Dynamical Properties :- (Fresnel's Relations) :-

1. For TE Waves (I) :-

$$\left( \frac{E_{or}}{E_{oi}} \right)_{\perp} = \frac{\eta_2 \cos \theta_i - \eta_1 \cos \theta_t}{\eta_2 \cos \theta_i + \eta_1 \cos \theta_t}$$

$E_{or}$  → Amp of E-field of reflected wave

$E_{oi}$  → " " " incident "

$\perp$  means electric field is  $\perp$  to the plane of incidence.

where  $\eta_1 = \sqrt{\frac{\mu_1}{\epsilon_1}}$  &  $\eta_2 = \sqrt{\frac{\mu_2}{\epsilon_2}}$

$$\left( \frac{E_{ot}}{E_{oi}} \right)_{\perp} = \frac{2\eta_2 \cos \theta_i}{\eta_2 \cos \theta_i + \eta_1 \cos \theta_t}$$

$E_{ot}$  → amp of E-field of transmitted wave.

$$\frac{H_{or}}{H_{oi}} \Rightarrow \left( \frac{E_{or}}{E_{oi}} \right)_{\perp} = \frac{\eta_2 \cos \theta_i - \eta_1 \cos \theta_t}{\eta_2 \cos \theta_i + \eta_1 \cos \theta_t} = - \left( \frac{H_{or}}{H_{oi}} \right)_{\perp}$$

$H_{or}$  → Amp of Mag. field of reflected wave. (-ve sign indicate phase change)

$H_{oi}$  → " " " incident "

$\perp$  → decides from electric field i.e. E-vector is  $\perp$  to the plane of incidence.

When reflected vector of electric field do not change phase then " " " Mag. " changes the phase of  $\pi$ .

$$\& \left( \frac{H_{ot}}{H_{oi}} \right)_{\perp} = \frac{2\eta_1 \cos \theta_i}{\eta_2 \cos \theta_i + \eta_1 \cos \theta_t}$$

2. For TM Wave (II) :-

$$\left( \frac{E_{or}}{E_{oi}} \right)_{\parallel} = \frac{\eta_2 \cos \theta_t - \eta_1 \cos \theta_i}{\eta_2 \cos \theta_t + \eta_1 \cos \theta_i} = - \left( \frac{H_{or}}{H_{oi}} \right)_{\parallel}$$

$$\left(\frac{E_{ot}}{E_{oi}}\right)_{||} = \frac{2\eta_2 \cos \theta_0}{\eta_2 \cos \theta_t + \eta_1 \cos \theta_i}$$

$$\left(\frac{H_{ot}}{H_{oi}}\right)_{||} = \frac{2\eta_1 \cos \theta_i}{\eta_2 \cos \theta_t + \eta_1 \cos \theta_i}$$

D) For  $\perp$  components:

When medium is Non-magnetic,  
 $\mu_1 = \mu_2 = \mu_0$

$$-\left(\frac{H_{or}}{H_{oi}}\right)_{\perp} = \left(\frac{E_{or}}{E_{oi}}\right)_{\perp} = -\frac{\sin(\theta_i - \theta_t)}{\sin(\theta_i + \theta_t)}$$

$$\left(\frac{E_{ot}}{E_{oi}}\right)_{\perp} = \frac{2 \sin \theta_t \cos \theta_i}{\sin(\theta_i + \theta_t)}$$

$$\left(\frac{H_{ot}}{H_{oi}}\right)_{\perp} = \sqrt{\frac{\epsilon_1}{\epsilon_2}} \cdot \left(\frac{E_{ot}}{E_{oi}}\right)_{\perp}$$

If  $\epsilon_1 < \epsilon_2$  then  $\boxed{n_2 > n_1}$

( $n = \sqrt{\epsilon_r}$ )

If EM wave going from Rare to denser (air-glass) then phase change will be

$$\frac{\sin \theta_i}{\sin \theta_t} > 1$$

( $\because n_2 > n_1$ )

i.e.  $\boxed{\theta_i > \theta_t}$

If EM wave going from Rare to denser then it will bend toward normal & reflected component of  $E_{\perp}$  will suffer a phase change of  $\pi$ . And Reflected comp. of mag. field will not suffer a phase change.

Transmitted components of electric & mag. field suffers No phase change.

If  $\epsilon_1 > \epsilon_2$  then  $\boxed{n_1 > n_2}$

$\boxed{\theta_i < \theta_t}$

When a EM wave is going from denser to rare (glass-air) or (water-air)

then reflected component of mag. field will suffer a phase change of  $\pi$  & Reflected comp. of Electric field vector will not suffer any phase change.

Transmitted components in this case suffer no phase change either go from rare to denser or denser to rare.

② For Parallel Components :-

$$-\left(\frac{H_{or}}{H_{oi}}\right)_{||} = \left(\frac{E_{or}}{E_{oi}}\right)_{||} = \frac{-\tan(\theta_i - \theta_r)}{\tan(\theta_i + \theta_r)}$$

$$\left(\frac{E_{ot}}{E_{oi}}\right)_{||} = \frac{2 \sin \theta_r \cos \theta_i}{\sin(\theta_i + \theta_r) \cos(\theta_i - \theta_r)}$$

$$\left(\frac{H_{ot}}{H_{oi}}\right)_{||} = \sqrt{\frac{\epsilon_1}{\epsilon_2}} \left(\frac{E_{ot}}{E_{oi}}\right)_{||}$$

Transmitted components never suffers a phase change in any case [ if  $\theta_i > \theta_r$  or  $\theta_r > \theta_i$  then  $\cos(\theta_i - \theta_r) \Rightarrow \cos(-\theta) = \cos \theta$  ]  
i.e. either go from rare to denser or denser to rare.

If  $(\theta_i + \theta_r) < 90^\circ$

$$\tan(\theta_i + \theta_r) \rightarrow 0$$

$$\theta_i > \theta_r \Rightarrow \epsilon_1 < \epsilon_2 \Rightarrow n_2 > n_1$$

EM wave is going from rare  $\rightarrow$  denser &  $(\theta_i + \theta_r) < 90^\circ$  then reflected vector of electric vector will suffer a phase change of  $\pi$ , <sup>Mag. field will not</sup> and for  $(\theta_i + \theta_r) < 90^\circ$

$$\epsilon_1 > \epsilon_2 \Rightarrow n_1 > n_2$$

$$\theta_r > \theta_i$$

EM wave is going from denser to rare & <sup>ref. comp. of</sup> Mag. field H will suffer a phase change of  $\pi$ .

No component of electric or mag. field will be reflected which is parallel to the plane of incidence.